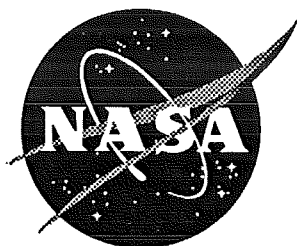


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Langley's CSI Evolutionary Model: Phase II

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N96-15201

Unclass

G3/18 0081136

October 1995

National Aeronautics and
Space Administration
Langley Research Center
Hampton, Virginia 23681-0001

(NASA-TM-109059) LANGLEY'S CSI
EVOLUTIONARY MODEL: PHASE 2 (NASA-
Langley Research Center) 105 p

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1. Introduction

The Phase 2 testbed is part of a sequence of laboratory models, developed at NASA Langley Research Center, to enhance understanding on how to model, control, and design structures for space applications. A key problem with structures that must perform in space is unwanted vibrations during operations. Instruments, designed independently by different scientists, must share the same vehicle causing interactions with each other. Once in space, these problems are difficult to correct and therefore prediction via analysis, design, and experiments is very important. Examples of these unwanted vibrations were evident in the Hubble Space Telescope and Upper Atmosphere Remote Satellite (UARS). Vibrations, although not crippling, can curtail the satellite effectiveness and data quality. The Phase 2 laboratory model is designed to fill a gap between theory and practice and to aid understanding of important aspects in modeling, sensor and actuator technology, ground testing techniques, and space control design issues. This report documents the Phase 2 structural properties, instrumentation, analytical and experimental models, and the suspension system.

Phase-2 is among the most sophisticated laboratory testbeds ever assembled to study spacecraft dynamics problems. Among the problems studied are actuator/sensor placement, dynamic modeling and testing of large flexible structures, use of active suspension for large structural testing, structure/control interaction of precision pointing instruments, application of modern control design methodology to large structures, and many others. The ability to construct an accurate mathematical model for dynamic response prediction is a critical technology area for future flight experiments. To develop some of the needed tools, a significant amount of time was spent on experimental validation of analytical models. Phase 1 truss design methodology was reported in Ref. [1], actuator and sensor descriptions are found in Ref. [2].

An outline of this document is as follows. Section 2 provides a description of the truss structure and its main components. Section 3 describes the structural models along with corresponding modal testing results and a detailed description of the gimbal models, and control electronics. Finally, a brief summary of the results and some concluding remarks are given in Section 4.

2. Testbed Description

2.1. Structure

The Phase-2 CSI Evolutionary Model (CEM), shown in Fig. 1, consists of a three-dimensional aluminum truss 620 inch long constructed from 10 inch cubical bays. The truss has a 62 bay long center truss, four 2 x 5 bay horizontal suspension trusses, an 11 bay vertical laser tower, and a four bay vertical reflector tower. There are three two axis-gimbals mounted on the main bus. Also a 17 inch diameter reflector is mounted at the top of the vertical tower on the aft end of the structure. All the main components are labeled in Fig. 1. Four cables support the structure from the ceiling, each cable is in series with a pneumatic magnetic suspension system. Active suspension allows all six suspension modes to have a frequency less than 0.2 Hz. The following sections contain a detailed description of the main structural components.

2.1.1. Truss

The truss consists of 117 ten inch cubical bays constructed from five different types of strut elements. There are four different longerons sizes, as indicated in Table 1, but all battens and diagonals are the same size. These strut sizes are used to construct four types of bays distributed throughout the structure as shown in Fig. 2. A close-up view of the truss, Fig. 3, shows a typical truss lacing pattern. The lacing pattern used in the main truss and vertical towers has six or seven struts intersecting at the node ball. Each horizontal suspension appendage is 2 bays wide and has five, eight, or eleven struts intersecting at a given node ball.

2.1.2. Struts

Figures 4 and 5 show the design features and nomenclature for a typical truss member. Notice that a repeatable element of the truss is considered to be the strut tube and two half node balls at each end, but is shown equivalently as having one full node ball at one end. First, a standoff is fastened to the node ball using a steel screw and then the standoff is connected to the strut tube by fastening the nut onto the threaded section of the strut tube. This joint connection allows removal of strut tubes without disassembling others struts in a given bay. The strut length, indicated in Table 1, includes an established stackup tolerance of ± 10 mils to facilitate truss assembly. Joint components such as node balls, standoffs, screws, and nuts are the same for all of the strut sizes. Strut development and testing results are documented in Ref. [3].

2.1.3. Reflector

An important component of the global line-of-sight (LOS) pointing subsystem is the reflector. The reflector, shown in detail in Fig. 6, is a 17 inch diameter 0.375 inch thick aluminum plate with a 10 inch diameter 0.25 inch thick mirror mounted on its surface. A steel circular plate 1.25 inches thick and 16.5 inches in diameter is mounted on the back of the aluminum plate to stiffen and add mass to the structural appendage. A tapered truss bay on the upper part of the aft truss tower supports the reflector at a 39.1 degree inclined position.

To monitor the LOS pointing accuracy, a laser mounted on the forward vertical truss tower is pointed towards the reflector and the laser beam reflection is measured by a photo-diode array over 600 inches above the reflector. This laser-reflector-detector system allows laser position measurements to within 3/10 in. Laser position is sampled and forwarded to the main computer at a maximum rate of 50 Hz. Although this signal is available to the control system, it has been used primarily to monitor the effectiveness of different control schemes.

2.1.4. Gimbals

To simulate interaction of instruments mounted on a spacecraft and the spacecraft control system, three two axis gimbal systems were fabricated and installed on the model. A typical gimbal system, known as a Science Instruments Simulator (SIS), is shown in Fig. 3. Each gimbal system is capable of slewing or pointing to a fixed point on earth with a pointing accuracy of less than 2 arc-seconds. Angular measurements are obtained using an Optical Sensor System (OSS) mounted on the floor underneath the gimbals, see Fig. 3. All OSS were designed and fabricated for use with the model.

Figure 7 shows a photograph of the gimbal system without a payload. The gimbal structure consists of two pivoting aluminum rings that are coplanar and concentric when in the null position. Axes associated with the interior and exterior gimbal rings have been named the "inner" and "outer" axis, respectively. The inner and outer gimbal rings have diameters 8.5 and 10 inches, respectively. Each ring has a motor module on one end and a sensor module at the other end. Each motor module includes a torquer and a cable wrap-up mechanism. The sensor module includes an optical encoder, interpolation

electronics, electromagnetic brakes, and a cable wrap-up for the payload and inner gimbal sensor module.

The gimbals are controlled with a STD Bus 386SX computer that reads encoder pulses, and commands the gimbal torque motors. During gimbal operation, this computer provides commands to control gimbal brakes, motor, and also provides status information to maintain communications with the main computer. All software is written in C language and is executed at 1000 samples per second. Communication of the SIS with the control system is via ARCNET Ref. [4] digital data link.

To test the gimbal with a realistic inertia and payload, a dummy payload is mounted in the two axis gimbal. The dummy payload assembly, shown in Fig. 8, consists of two steel quarter sections, a top aluminum plate with a mirror and plate bracket, a bottom aluminum plate with a laser mounting clamp, a laser, and a mounting ring. The payload is tailored to have a higher mass moment of inertia about the inner axis than the outer axis to counter the smaller outer axis inertia, see Table 2. A removable payload top allows for the inertia and weight to be easily increased if desired. Slotted mounts between the steel quarter sections and the inner ring mount allow some adjustment for balancing purposes. A laser source is clamped to the bottom plate and is pointed towards the Optical Scoring System.

2.1.5. Suspension System

The model is suspended from four points on the ceiling of the laboratory, see Fig. 9. Four pneumatic-magnetic suspension devices are used to provide a near zero-g suspension, Fig. 10a. Attached to these devices are 66.75 foot long 0.170 inch diameter Kevlar cables. All cables are terminated in a Y configuration consisting of two 1/8" 7x19 braided stainless steel cables which attach to the top of two node balls on the model, Fig. 10b. The Y raised the pivot point of the model slightly above the center of gravity (cg.) to produce a desired roll mode of 0.2 Hz.

One goal of the suspension system is to have the frequencies of all 6 suspension modes of the model below 0.2 Hz. This separates the suspension modes from the flexible body modes. The pendulum action of the model hanging from 66.75 ft. cables determined the x, y and yaw modes. The stiffness of the pneumatic suspension system and the geometry of the structure determined the z, roll and pitch modes.

2.2. Instrumentation

Instrumentation for the testbed had to fulfill a number of different purposes, namely instrumentation for model validation, controller performance verification, controller design, and safety. In the following sections, highlights of the different sensors and/or actuators available are discussed.

2.2.1. Accelerometers

The model is instrumented with 51 Sundstrand model QA-900 servo accelerometers, 8 Sundstrand model QA-1400 servo accelerometers, and 129 PCB 330A piezo-film accelerometers. Sensor distribution is shown in Fig. 11 with coordinates given in Table 3. The servo accelerometers provide low-frequency acceleration measurements. Eight of the servo accelerometers are collocated with the air thrusters, and they are generally used as sensors during structural control experiments. The piezo-film accelerometers are used for structural identification tests at frequencies above 1 Hz.

2.2.2. Inertial Measurement Units

To measure angular rates, four Guidance Instrument Clusters GIC-100 units were purchased from Rockwell International. Each instrument cluster unit (size 5.85" x 5.85" x 1.978") provides angular rates and translational accelerations in three orthogonal directions. These units, which are commonly used in missiles, have a serial communication interface via an RS-422. The units are configured with a fixed sample-rate of 600 Hz. Angular rates are measured with a nominal least significant bit (LSB) of ± 16.45 arc-sec/sec and for acceleration the LSB is 0.177 in/s^2 . A significant amount of noise is introduced into the rate measurement due to the gyro bearing noise which can be anywhere between 200 and 600 arc-sec/sec. After initial testing, the units were modified to reduce noise. All units are rated for 150 deg/sec and 15 g's with a corresponding bandwidth of 90 and 60 Hz, respectively. By internal scaling of the signals and a bandwidth reduction, noise levels were reduced by a factor of 2 for rates and 3 for accelerations.

2.2.3. Optical Scoring System

Figure 12 shows a diagram of the OSS and Fig. 3 shows a photograph of the gimbal and OSS station for the CEM. The purpose of the OSS is to measure the relative angle

between an incoming laser beam and the optical axis of the OSS. This measurement is independent of the laser beam translations allowing the CEM tests to simulate a real spacecraft where linear motions have a small impact on image degradation. To remove translation effects, a collimated laser beam is focused into a two axis photo-detector placed in the effective focal plane of the OSS optics. The photo-detector output is proportional to the angle that the laser beam enters the OSS optics. The detector electronics is housed in an annular circuit board and communicates with the OSS computer via an RS-422 high speed serial data link. The OSS computer samples the angular motions and communicates this data at 1000 samples per second via an ARCNET data link.

The OSS has a field of view (FOV) greater than 1000 arc-seconds and accepts laser beam translations up to 6.0 inches. To accommodate the large translation, two six-inch diameter clear aperture objective lenses (focal length = 12 inches) are located in front of the OSS. The FOV is limited by the spot traversing off the detector which is dependent on the effective focal length. For a FOV of 1200 arc-seconds, the required effective focal length is 36 inches. Two small concave lenses achieve this focal length and focus the beam at the photo-detector. When the OSS is mounted toward the ceiling lights, an optical filter reduces detector output noise caused by ambient light.

2.2.4 Air Thrusters

There are 16 air thrusters operating in pairs at eight locations, shown in Fig. 11. The thrusters are linear, bi-directional devices designed and built by Boeing Aerospace Ref. [5]. Each thruster will produce a peak force of 2.2 lbs. The thruster's dynamics is described in Ref. [2].

2.2.5 Shakers

Up to eight long-stroke electrodynamic shakers are available to apply excitations at most points on the structure. Details of the shakers can be found in Ref. [2]. Four of these shakers were used during the modal survey. The shakers were mounted to provide forces at 45 degrees angles relative to the global coordinate system, as shown in Fig. 11. Moreover, servo accelerometers are placed at these skewed locations to measure drive point frequency response functions. Thread mounted PCB 208 force gauges are also used to measure input excitation force at all shaker drive points and Nylon quills (1/4" diameter) are used to transmit shaker excitation.

2.3 Control and Data Acquisition System

The control and data acquisition system (DAS) is centered around two separate data acquisition systems. One system is used for structural dynamics testing, and the another system is used for control experiments. The structural test system is based on a ZONIC SYSTEM 7000 DAS. This system is a commercial general purpose data acquisition and signal processing system. The ZONIC 7000 provides 256 channels of simultaneous data acquisition and 8 channels of excitation. The system can be configured to acquire either time domain or frequency domain data, and this data can be saved in either ASCII or SDRC's ADF (associated data file) data formats. Figure 13 shows the configuration of the system during the modal test. The system is configured to receive analog signals from the accelerometers and force gages and output analog command signals to the shaker amplifiers.

The control system is custom based on the CAMAC (Computer Automated Measurement and Control) standard, see Ref. [9]. The CAMAC system is composed of modules that are mounted in a 'crate' or chassis. These modules interface an external process to a bus, located in the crate, called a dataway. Modules are available to provide analog input and output, communication interfaces (such as ARCnet), and computer interfaces. The system is flexible, and it can be re-configured to meet the experimenter's need. A typical control system configuration is shown in Fig. 14. In this case, four crates are configured to perform control experiments using a centralized or distributed architecture. Three of the crates are used to control each of the gimbals. These crates are equipped with two controllers: one controller is linked to a central computer to provide centralized control of the gimbals, while the other controller is linked to an internal single board real-time computer to provide local control of the gimbals. Gimbal communications are provided via a point-to-point ARCNet network. The fourth crate is configured to provide control of the structure using the air-thrusters as actuators and collocated servo-accelerometers or IMU units as sensors. All the crates are configured to receive data from the optical scoring system via a separate ARCNet network.

3.0 Analytical and Experimental Models

Analytical and/or experimental models have been developed for the main truss structure, Science Instrument Simulators, and the active suspension system. In most cases these models are validated with experimental data and experimentally derived model properties

are obtained via heuristic approaches. Models and experimental results are discussed in the following sections.

3.1. Finite Element Model : Test and Analysis

3.1.1. Finite Element Analysis

A Finite Element Model (FEM) of the Phase-2 Evolutionary Model was constructed using MSC/NASTRAN. A static analysis including gravity preload effects was conducted followed by a normal mode analysis. Static preloading modifies the stiffness matrices used in the vibration analysis. NASTRAN input data deck listings for the static and dynamic analyses are given in Appendix A.

The FEM, shown in Fig. 9, has 664 grid points with 3984 degrees of freedom. Some grid point locations are shown in Fig. 9 and detailed grid point locations are included in Table 4. Beam elements are used to model the struts. Square aluminum-honeycomb core sandwich plates, used to support thrusters, laser, and gimbal controller are modeled using CTRIA3 triangular elements, 4 elements per plate. CQUAD4 elements are used to model the gimbal support plates. The reflector plate geometry is modeled using 8 CTRIA3. All concentrated masses are modeled using CONM2 including the laser, node balls, reflector mirror, instrumentation, and thrusters. In addition, CELAS2 elastic elements are used to model the effects of the thruster air hoses stiffness on the structure. Each pneumatic/magnetic suspension system is modeled as a spring-lumped mass system. A vertical suspension stiffness value of 0.7 lb/in and a suspension carriage moving mass of 0.186 slugs, determined experimentally, are incorporated into the FEM. Each of the four Kevlar cables supporting the structure is represented by 5 CROD elements. For the static differential stiffness computation, the suspension system model has all degrees-of-freedom constrained to avoid excessive deflections during initial loading. Constraints are removed for vibration analyses, allowing displacement of the lumped masses and stretching of the suspension springs.

The geometry of the gimbal rings is modeled by forming CBEAM elements polygons inscribed within 8.5 inches inner and 11 inches outer diameter circles. Motor and sensor shafts as well as the vertical posts supporting the gimbal system are also modeled using CBEAM elements. Lump mass elements, CONM2, including mass moments of inertia properties, are used to model the payload, motor, and sensor units. For modeling purposes, the payload at the center of the inner ring is connected to the ring using four

steel beams 1 in² cross-sectional area. Stiffening of the inner ring due to the payload rigidity is approximated by steel beams.

A complete summary of the element type, element identification number, property identification number, and element locations on the structure are included in Table 5. The material and physical properties of the elements based on the property identification numbers are given in Table 6.

3.1.2. Experimental Set-up and Procedures

A modal test was performed on the Phase-2 CEM in its suspended configuration. Natural frequencies and damping values for six pendulum modes are measured using free decay data. Pure bandpass burst random excitation is employed to excite the 0 to 15 Hz frequency range. Flexible modes are identified from frequency response functions for all sensors described in the following section. Flexible modal parameters are determined using the polyreference complex exponential technique, Ref. [7], on SDRC I-DEAS TestTM.

Pretest analysis - 34 iterations using the Lanczos method yielded 66 modes in the 0 - 30 Hz bandwidth. Sensor and actuator locations are chosen by evaluating their effective independence, see Ref. [8], using mode shape influence coefficients. Appendix B shows an implementation of the algorithm, written using the commercially available program MATLAB. Sensor and actuator locations are described in Sections 2.2.1 and 2.2.5.

Two normal mode solutions are computed, one using all degrees-of-freedom, and a second solution using Guyan reduction which retains only degrees of freedom at locations where sensors are placed. Natural frequencies and eigenvectors cross orthogonality are compared for the full and reduced order models. Results indicated that the reduced inertia properties are well preserved and suitable for test-analysis correlation. Frequencies and corresponding mode shapes excluding cable modes are shown in figures 15 through 49. The first six modes are pendulum modes from 0.14 to 0.27 Hz while the first structural mode appears at 1.72 Hz. A number of cable modes appeared throughout the frequency range analyzed.

Test procedure and modal identification- Natural frequency and damping values for the first six rigid body modes are estimated using free decay data. Specifically, damped natural frequencies are determined by computing the auto spectrum of the response and locating the frequency at which resonance occurred. Damping values are determined by fitting a line to the decaying response in logarithmic space. Five measurements, using 10 servo accelerometers for each measurement, are made for each mode with the thruster air hoses both connected and disconnected. Undamped natural frequencies are then determined from the second order relation:

$$f_n = \frac{f_d}{\sqrt{1 - \zeta^2}}$$

where :

f_n = natural frequency

f_d = frequency of damped oscillation

ζ = damping ratio

Flexible modes are identified from frequency response function measurements. Time history data and frequency response functions are acquired for all sensors chosen in the pretest analysis. Pure bandpass burst random excitation is employed and the modal parameters in terms of natural frequency, damping, and mode shapes are determined using the polyreference technique.

3.1.3. Test/Analysis Correlation Results

Mode Shape Correlation - Analytical and experimental mode frequencies and damping values are compared in Table 7. Also shown are results for cases with and without hoses. Note that thruster air hoses significantly increase the damping of the x-y plane, x-z plane, and y-z plane pendulum modes. Also showing a slight increase in damping are bounce and roll modes, although they are most affected by the suspension system damping. A maximum difference of 5% is observed between analytical and experimental frequencies for the range 0 - 15 Hz with cable modes excluded. In addition, Modal Assurance Criteria (MAC) values show good correlation between test and analysis mode shapes.

After updating the FEM model with new weight information, results between the modal test and analysis showed lower correlation values for all third bending modes than the

previous model. Apparently, the weight distribution for cables and other support equipment mounted on the model have a significant effect on the coupling between higher bending and torsional modes.

Transfer Function Correlation - For control design, transfer functions between the control actuators and sensors are very important. In most cases, air thrusters are used as control actuators and their collocated accelerometers as control sensors. Using the first 95 structural modes, predicted by NASTRAN, Figs. 50 to 53 shows a comparison of the analysis transfer function with test. Figure 50-a shows thruster 1 to its collocated accelerometer 1, and Fig. 50-b shows data for thruster 2 and accelerometer 2. Included structural modes covered a frequency range up to 58 Hz. All analysis modes have assumed modal damping values of 0.1 %. Results compared well in the 0 to 10 Hz range where frequency errors are less than 5 %. Beyond 10 Hz the correlation is not as good. Thruster dynamic is assumed to be first order with a pole at 276.42 rad/sec and a gain of 111.3 lb_f/volt. For controller performance comparison the line-of-sight measured using the OSS is used. Since there are eight thrusters and six OSS angles, a multi-input multi-output frequency response function, shown in Fig. 54, is compared to test in terms of maximum singular values of the thruster to OSS.

3.2. Gimbal Modeling and Test Results

A description of the SIS gimbals was given in Section 2.1.4. Modeling of gimbal system includes the supporting structure and the control system electronics. Both aspects are discussed in the following sections along with experimental results.

Gimbal system - As mentioned earlier, the gimbals are constructed using two concentric rings actuated by torque motors. Support brackets connect the motors to an aluminum base plate which serves as an interface to the truss structure, shown in Fig. 3. MSC/NASTRAN is used for structural modeling and vibration analyses. The inner and outer rings are free to rotate about the global x and y axes. Figure 55 shows axes orientation and gimbal geometry while mounted on the platform. To study gimbal dynamics independently of the truss structure, one gimbal system is bolted to ground and analyzed in that configuration. Inner and outer axes are allowed to rotate in the FEM model to evaluate ring inertia and structural flexibility. Figures 56-60 show the first five gimbal modes. The first two modes are inner and outer ring rigid body modes and the first ring bending mode appeared at 47.32 Hz. Mode number four, which appeared at

108.01 Hz, is an in-plane collapsing of both inner and outer rings. To correlate model with test, hammer tests of the gimbal system were performed to determine resonance frequencies. A proving accelerometer was mounted at various points on the inner and outer ring. The strongest response appeared at a frequency 44 Hz and it is belief to be the first ring mode. To examine the effect of payload inertia, the payload was removed and a hammer test showed a frequency increase of 10 Hz., i.e., the first ring mode is now at 54 Hz. Both these conditions are simulated with the NASTRAN model. Based on analysis the first ring mode without payload was predicted at 53.8 Hz and with payload at 47.3 Hz. In order to match the first mode frequency without payload of the NASTRAN model, the connection between the motor shaft and ring stiffness had to be reduced to 70 % of its ideal value. Although the frequency prediction without payload is good, the total frequency change with the payload is not predicted. Payload inertias computed based on a solid model are 0.0854 $\text{lb}_f\text{-sec}^2\text{-ft}$ for outer axis and 0.1344 $\text{lb}_f\text{-sec}^2\text{-ft}$ for inner axis. In addition to the payload inertia, the estimated outer and inner ring inertias are 0.192 and 0.00314 $\text{lb}_f\text{-sec}^2\text{-ft}$. Although these values are not used directly in NASTRAN, one can compare them to those obtained from the vibration analysis. NASTRAN estimated the total outer axis inertia to be 0.4127 $\text{lb}_f\text{-sec}^2\text{-ft}$ and the total inner inertia to be 0.1384 $\text{lb}_f\text{-sec}^2\text{-ft}$. Over 30% discrepancy is noted in the outer axis inertia, whereas, the inner axis showed less than 0.1 %.

Gimbal Controller - To maintain precision pointing of the gimbal system, a digital control loop is made active using a 386SX computer. A block diagram of the control system is shown in Fig. 61. Operations represented by the discrete transform $G_c(z)$ are implemented digitally at 1000 Hz. Data from the optical encoder θ_e are internally represented in terms of 1/64 of an arc-second. Furthermore, reference commands to the gimbal must be given in terms of 1/64 of an arc-second. All gains in the controller loops are scaled to accept angle information in 1/64 arc-sec increments. A complete model of the gimbal with control electronics is assembled in MATLAB to simulate the closed-loop system. Gimbal controller coefficients and filter settings are also included in Fig. 61.

With the gimbal system bolted to the floor, a transfer function from gimbal commands to the encoder angle is shown in Fig. 62; outer axis at the top, inner axis at the bottom. The predicted corner frequency for the outer axis is 12 % lower than test. This is consistent with the inertia overprediction from the NASTRAN model. Inner axis results showed excellent agreement. For the case shown in Fig. 62, the controller parameter k_e is set to be 0.025 for both outer/inner axes. During bench testing, the controller loop gains were

adjusted to prevent instabilities. Without payload, the loop gain is reduced to 0.01 for outer and 0.001 for inner axis. These gains do not correspond to the stability margin of the controller but are a good experimental compromise.

3.3. Suspension Dynamics and Test Results

Pneumatic-magnetic suspension devices, designed and built by CSA Engineering, are the heart of the suspension system. Each device, shown in Figures 63 and 64 --CSA Model 60350-D--, can lift up to 350 pounds with a stroke of ± 3 inches. The devices are controlled from a control panel on the floor which regulates air pressure and electrical commands. Each device has one hose supplying 60 psi air to the air bearings, a second hose supplying regulated air to the air pistons, and one cable supplying power and control commands.

Operating Principle : The pneumatic-magnetic suspension device uses two parallel subsystems: one passive pneumatic subsystem and one active electromagnetic subsystem, schematic shown in Fig. 65. The passive pneumatic subsystem consists of a clean, dry, air supply, a precision regulator, a 60 gallon accumulator tank and two air pistons. The regulated air balances the load in the air pistons and lifts the payload. The active electromagnetic subsystem consists of an LVDT position sensor, a controller, power amplifier, and a voice coil actuator. Once the controller senses the position of the air piston, commands are sent to the voice coil actuator to keep the payload centered. Without active control, the payload would drift from the center because there would be no restoring force.

Apparent stiffness of each suspension device can be varied independently. It has two components, a pneumatic stiffness and an active stiffness. The pneumatic stiffness is a function of the payload and increases as the load increases. Active stiffness is controlled manually from the control panel and can be varied from 0.05 lb_f/in to over 2.0 lb_f/in . For all testing the active stiffness is set to 0.5 lb_f/in and the pneumatic stiffness is 0.212 lb_f/in for a total stiffness of 0.712 lb_f/in .

4.0 Concluding Remarks

This document describes the Phase-2 CSI Evolutionary Model testbed and characterization. A number of different aspects of this testbed have been discussed in the paper. Instrumentation, control computer, advanced science instrument simulator, and structural modeling are but a few of the unique elements of this testbed. Because of its short life, only limited testing and correlation of most of the analytical models are available. However, the finite element model results in the 0 - 10 Hz frequency range showed good correlation between test and analysis. Also studied, are the effects of air hoses connections on suspension modes. Results indicated significant increase in damping values for pendulum modes.

Modeling of the Science Instrument Simulators (SIS) has proven to be an interesting challenge because of unexplained discrepancies and instabilities observed during testing which are still unresolved. Since these instruments will continue to be used, further modeling work would be required. Nevertheless, the SIS have provided unprecedented accuracy for angular measurements and are a good representation of science instruments flying in spacecrafts today.

A new pneumatic-magnetic suspension system was installed and tested. Although some initial failures occurred, after minor modifications the suspension devices have operated for extended periods of time without any problems. They have proven to be reliable and effective devices for testing large structures under near zero gravity conditions.

This document is a compilation of results generated for this testbed and some of the efforts to resolve discrepancies in our modeling techniques.

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Table 1. Truss struts mass and stiffness properties

Strut Description	Strut Length (in)	Actual OD/ID	Effective Area (in ²)	Strut Weight (lbs)	Node Ball Weight (lbs)
S1 longeron	10.000	0.876/0.376	0.3326	0.467	0.159
S2 longeron	10.000	0.586/0.500	0.0991	0.223	0.159
S3 longeron	10.000	0.660/0.500	0.1747	0.271	0.159
S4 longeron	10.000	0.786/0.500	0.2640	0.353	0.159
Batten	10.000	0.574/0.500	0.0974	0.220	0.159
Diagonal	14.142	0.578/0.500	0.0831	0.245	0.159

- Strut length includes node ball (center-to-center)
- Effective area and strut weight include standoffs, nuts and screws and node balls
- Effective area assumes $E=10.E+6$ lb/in²

Table 2. Gimbal Assembly and Payload Inertia Properties

	I outer in-lbf-sec ²	I inner in-lbf-sec ²
Gimbal assembly (no payload)	2.3031	0.03764
Payload	0.98165	1.5687

Table 3. Actuator and sensor locations

Servo Accelerometers					
No.	X	Y	Z	Direction	Grid No.
1	0.000	5.000	-5.000	Z	4
2	0.000	5.000	-5.000	Y	4
3	0.000	5.000	-5.000	X	4
4	160.000	-5.000	115.000	Z	311
5	160.000	-5.000	115.000	Y	311
6	160.000	-5.000	115.000	X	311
7	120.000	-55.000	-5.000	Z	352
8	120.000	-55.000	-5.000	Y	352
9	120.000	-55.000	-5.000	X	352
10	120.000	55.000	-5.000	Z	348
11	120.000	55.000	-5.000	Y	348
12	120.000	55.000	-5.000	X	348
13	620.000	-5.000	-5.000	Z	251
14	620.000	-5.000	-5.000	Y	251
15	620.000	-5.000	-5.000	X	251
16	620.000	-5.000	35.000	Z	263
17	620.000	-5.000	35.000	Y	263
18	620.000	-5.000	35.000	X	263
19	560.000	55.000	-5.000	Z	431
20	560.000	55.000	-5.000	Y	431
21	560.000	55.000	-5.000	X	431
22	560.000	-55.000	-5.000	Z	435
23	560.000	-55.000	-5.000	Y	435
24	560.000	-55.000	-5.000	X	435
25	60.000	5.000	-5.000	Z	28
26	60.000	5.000	-5.000	Y	28
27	120.000	5.000	-5.000	Z	52
28	120.000	5.000	-5.000	Y	52
29	160.000	5.000	-5.000	Z	68
30	160.000	5.000	-5.000	Y	68
31	250.000	5.000	-5.000	Z	104
32	250.000	5.000	-5.000	Y	104
33	330.000	5.000	-5.000	Z	136
34	330.000	5.000	-5.000	Y	136
35	450.000	5.000	-5.000	Z	184
36	450.000	5.000	-5.000	Y	184
37	560.000	5.000	-5.000	Z	228
38	560.000	5.000	-5.000	Y	228
39	0.000	-5.000	-5.000	Z	3
40	60.000	-5.000	-5.000	Z	27
41	120.000	-5.000	-5.000	Z	51

Table 3. Actuator and sensor locations (Continued)

Servo Accelerometers (Continued)

No.	X	Y	Z	Direction	Grid No.
42	160.000	-5.000	-5.000	Z	67
43	250.000	-5.000	-5.000	Z	103
44	330.000	-5.000	-5.000	Z	135
45	450.000	-5.000	-5.000	Z	183
46	560.000	-5.000	-5.000	Z	227
47	620.000	5.000	-5.000	Z	252
48	140.000	55.000	-5.000	Z	370
49	140.000	-55.000	-5.000	Z	372
50	540.000	55.000	-5.000	Z	454
51	540.000	-55.000	-5.000	Z	456

PCB Structcel Accelerometers

No.	X	Y	Z	Direction	Grid No.
1	140.000	-5.000	-5.000	Z	59
2	140.000	-5.000	-5.000	Y	59
3	140.000	-5.000	-5.000	X	59
4	140.000	5.000	-5.000	Z	60
5	140.000	5.000	-5.000	Y	60
6	140.000	5.000	-5.000	X	60
7	190.000	-5.000	-5.000	Z	79
8	190.000	-5.000	-5.000	Y	79
9	190.000	-5.000	-5.000	X	79
10	190.000	5.000	-5.000	Z	80
11	190.000	5.000	-5.000	Y	80
12	190.000	5.000	-5.000	X	80
13	220.000	-5.000	-5.000	Z	91
14	220.000	-5.000	-5.000	Y	91
15	220.000	-5.000	-5.000	X	91
16	220.000	5.000	-5.000	Z	92
17	220.000	5.000	-5.000	Y	92
18	220.000	5.000	-5.000	X	92
19	280.000	-5.000	-5.000	Z	115
20	280.000	-5.000	-5.000	Y	115
21	280.000	-5.000	-5.000	X	115
22	280.000	5.000	-5.000	Z	116
23	280.000	5.000	-5.000	Y	116
24	280.000	5.000	-5.000	X	116
25	310.000	-5.000	-5.000	Z	127
26	310.000	-5.000	-5.000	Y	127
27	310.000	-5.000	-5.000	X	127

Table 3. Actuator and sensor locations (Continued)

PCB Structural Accelerometers (Continued)					
No.	X	Y	Z	Direction	Grid No.
28	310.000	5.000	-5.000	Z	128
29	310.000	5.000	-5.000	Y	128
30	310.000	5.000	-5.000	X	128
31	360.000	-5.000	-5.000	Z	147
32	360.000	-5.000	-5.000	Y	147
33	360.000	-5.000	-5.000	X	147
34	360.000	5.000	-5.000	Z	148
35	360.000	5.000	-5.000	Y	148
36	360.000	5.000	-5.000	X	148
37	390.000	-5.000	-5.000	Z	159
38	390.000	-5.000	-5.000	Y	159
39	390.000	-5.000	-5.000	X	159
40	390.000	5.000	-5.000	Z	160
41	390.000	5.000	-5.000	Y	160
42	390.000	5.000	-5.000	X	160
43	420.000	-5.000	-5.000	Z	171
44	420.000	-5.000	-5.000	Y	171
45	420.000	-5.000	-5.000	X	171
46	420.000	5.000	-5.000	Z	172
47	420.000	5.000	-5.000	Y	172
48	420.000	5.000	-5.000	X	172
49	480.000	-5.000	-5.000	Z	195
50	480.000	-5.000	-5.000	Y	195
51	480.000	-5.000	-5.000	X	195
52	480.000	5.000	-5.000	Z	196
53	480.000	5.000	-5.000	Y	196
54	480.000	5.000	-5.000	X	196
55	510.000	-5.000	-5.000	Z	207
56	510.000	-5.000	-5.000	Y	207
57	510.000	-5.000	-5.000	X	207
58	510.000	5.000	-5.000	Z	208
59	510.000	5.000	-5.000	Y	208
60	510.000	5.000	-5.000	X	208
61	540.000	-5.000	-5.000	Z	219
62	540.000	-5.000	-5.000	Y	219
63	540.000	-5.000	-5.000	X	219
64	540.000	5.000	-5.000	Z	220
65	540.000	5.000	-5.000	Y	220
66	540.000	5.000	-5.000	X	220
67	590.000	-5.000	-5.000	Z	239
68	590.000	-5.000	-5.000	Y	239

Table 3. Actuator and sensor locations (Continued)

PCB Structcel Accelerometers (Continued)					
No.	X	Y	Z	Direction	Grid No.
69	590.000	-5.000	-5.000	X	239
70	590.000	5.000	-5.000	Z	240
71	590.000	5.000	-5.000	Y	240
72	590.000	5.000	-5.000	X	240
73	620.000	-5.000	15	Z	255
74	620.000	-5.000	15	Y	255
75	620.000	-5.000	15	X	255
76	620.000	5.000	15	Z	256
77	620.000	5.000	15	Y	256
78	620.000	5.000	15	X	256
79	620.000	5.000	35	Z	264
80	620.000	5.000	35	Y	264
81	620.000	5.000	35	X	264
82	160.000	-5.000	55	Z	287
83	160.000	-5.000	55	Y	287
84	160.000	-5.000	55	X	287
85	160.000	5.000	55	Z	288
86	160.000	5.000	55	Y	288
87	160.000	5.000	55	X	288
88	160.000	-5.000	85	Z	299
89	160.000	-5.000	85	Y	299
90	160.000	-5.000	85	X	299
91	160.000	5.000	85	Z	300
92	160.000	5.000	85	Y	300
93	160.000	5.000	85	X	300
94	160.000	5.000	115	Z	312
95	160.000	5.000	115	Y	312
96	160.000	5.000	115	X	312
97	0.000	-5.000	-5.000	Y	3
98	0.000	-5.000	-5.000	X	3
99	60.000	-5.000	-5.000	Y	27
100	60.000	-5.000	-5.000	X	27
101	120.000	-5.000	-5.000	Y	51
102	120.000	-5.000	-5.000	X	51
103	160.000	-5.000	-5.000	Y	67
104	160.000	-5.000	-5.000	X	67
105	250.000	-5.000	-5.000	Y	103
106	250.000	-5.000	-5.000	X	103
107	330.000	-5.000	-5.000	Y	135
108	330.000	-5.000	-5.000	X	135
109	450.000	-5.000	-5.000	Y	183

Table 3. Actuator and sensor locations (Continued)

PCB Structcel Accelerometers (Continued)

No.	X	Y	Z	Direction	Grid No.
110	450.000	-5.000	-5.000	X	183
111	560.000	-5.000	-5.000	Y	227
112	560.000	-5.000	-5.000	X	227
113	620.000	5.000	-5.000	Y	252
114	620.000	5.000	-5.000	X	252
115	140.000	55.000	-5.000	Y	370
116	140.000	55.000	-5.000	X	370
117	140.000	-55.000	-5.000	Y	372
118	140.000	-55.000	-5.000	X	372
119	540.000	55.000	-5.000	Y	454
120	540.000	55.000	-5.000	X	454
121	540.000	-55.000	-5.000	Y	456
122	540.000	-55.000	-5.000	X	456
123	60.000	5.000	-5.000	X	28
124	120.000	5.000	-5.000	X	52
125	160.000	5.000	-5.000	X	68
126	250.000	5.000	-5.000	X	104
127	330.000	5.000	-5.000	X	136
128	450.000	5.000	-5.000	X	184
129	560.000	5.000	-5.000	X	228

Thrusters Servo accelerometers

No.	X	Y	Z	Direction	Grid No.
1	5.000	5.000	0.000	Y	492
2	5.000	0.000	5.000	Z	489
3	325.000	5.000	0.000	Y	501
4	325.000	0.000	5.000	Z	498
5	620.000	0.000	40.000	X	503
6	615.000	5.000	40.000	Y	502
7	160.000	0.000	100.000	X	494
8	155.000	5.000	100.000	Y	493

Shakers Driving Points Servo Accelerometers

No.	X	Y	Z	Direction	Grid No.
1	0.000	-5.000	-5.000	X	901
2	320.000	-5.000	-5.000	X	902
3	140.000	-55.000	-5.000	X	903
4	540.000	-55.000	-5.000	X	904

Table 4. Summary of FEM grid numbers

Truss Coordinate Information					
Grids	No.	Location	X	Y	Z
1 - 252	252	main truss	0,620	5,-5	5,-5
253 - 268	16	reflector truss	610,620	5,-5	15,45
269-312	44	tower truss	150,160	5,-5	15,115
313 - 372	60	forward suspension truss	120,140	55,-55	5,-5
397 - 456	60	back suspension truss	540,560	55,-55	5,-5
485 - 488	4	reflector support bracket	610,620	5,-5	52.06,60.16
489 -492	4	forward thruster	5	5,-5	5,-5
493 - 496	4	tower thruster	150,160	5,-5	100
497	1	laser	155	0	155
498 - 501	4	middle thruster	325	5,-5	5,-5
502 - 505	4	reflector truss thruster	610,620	5,-5	40
508 - 516	9	front suspension cable & spring, +Y	130	45,55	6.78,803.5
518 - 526	9	front suspension cable & spring, -Y	130	-45,-55	6.78,803.5
528 - 536	9	back suspension cable & spring, +Y	550	45,55	6.78,803.5
538 - 546	9	back suspension cable & spring, -Y	550	-45,-55	6.78,803.5
550 - 602	53	gimbal #1	115,140	10,-10	12.71,18.71
650 - 702	53	gimbal #2	175,200	10,-10	12.71,18.71
750 - 802	53	gimbal #3	535,560	10,-10	12.71,18.71
605	1	gimbal #1 controller plate	140	0.00	0.00
705	1	gimbal #2 controller plate	200	0.00	0.00
805	1	gimbal #3 controller plate	560	0.00	0.00
901 - 904	4	shakers	0,540	-5,-55	-5

Reflector, Cylindrical Coordinates

Grids	No.	Location	R, in	Theta, deg.	Z, in
851,858	8	base plate	8.15	0, 322.16	0.811
859	1	plate center	0.00	0.00	0.811

truss grids = 655
 reflector grids = 9
 total grids = 664

Table 5. Summary of FEM element numbers

Truss Elements Information

Element	EID's	No.	PID	Location
CBEAM	1 - 80	80	101	main truss, S1 longerons
CBEAM	81 - 248	168	401	main truss, S4 longerons
CBEAM	249 - 332	84	102	main truss, S1 battens
CBEAM	333 - 500	168	402	main truss, S4 battens
CBEAM	501 - 521	21	103	main truss, S1 batten diagonals
CBEAM	522 - 563	40	403	main truss, S4 batten diagonals
CBEAM	566 - 603	34	103	main truss, S1 top and bottom diagonals
CBEAM	604 - 687	80	403	main truss, S4 top and bottom diagonals
CBEAM	690 - 727	38	103	main truss, S1 side diagonals
CBEAM	728 - 811	82	403	main truss, S4 side diagonals
CBEAM	812 - 855	44	301	tower truss, S3, longerons
CBEAM	856 - 899	44	302	tower truss, S3, battens
CBEAM	900 - 909	10	303	tower truss, S3 batten diagonals
CBEAM	911 - 932	20	303	tower truss, S3, front and back diagonals
CBEAM	933 - 954	20	303	tower truss, S3, side diagonals
CBEAM	955 - 970	16	201	reflector truss, S2, longerons
CBEAM	971 - 986	16	202	reflector truss, S2, battens
CBEAM	987 - 990	4	203	reflector truss, S2, batten diagonals
CBEAM	991 - 996	6	203	reflector truss, S2, side diagonals
CBEAM	999 - 1004	6	203	reflector truss, S2, front and back diagonals
CBEAM	1007 - 1036	30	201	front suspension truss, S2 longerons, +Y
CBEAM	1037 - 1066	30	201	front suspension truss, S2 longerons, -Y
CBEAM	1072 - 1106	35	202	front suspension truss, S2 battens, +Y
CBEAM	1112 - 1146	35	202	front suspension truss, S2 battens, -Y
CBEAM	1167 - 1176	10	203	front suspension truss, S2 batten diagonals, +Y
CBEAM	1177 - 1186	10	203	front suspension truss, S2 batten diagonals, -Y
CBEAM	1187 - 1201	15	203	front suspension truss, S2 front and back diagonals, +Y
CBEAM	1207 - 1221	15	203	front suspension truss, S2 front and back diagonals, -Y
CBEAM	1227 - 1246	20	203	front suspension truss, S2 top and bottom diagonals, +Y
CBEAM	1247 - 1266	20	203	front suspension truss, S2 top and bottom diagonals, -Y
CBEAM	1267 - 1296	30	201	back suspension truss, S2 longerons, +Y
CBEAM	1307 - 1336	30	201	back suspension truss, S2 longerons, -Y
CBEAM	1347 - 1381	35	202	back suspension truss, S2 battens, +Y
CBEAM	1387 - 1421	35	202	back suspension truss, S2 battens, -Y
CBEAM	1427 - 1436	10	203	back suspension truss, S2 batten diagonals, +Y
CBEAM	1437 - 1446	10	203	back suspension truss, S2 batten diagonals, -Y
CBEAM	1447 - 1461	15	203	back suspension truss, S2 front and back diagonals, +Y
CBEAM	1467 - 1481	15	203	back suspension truss, S2 front and back diagonals, -Y
CBEAM	1487 - 1506	20	203	back suspension truss, S2 top and bottom diagonals, +Y
CBEAM	1507 - 1526	20	203	back suspension truss, S2 top and bottom diagonals, -Y
CBEAM	1531 - 1534	4	27	reflector support bracket beams

Table 5. Summary of FEM element numbers (Continued)

Truss Elements Information (continued)

Element	EID's	No.	PID	Location
CBEAM	1535 - 1540	6	28	reflector support bracket beams
CBEAM	1541 - 1542	2	29	reflector support bracket beams

Suspension, gimbals, reflector and thrusters elements

Element	EID's	No.	PID	Location
CROD	1551 - 1555	5	14	front suspension kevlar cable, +Y
CROD	1556 - 1557	2	13	front suspension short stainless steel cable, +Y
CBEAM	1558 - 1559	2	12	front suspension cable standoff, +Y
CROD	1561 - 1565	5	14	front suspension cable, -Y
CROD	1566 - 1567	2	13	front suspension short stainless steel cable, -Y
CBEAM	1568 - 1569	2	12	front suspension cable standoff, -Y
CROD	1571 - 1575	5	14	back suspension cable, +Y
CROD	1576 - 1577	2	13	back suspension short stainless steel cable, +Y
CBEAM	1578 - 1579	2	12	back suspension cable standoff, +Y
CROD	1581 - 1585	5	14	back suspension cable, -Y
CROD	1586 - 1587	2	13	back suspension short stainless steel cable, -Y
CBEAM	1588 - 1589	2	12	back suspension cable standoff, -Y
CBEAM	1601 - 1608	8	502	gimbal #1 support beams
CBEAM	1609 - 1646	38	4	gimbal #1 1/2"X1" ring
CBEAM	1647 - 1648	2	5	gimbal #1 3"X3" posts
CBEAM	1651 - 1654	4	11	support for gimbal #1 laser
CBEAM	1661 - 1672	12	17	weightless back-up beams for gimbal #1 plate
CQUAD4	1681 - 1688	8	1	gimbal #1 plate
CTRIA3	1691 - 1694	4	15	gimbal #1 controller (IMU) board plate
CBEAM	1695 - 1698	4	17	weightless back-up beams for gimbal #1 IMU plate
CBEAM	1701 - 1708	8	502	gimbal #2 support beams
CBEAM	1709 - 1746	38	4	gimbal #2 1/2"X1" ring
CBEAM	1747 - 1748	2	5	gimbal #2 3"X3" posts
CBEAM	1751 - 1754	4	11	support for gimbal #2 laser
CBEAM	1761 - 1772	12	17	weightless back-up beams for gimbal #2 plate
CQUAD4	1781 - 1788	8	1	gimbal #2 plate
CTRIA3	1791 - 1794	4	15	gimbal #2 controller (IMU) board plate
CBEAM	1795 - 1798	4	17	weightless back-up beams for gimbal #2 IMU plate
CBEAM	1801 - 1808	8	502	gimbal #3 support beams
CBEAM	1809 - 1846	38	4	gimbal #3 1/2"X1" ring
CBEAM	1847 - 1848	2	5	gimbal #3 3"X3" posts
CBEAM	1851 - 1854	4	11	support for gimbal #3 laser
CBEAM	1861 - 1872	12	17	weightless back-up beams for gimbal #3 plate
CQUAD4	1881 - 1888	8	1	gimbal #3 plate
CTRIA3	1891 - 1894	4	15	gimbal #3 controller (IMU) board plate
CBEAM	1895 - 1898	4	17	weightless back-up beams for gimbal #3 IMU plate

Table 5. Summary of FEM element numbers (Continued)

Suspension, gimbals, reflector and thrusters elements (continued)

Element	EID's	No.	PID	Location
CQUAD4	1900	1	40	front end steel plate
CTRIA3	1901 - 1916	16	15	forward thruster plate
CTRIA3	1921 - 1936	16	15	tower thruster plate
CTRIA3	1941 - 1956	16	15	middle thruster plate
CTRIA3	1961 - 1976	16	15	reflector truss thruster plate
CTRIA3	1981 - 1984	4	15	laser plate
CQUAD4	1991 - 1992	2	15	thruster controller board plate
CBEAM	2000 - 2007	8	17	weightless back-up beams for forward thruster
CBEAM	2010 - 2019	10	17	weightless back-up beams for tower thruster
CBEAM	2020 - 2027	8	17	weightless back-up beams for middle thruster
CBEAM	2030 - 2037	8	17	weightless back-up beams for reflector tower thruster
CBEAM	2040 - 2043	4	17	weightless back-up beams for reflector plate
CBEAM	2045 - 2048	4	12	reflector plate connectors to reflector truss
CTRIA3	2051 - 2058	8	25	reflector plate
CELAS2	2201 - 2204	4		suspension springs
CELAS2	2241 - 2252	12		air tubing stiffness at thrusters

Lumped mass elements

Element	EID's	No.	Location
CONM2	3001 - 3372	372	joint lumped mass
CONM2	3393 - 3452	60	joint lumped mass
CONM2	3453 - 3464	12	suspension cable mass
CONM2	3465 - 3476	12	gimbal encoder, decoder mass
CONM2	3477 - 3479	3	gimbal laser mass
CONM2	3481 - 3492	12	half node balls at ends of gimbal support beams
CONM2	3501 - 3562	62	instrumentation mass
CONM2	3563 - 3569	7	thruster air hose mass
CONM2	3770	1	thruster air hose mass
CONM2	3570 - 3577	8	thruster controller mass
CONM2	3578 - 3589	12	air supply bracket and tubing mass
CONM2	3590 - 3605	16	thruster mass
CONM2	3606	1	laser mass
CONM2	3610 - 3615	6	thruster controller board signal cable mass
CONM2	3621 - 3632	12	gimbal controller board
CONM2	3633 - 3635	3	MU at controller board
CONM2	3636 - 3639	4	mass at suspension springs

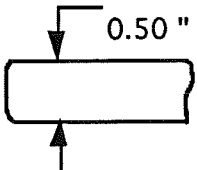
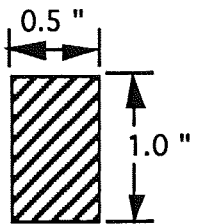
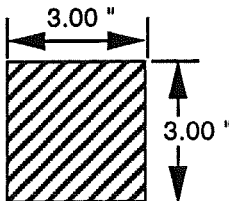
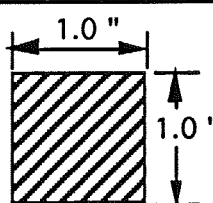
Table 5. Summary of FEM element numbers (Continued)

Elements removed from truss				
Element	EID's	No.	PID	Location
CBEAM	526	-1	403	batten diagonal in the way of controller plate
CBEAM	542	-1	403	batten diagonal in the way of controller plate
CBEAM	588	-1	103	top, bottom diagonal in the way of gimbal #1
CBEAM	589	-1	103	top, bottom diagonal in the way of gimbal #1
CBEAM	600	-1	103	top, bottom diagonal in the way of gimbal #2
CBEAM	601	-1	103	top, bottom diagonal in the way of gimbal #2
CBEAM	672	-1	103	top, bottom diagonal in the way of gimbal #3
CBEAM	673	-1	103	top, bottom diagonal in the way of gimbal #3

Total number of elements

CBEAM	1687
CROD	28
CTRIA3	88
CQUAD4	27
CELAS2	16
CONM2	603

Table 6. FEM Physical Section Properties

PID	Dimension	Sections	Elements	Property of sections	Material property
1	t= 0.500"		CQUAD4 gimbal plate	t= 0.500"	E = 1.0E+07 v = 0.333 ρ = 3.8E-04
4	1/2" X 1"		CBEAM gimbal ring	A= 0.500 I1= 0.041667 I2= 0.010417 J= 0.02861	E = 1.0E+07 v = 0.333 ρ = 2.62E-4
5	3" X 3"		CBEAM gimbal posts	A= 9.00 I1= 6.75 I2= 6.75 J= 11.407	E = 1.0E+07 v = 0.333 ρ = 0.000
11 , 12	1" X 1"		CBEAM support beams for gimbal laser, suspension cable standoff, rfl plate	A= 1.00 I1= 0.08333 I2= 0.08333 J= 0.166667	E = 3.0E+07 G = 1.1538E+07 ρ = 0.000

where,

A is the cross sectional area in units of in²

J is the bending moment of inertia in units of in⁴

I is the torsional moment of inertia in units of in⁴

E is the Young's Modulus in units of lb_f / in²

G is the Shear Modulus in units of lb_f / in²

v is Poisson's ratio

ρ is the mass density in units of lb_f -sec² / in

Table 6. FEM Physical Section Properties (Continued)



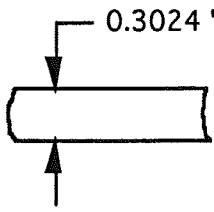
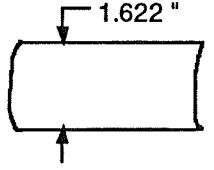

PID	Dimension	Sections	Elements	Property of sections	Material property
13	O.D.= 0.125"	 O.D.= 0.125"	CROD suspension short stainless steel cables	A= 0.012272 J= 0.000	E = 3.0E+07 G = 1.1538E+07 ρ = 7.332E-04
14	O.D.= 0.170"	 O.D.= 0.170"	CROD suspension kevlar cable	A= 0.022698 J= 0.000	E = 5.0E+06 ρ = 1.01E-04
15	t= 0.3024"	 0.3024 "	CTRIA3 thruster, laser, and gimbal, controller board (IMU) plates	t= 0.3024"	E = 1.0E+07 ν = 0.333 ρ = 0.000
17	N/A	N/A	CBEAM wtless back-up beams for thruster, rfl., gimbal and IMU board plates	A= 0.001 I1= 0.0001 I2= 0.0001 J= 0.0002	E = 1.0E+07 ν = 0.333 ρ = 0.000
25	t= 1.622"	 1.622 "	CTRIA3 reflector plate	t= 1.622"	E = 3.0E+07 G = 1.1538E+07 ρ = 7.332E-04
27	O.D.= 0.75"	 O.D.= 0.75"	CBEAM reflector support bracket beams	A= 0.4418 I1= 0.0155 I2= 0.0155 J = 0.031	E = 1.0E+07 G = 3.7509E+06 ρ = 2.5390E-04

Table 6. FEM Physical Section Properties (Continued)

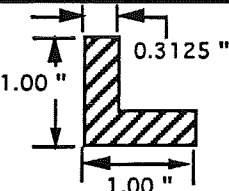
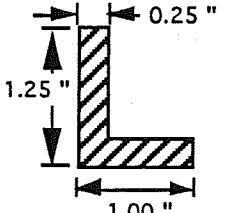
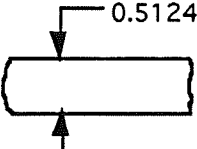
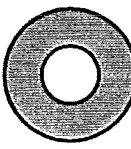
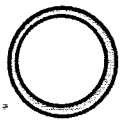
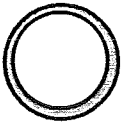
PID	Dimension	Sections	Elements	Property of sections	Material property
28	1 X 1 X 5/16"		CBEAM aluminum angle for rfl support	A= 0.3390 I1= 0.0300 I2= 0.0300 J= 0.00439	E = 1.0E+07 G = 3.7509E+06 ρ = 2.5390E-04
29	1 X 1.25 X 1/4"		CBEAM aluminum angle cross members, rfl support	A= 0.500 I1= 0.0397 I2= 0.0397 J= 0.071	E = 1.0E+07 G = 3.7509E+06 ρ = 2.5390E-04
40	t= 0.512367"		CQUAD4 front end steel plate	t= 0.512367"	E = 3.0E+07 G = 1.1538E+07 ρ = 7.332E-04
101	O.D.= 0.876" I.D.= 0.376"	 O.D.= 0.876" I.D.= 0.376"	CBEAM S1 longerons	A= 0.333 I1= 0.027803 I2= 0.027803 J= 0.055607	E = 1.0E+07 ν = 0.333 ρ = 3.6358E-04
102, 202, 302, 402, 502	O.D.= 0.574" I.D.= 0.500"	 O.D.= 0.574" I.D.= 0.500"	CBEAM S1 battens S2 battens S3 battens S4 battens gimbal support	A=0.0974 I1= 0.002335 I2= 0.002335 J= 0.00467	E = 1.0E+07 ν = 0.333 ρ = 5.8464E-04
201	O.D.= 0.586" I.D.= 0.500"	 O.D.= 0.586" I.D.= 0.500"	CBEAM S2 longerons	A= 0.0991 I1= 0.00276 I2= 0.00276 J= 0.00552	E = 1.0E+07 ν = 0.333 ρ = 5.8206E-04

Table 6. FEM Physical Section Properties (Continued)


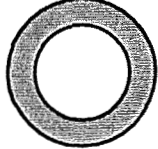
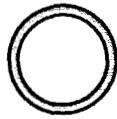
PID	Dimension	Sections	Elements	Property of sections	Material property
301	O.D.= 0.660" I.D.= 0.500"	 O.D.= 0.660" I.D.= 0.500"	CBEAM S3 longerons	A=0.1750 I1= 0.006303 I2= 0.006303 J= 0.012605	E = 1.0E+07 ν = 0.333 ρ = 4.0156E-04
401	O.D.= 0.786" I.D.= 0.500"	 O.D.= 0.786" I.D.= 0.500"	CBEAM S4 longerons	A= 0.2640 I1= 0.01576 I2= 0.01576 J= 0.031525	E = 1.0E+07 ν = 0.333 ρ = 3.4581E-04
103, 203, 303, 403,	O.D.= 0.578" I.D.= 0.500"	 O.D.= 0.578" I.D.= 0.500"	CBEAM S1 diagonals S2 diagonals S3 diagonals S4 diagonals	A=0.0831 I1= 0.002449 I2= 0.002449 J= 0.004897	E = 1.0E+07 ν = 0.333 ρ = 5.3917E-04

Table 7. Phase - 2 CEM analytical and experimental mode frequencies and damping

Mode No.	Test Frequency with hoses (Hz)	Analysis Frequency with hoses (Hz)	With Hose Test-Analysis MAC Value	Test Damping with hoses %	Test Damping without hoses %	Description
1	0.136	0.139		3.658	0.607	Y-Pendulum
2	0.135	0.140		4.576	0.471	X-Pendulum
3	0.132	0.149		5.503	0.448	Yaw
4	0.180	0.161		5.807	5.086	Bounce (Node Near Laser Tower)
5	0.192	0.164		5.885	4.585	Bounce (Node Near Reflector Tower)
6	0.344	0.276		2.420	1.910	Roll
7	1.780	1.725	0.997	0.181	0.181	1st Torsion
8	2.434	2.400	0.998	0.181	0.146	1st X,Z Bending
9	3.049	2.967	0.998	0.291	0.184	1st X,Y Bending
10	5.689	5.486	0.997	0.183	0.147	2nd X,Z Bending
11	6.137	5.850	0.998	0.175	0.131	Refl Appendage Rocking
12	6.577	6.421	0.964	0.202	0.514	Refl Appendage Rocking
13		6.444				
14		6.509				
15	6.451	6.533	0.555	0.575	0.407	Cable
16	7.218	6.923	0.730	0.195	0.204	
17		6.955				
18		7.014				
19		7.046				
20	7.777	7.684	0.998	0.236	0.143	Laser Tower X,Z Bending
21	8.719	8.405	0.993	0.25	0.221	2nd X,Y Bending
22	9.146	9.002	0.995	0.177	0.177	2nd X,Z Bending
23	10.212	10.042	0.996	0.206	0.191	Laser Tower Y,Z Bending
24		12.241				
25		12.287				

Table 7. Phase - 2 CEM analytical and experimental mode frequencies and damping (Continued)

Mode No.	Test Frequency with hoses (Hz)	Analysis Frequency with hoses (Hz)	With Hose Test-Analysis MAC Value	Test Damping with hoses %	Test Damping without hoses %	Description
26		12.374				
27		12.419				
28		12.679				
29		13.203				
30		13.264				
31		13.343				
32		13.404				
33	13.628	13.551	0.860	0.341	0.335	3rd X,Z Bending
34	13.087	13.635	0.954	0.057	0.061	3rd X,Y Bending
35		14.088				
36	14.578	14.267	0.866	0.077	0.446	Cable
37		15.054				
38		15.668				
39	14.32	16.302	0.596	0.254	0.227	Cable
40		16.926				
41		16.987				
42		17.028				
43		17.089				
44		17.817				
45		18.164				
46		18.246				
47		18.329				
48		18.361				
49		18.446				
50		18.739				

Table 7. Phase - 2 CEM analytical and experimental mode frequencies and damping (Continued)

Mode No.	Test Frequency with hoses (Hz)	Analysis Frequency with hoses (Hz)	With Hose Test-Analysis MAC Value	Test Damping with hoses %	Test Damping without hoses %	Description
51		19.974				
52		20.012				
53		20.046				
54		20.084				
55		20.921				
56		21.542				
57		21.578				
58		21.640				
59		21.677				
60		23.185				
61		23.910				
62		24.825				
63		25.752				
64		27.575				
65		28.433				
66		28.984				

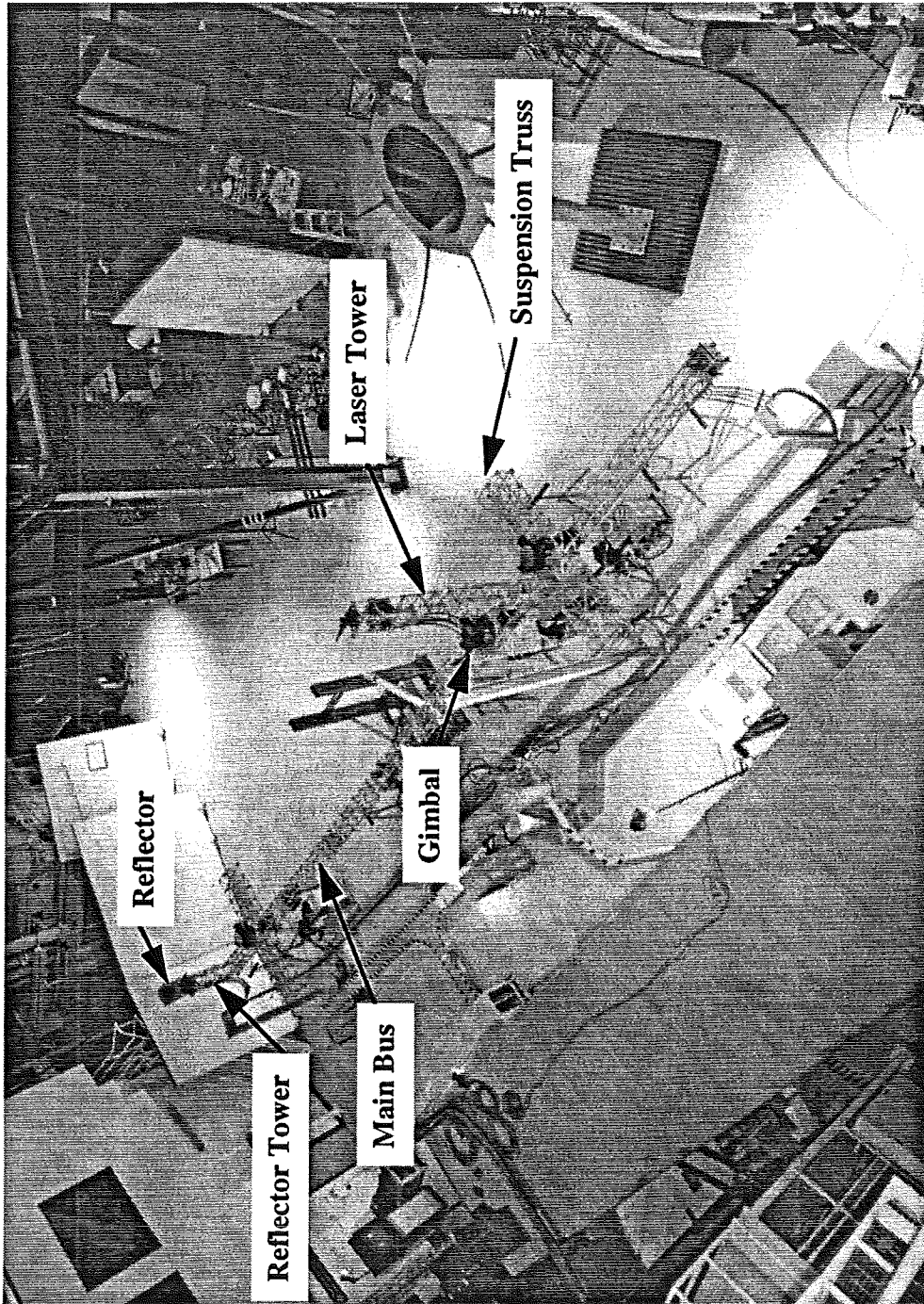


Figure 1. Phase-2 CSI Evolutionary Model (CEM)

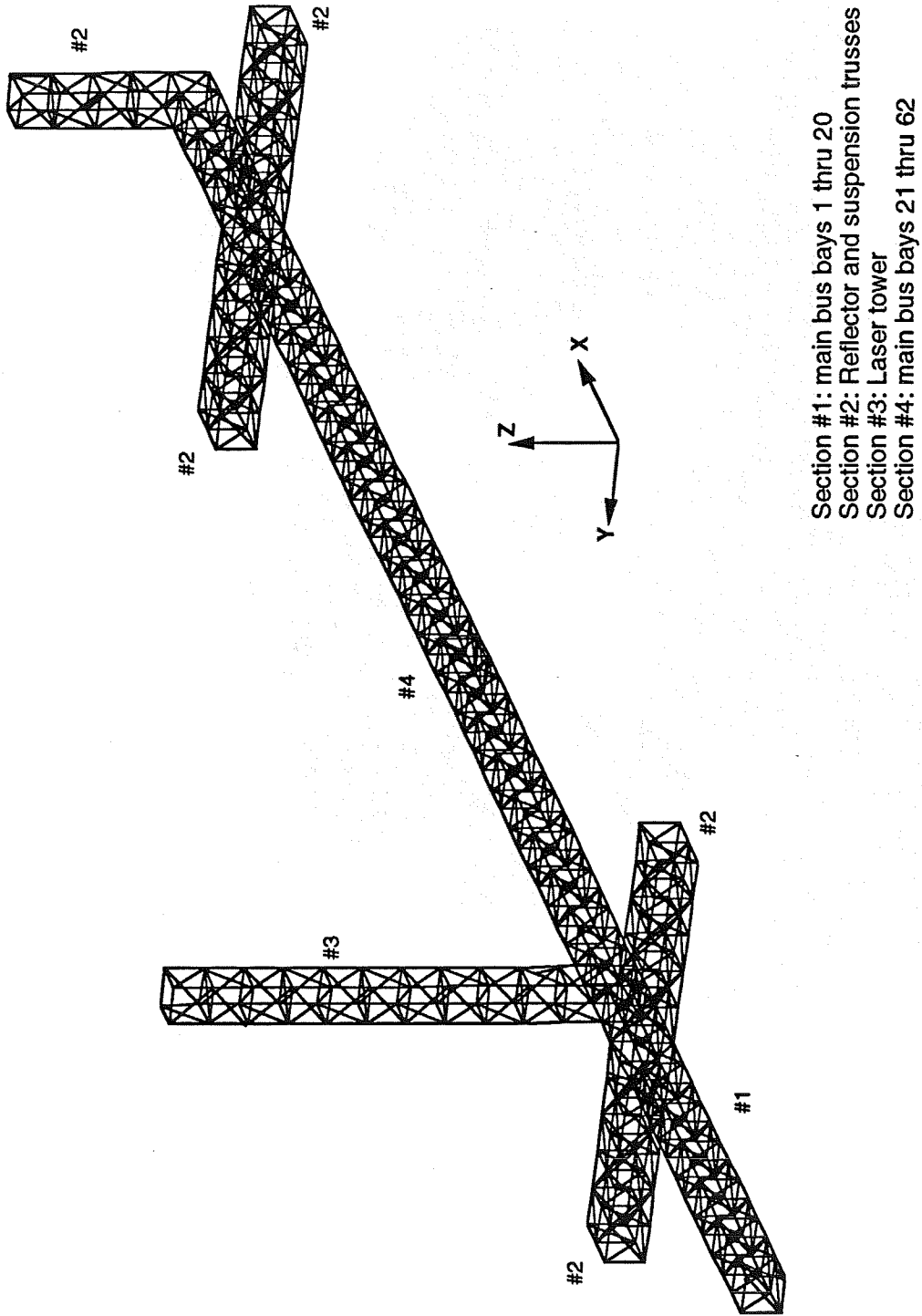


Figure 2. Phase-2 CEM truss sections

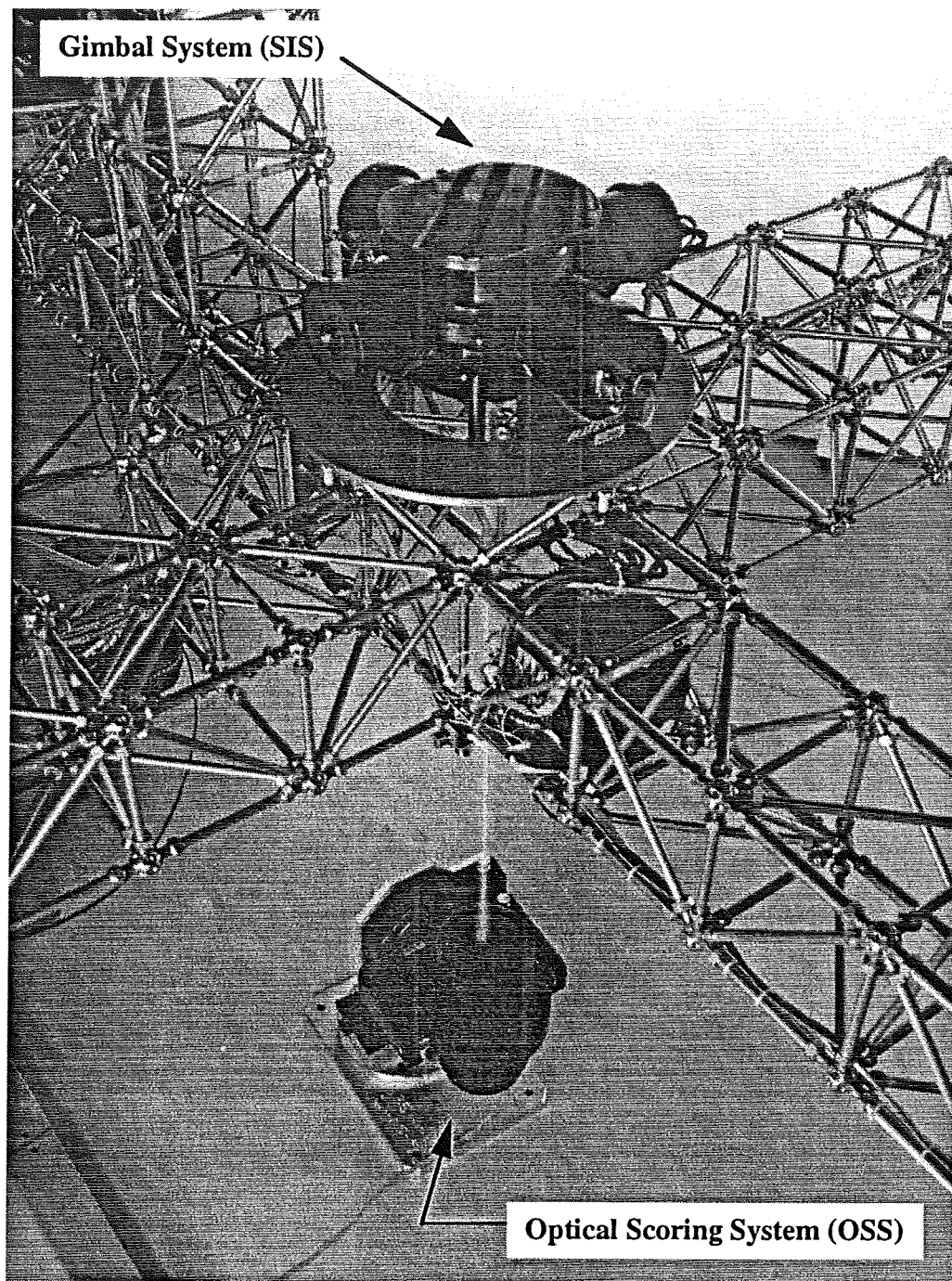


Figure 3. Closed-up of truss lacing and science instrument simulator

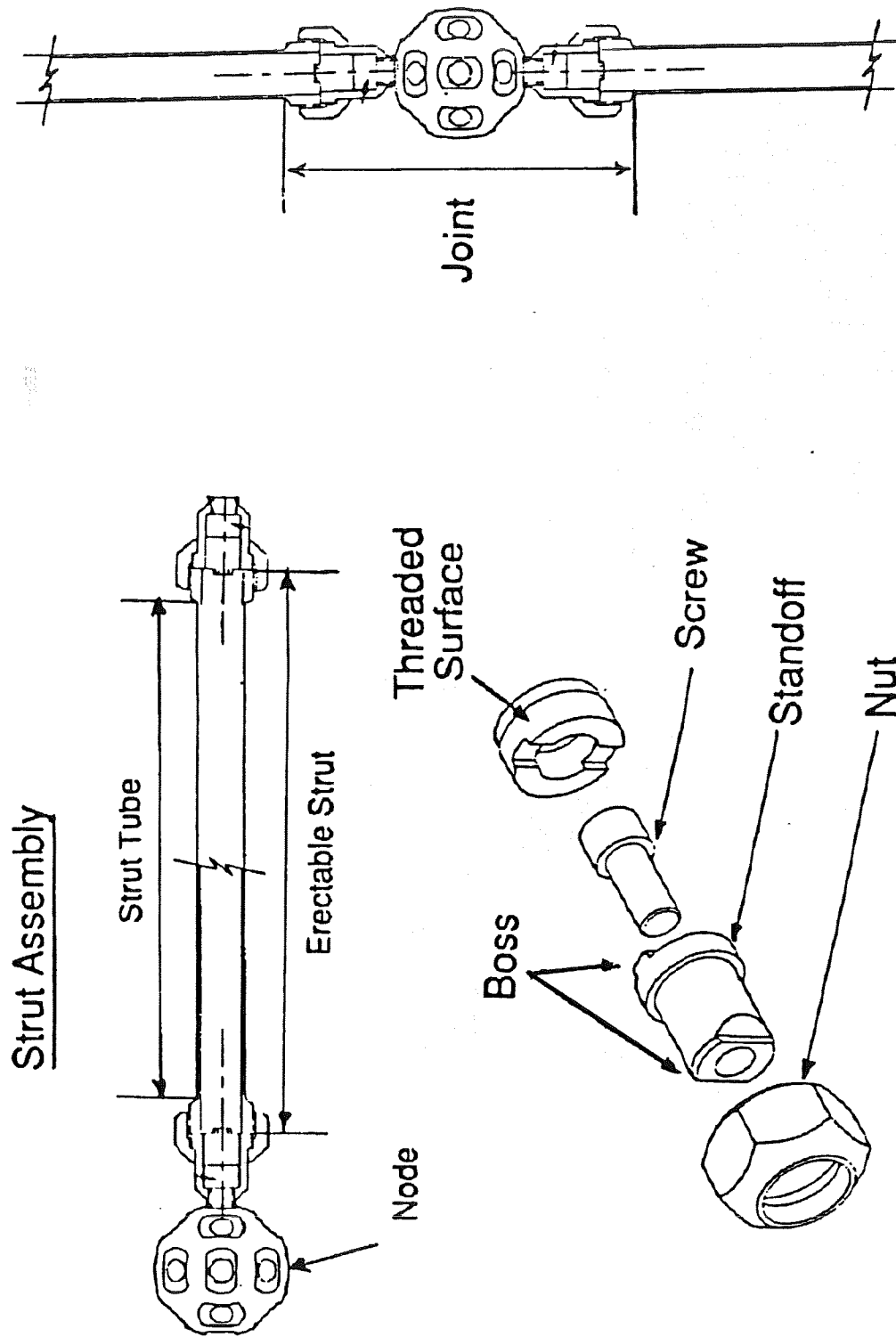


Figure 4. Phase-2 Strut design features and nomenclature

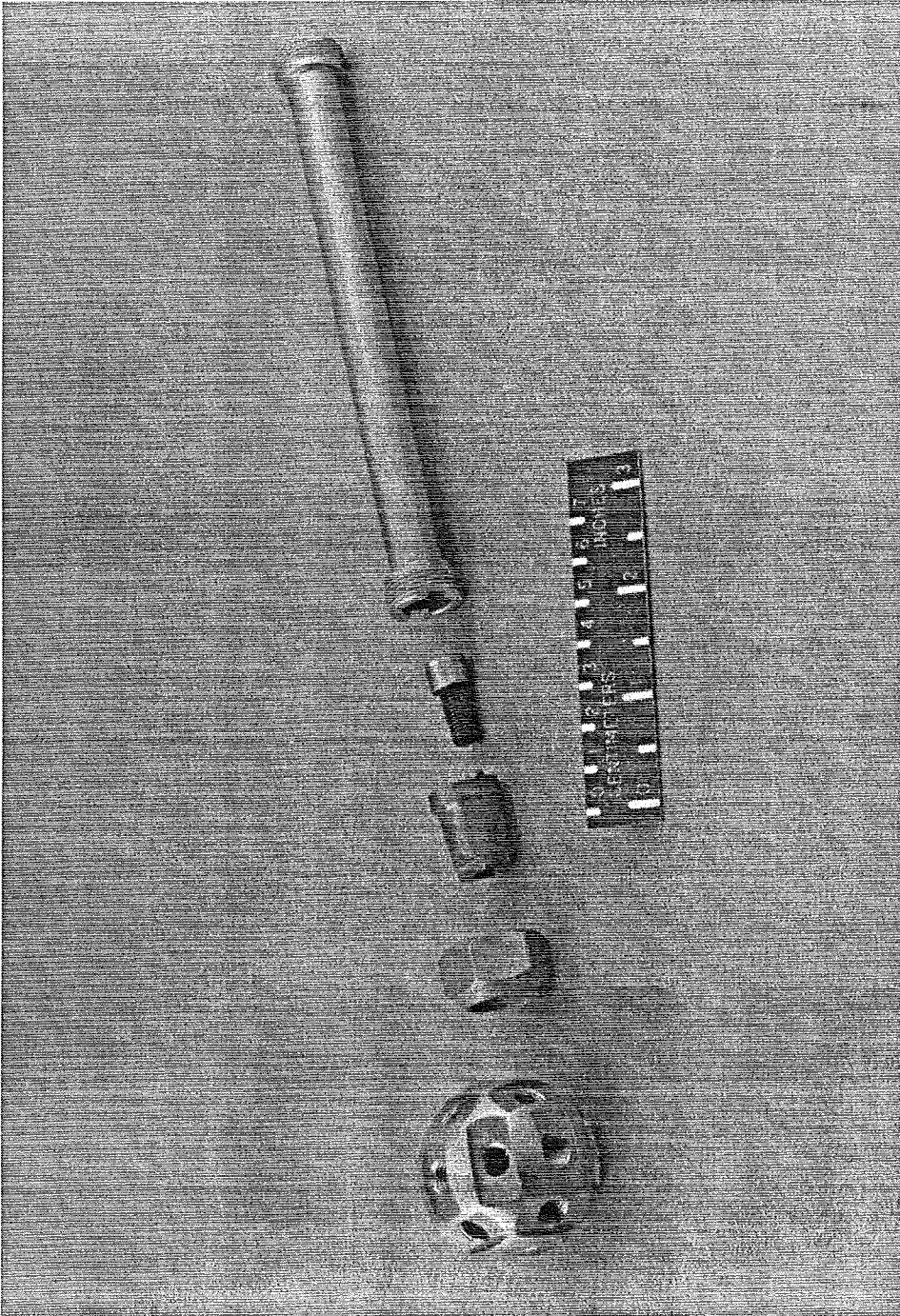


Figure 5. Strut and node ball hardware

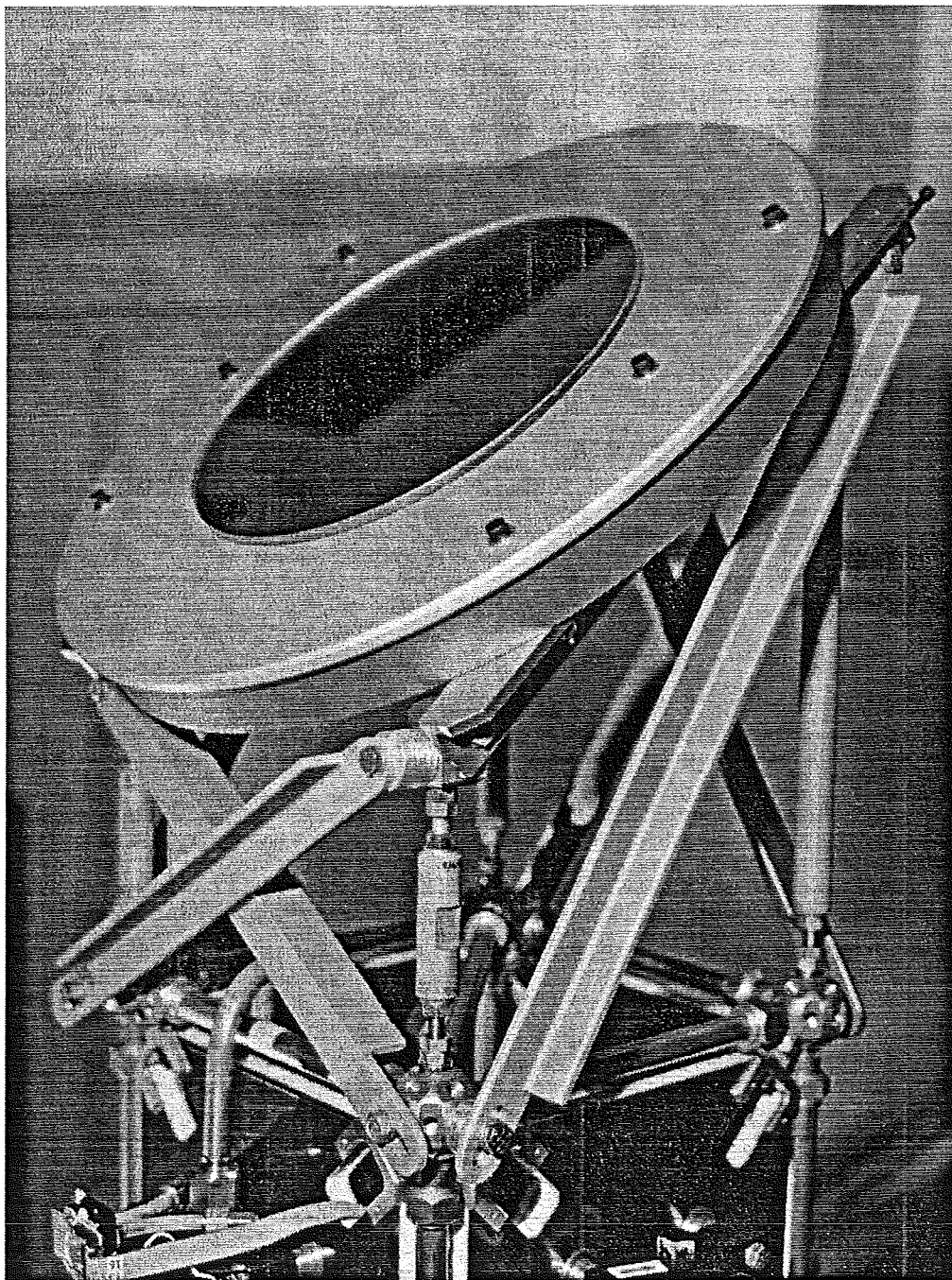


Figure 6. Phase-2 CEM reflector

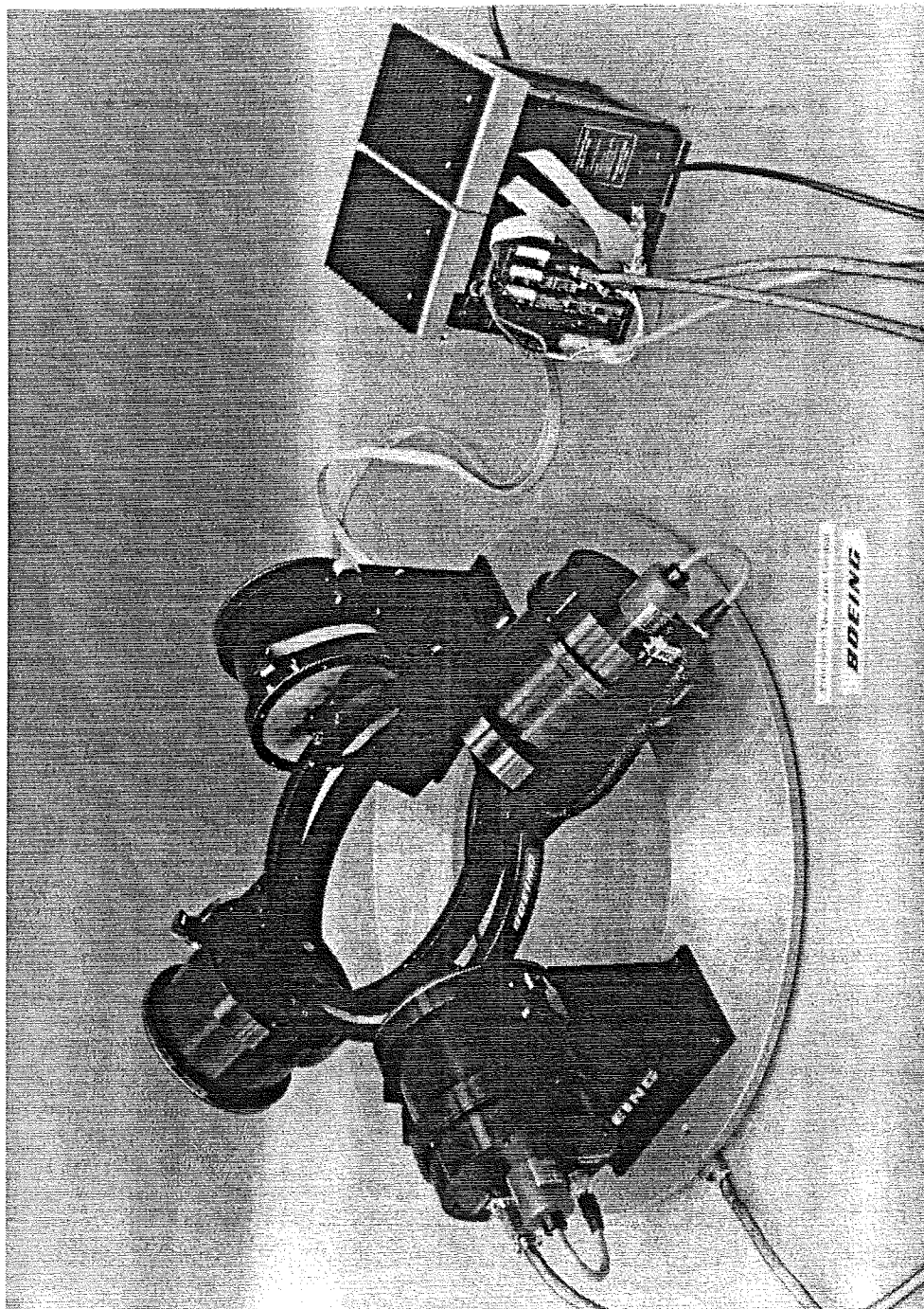


Figure 7. Gimbal system (SIS) without payload

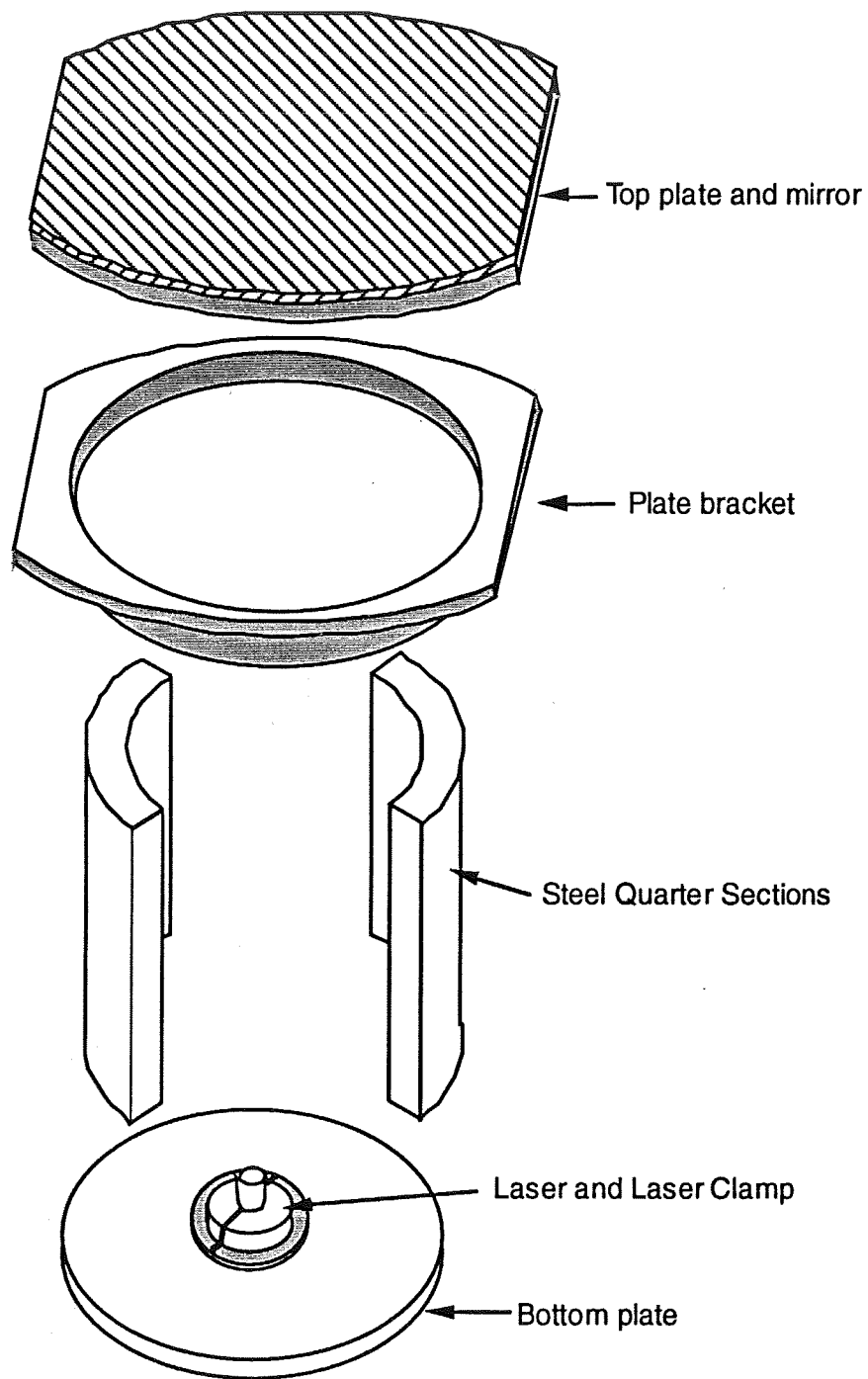


Figure 8. Payload assembly

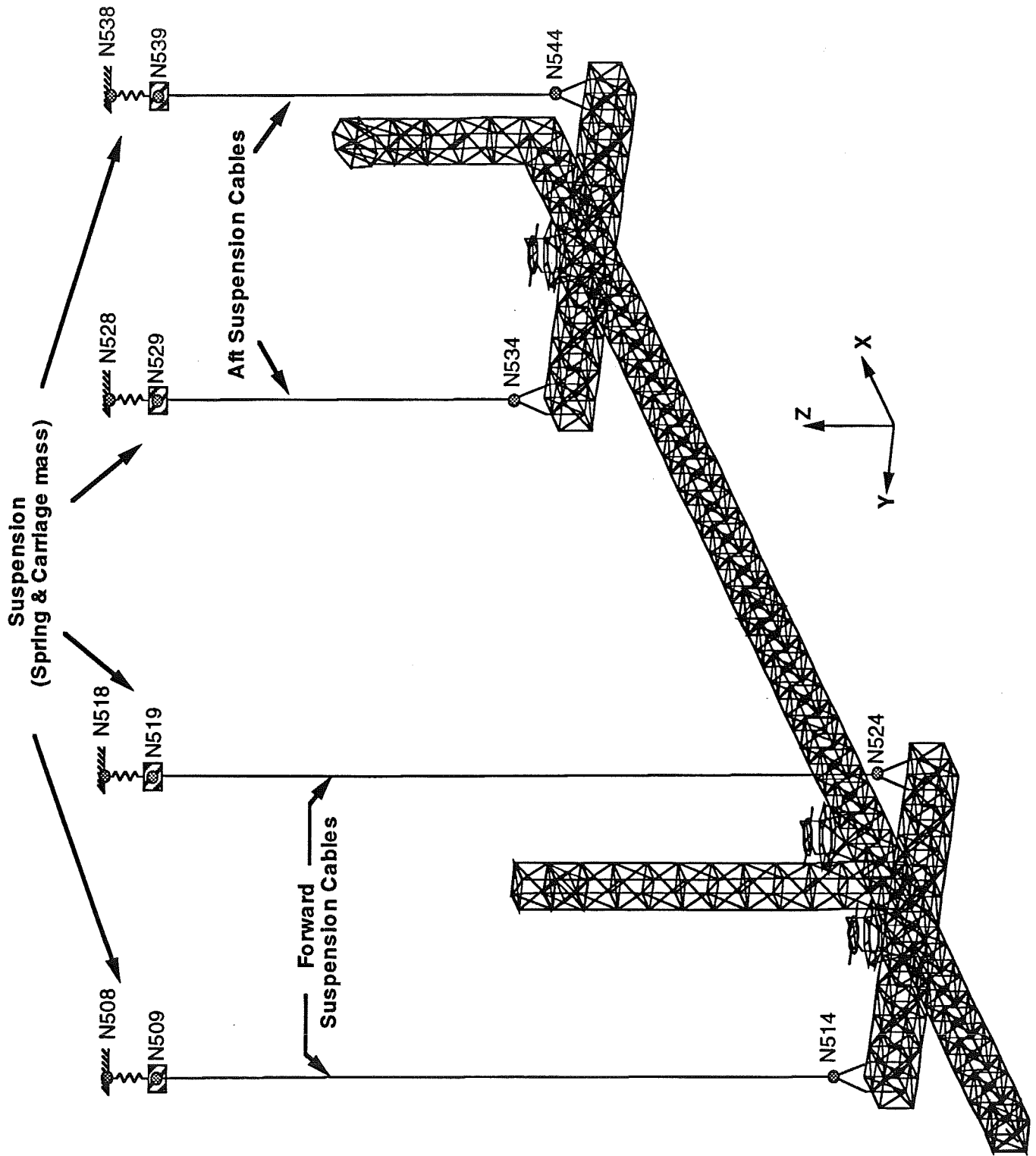


Figure 9. Schematic of CEM Phase2 suspension

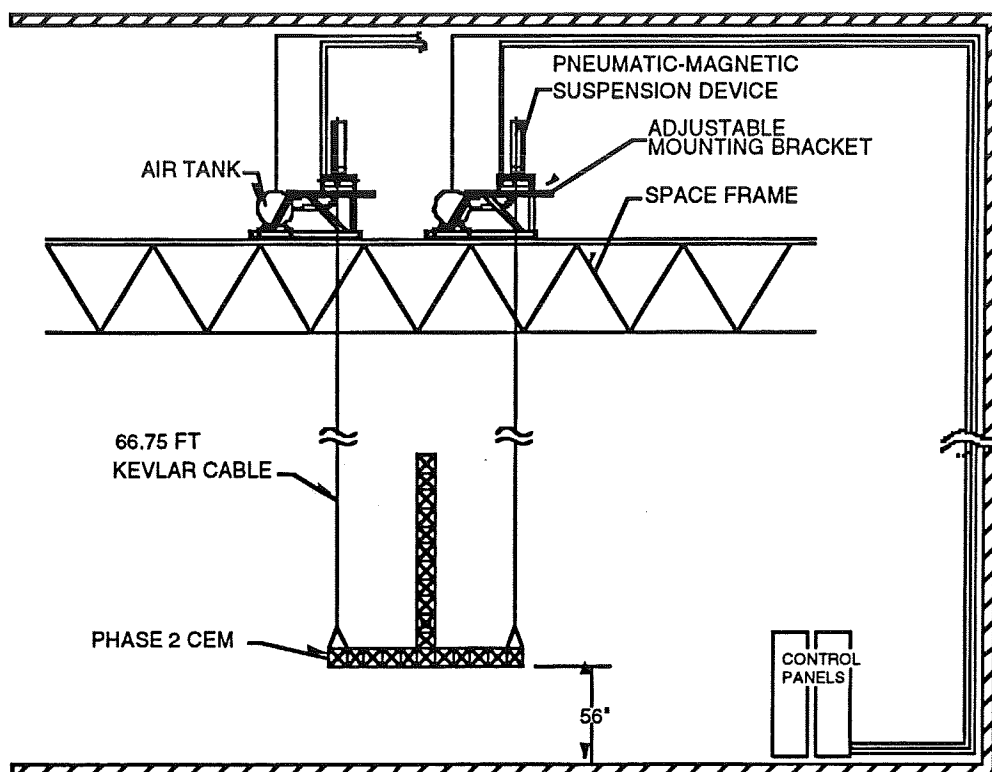


Figure 10a. Schematic of suspension system arrangement in laboratory

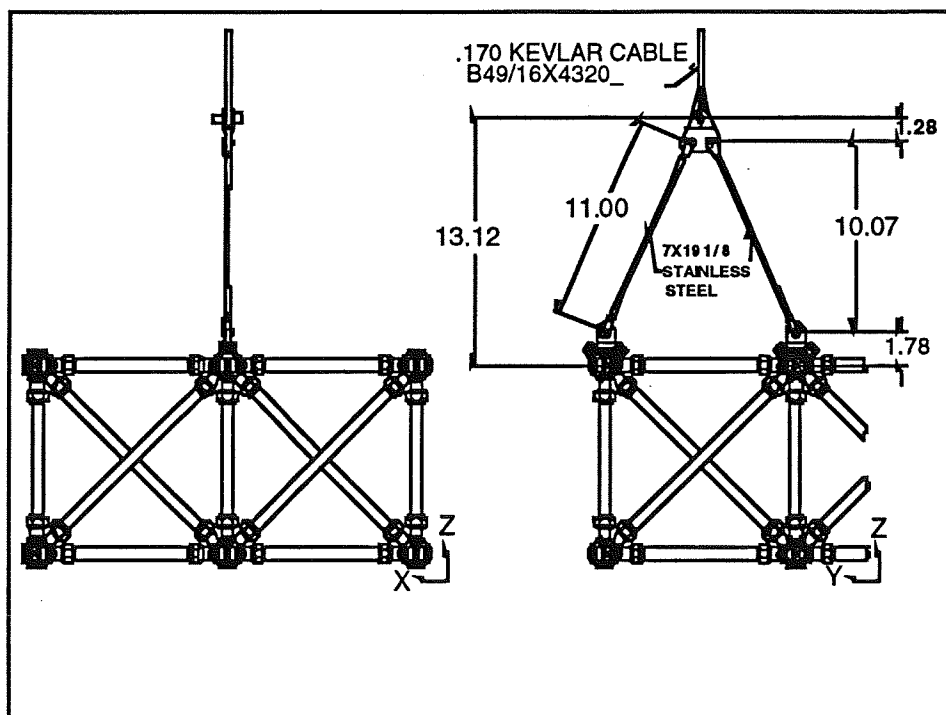


Figure 10b. Cable attachment to truss structure

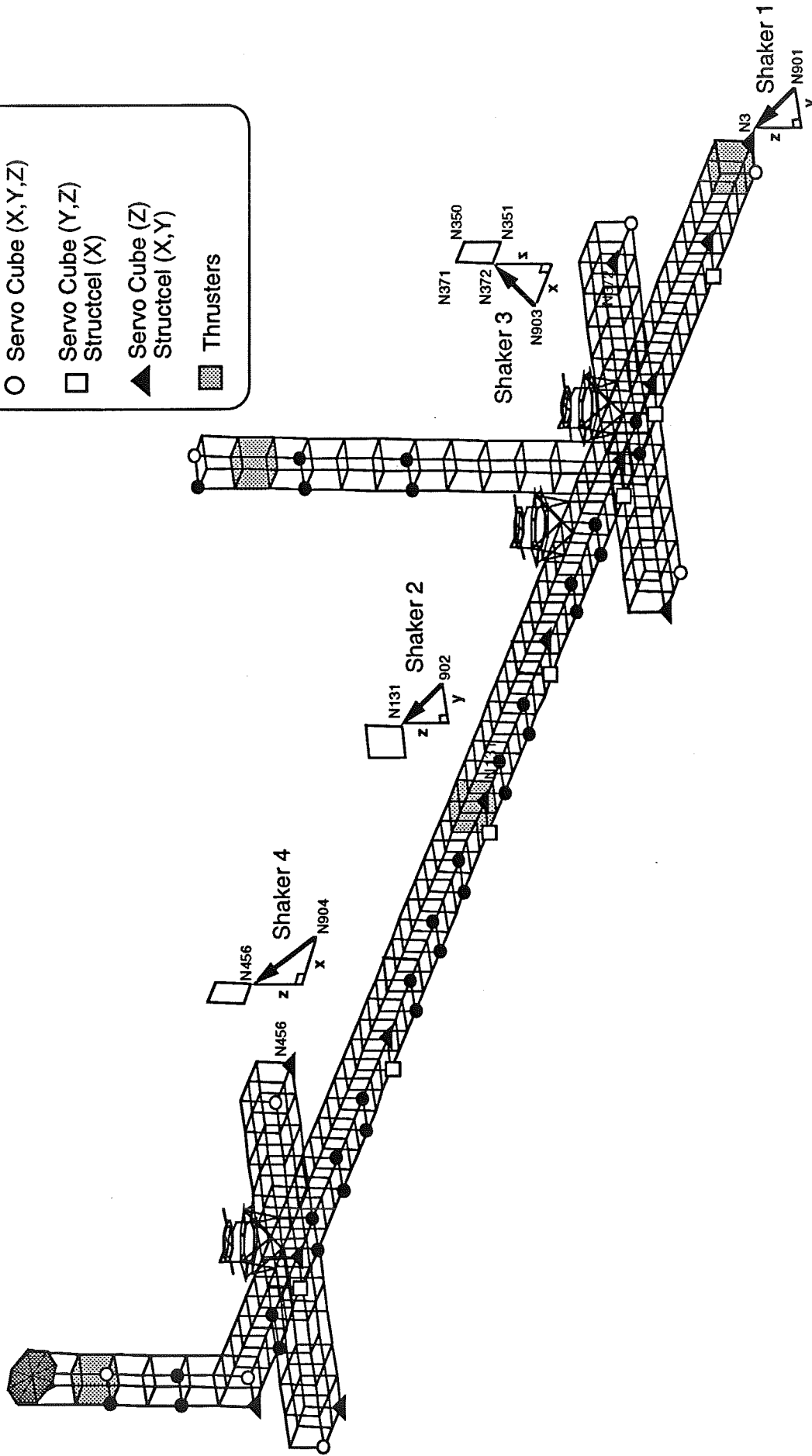
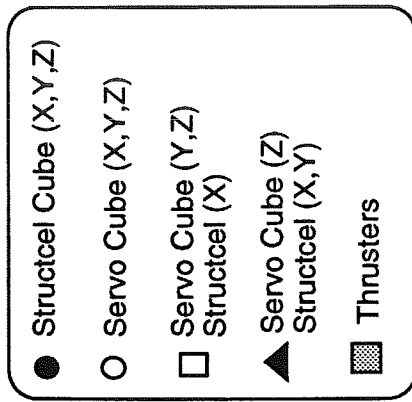


Figure 11. Phase2 CEM sensors and actuators locations

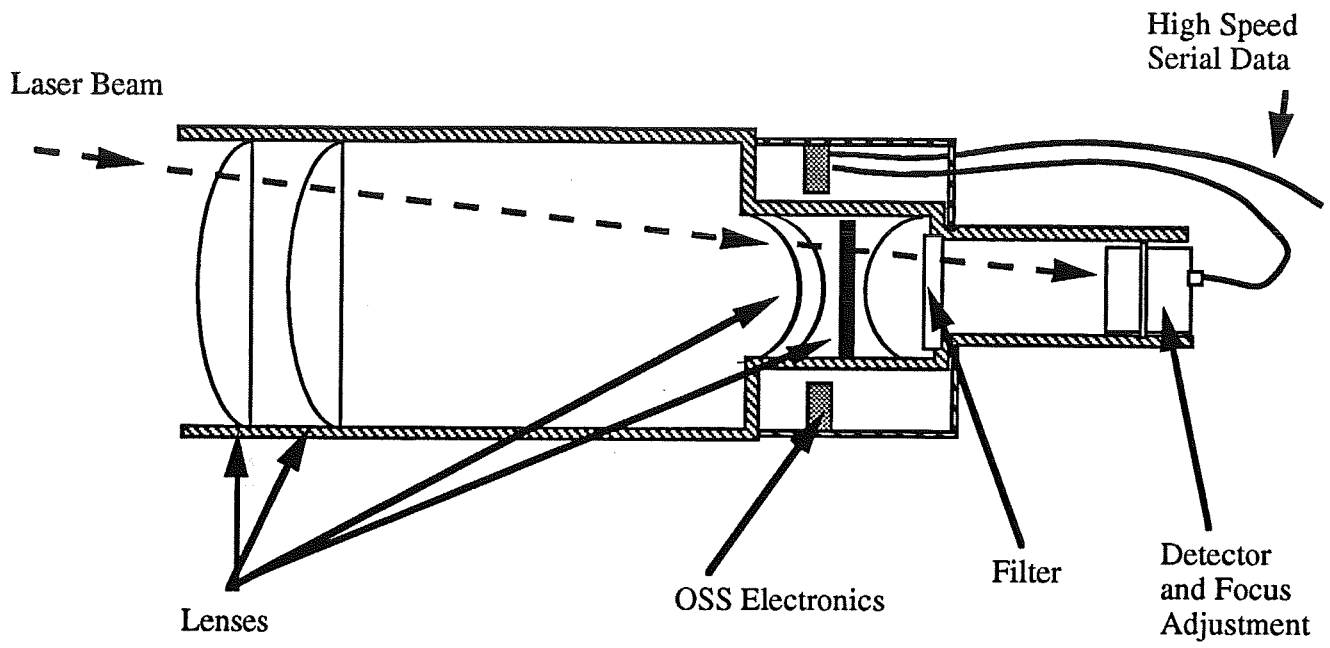


Figure 12. Optical Scoring System (OSS) diagram

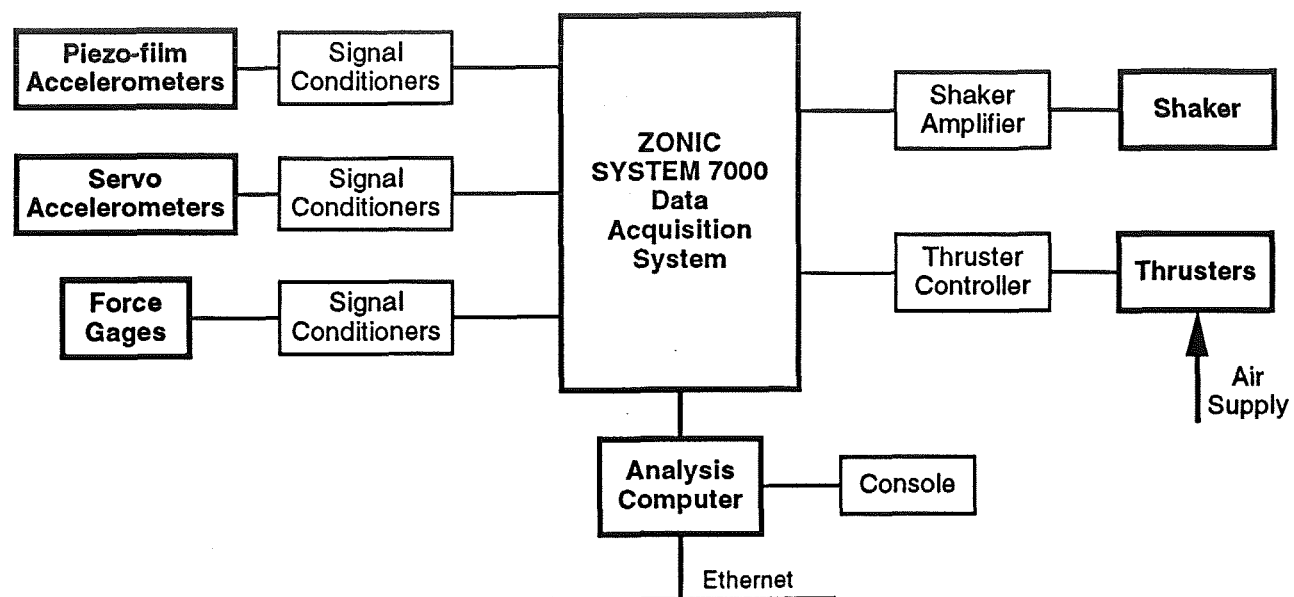


Figure 13. Data acquisition system configuration

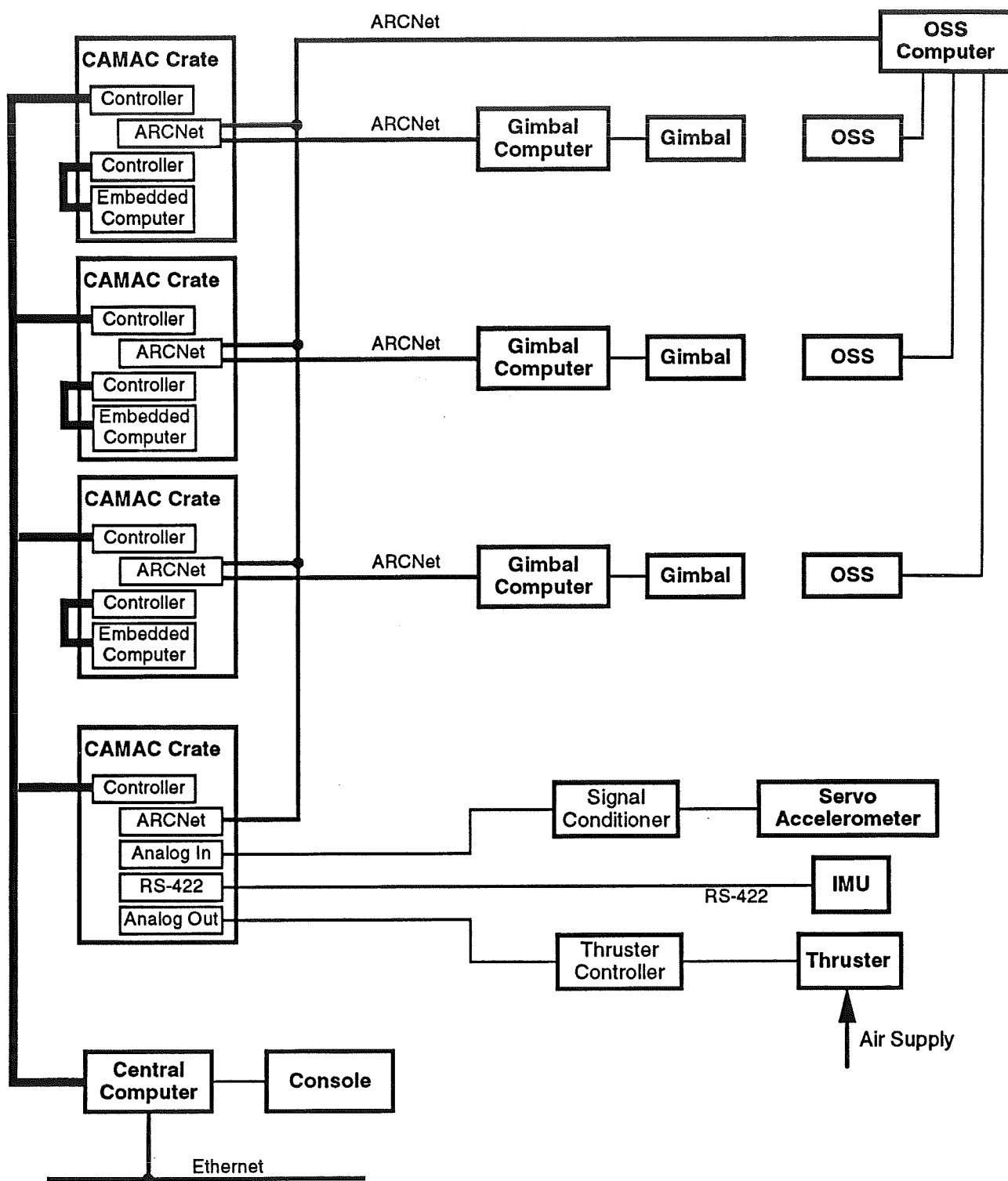


Figure 14. Control computer configuration

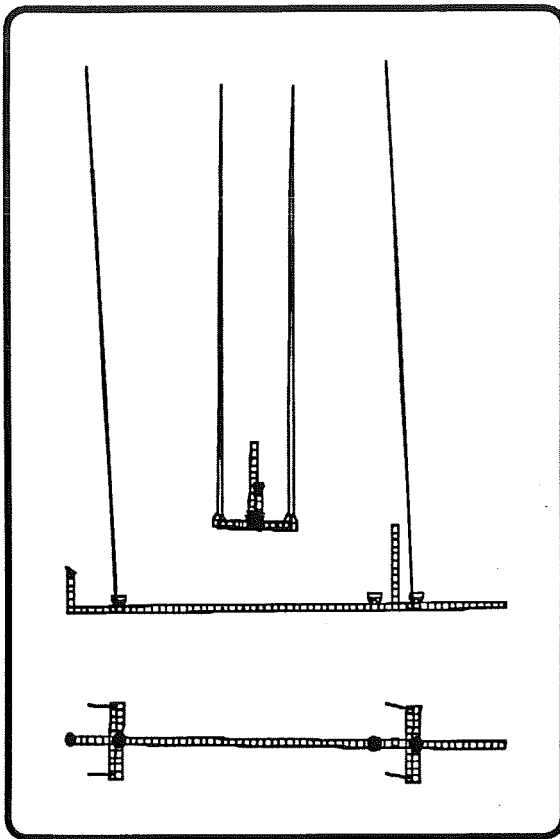


Figure 15. Mode 1, $f=0.1393$ Hz

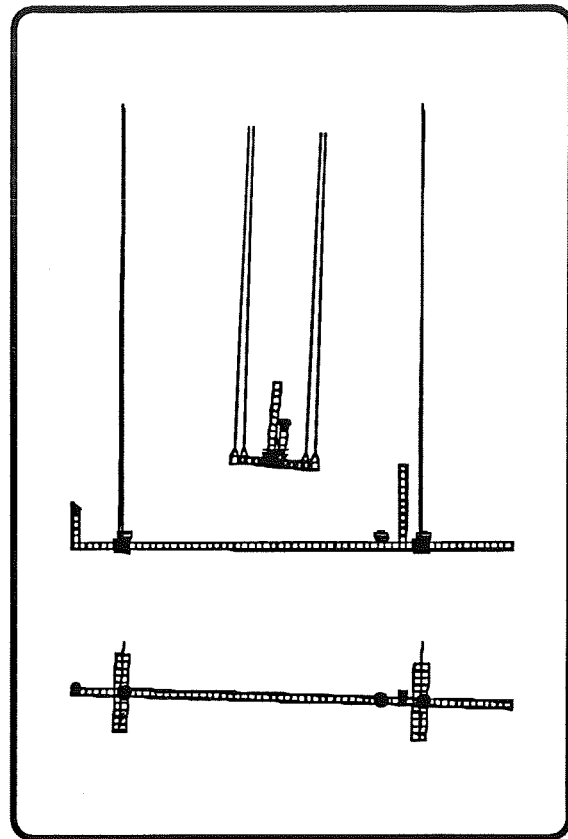


Figure 16. Mode 2, $f=0.1404$ Hz

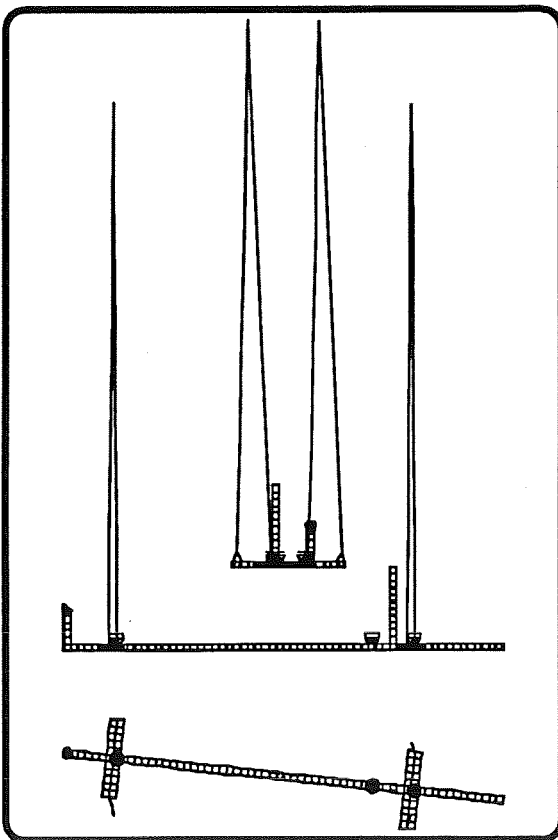


Figure 17. Mode 3, $f=0.1492$ Hz

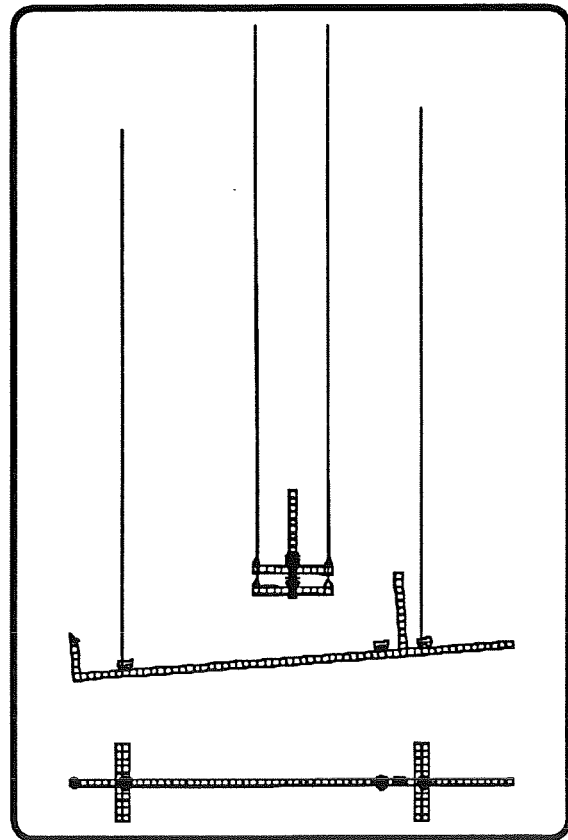


Figure 18. Mode 4, $f=0.1609$ Hz

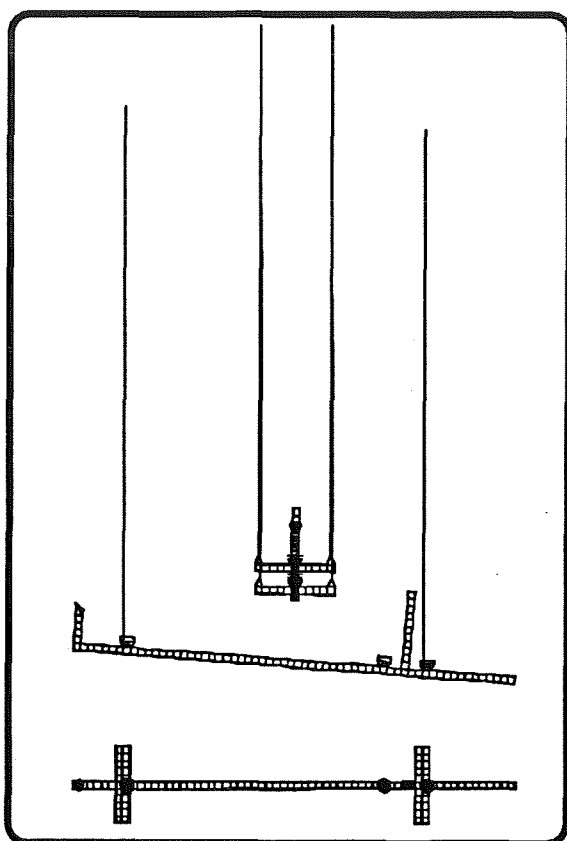


Figure 19. Mode 5, $f=0.1643$ Hz

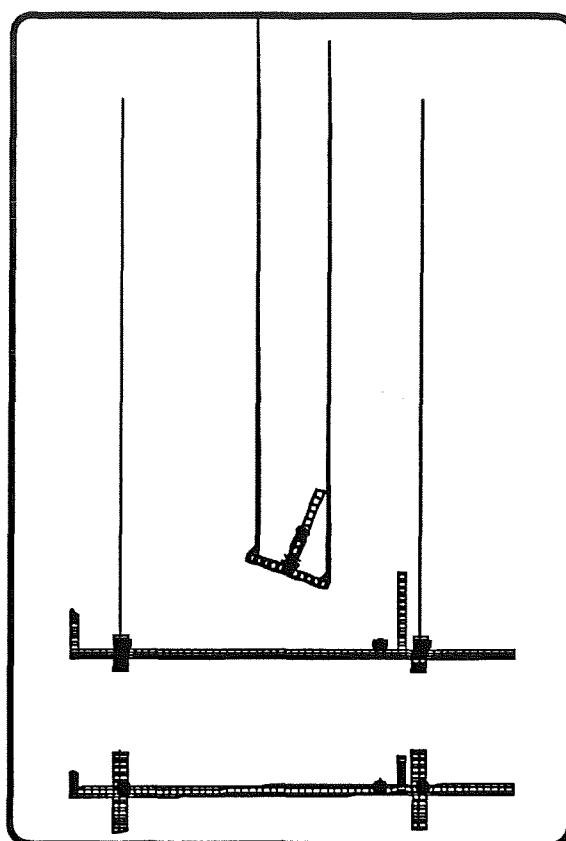


Figure 20. Mode 6, $f=0.2760$ Hz

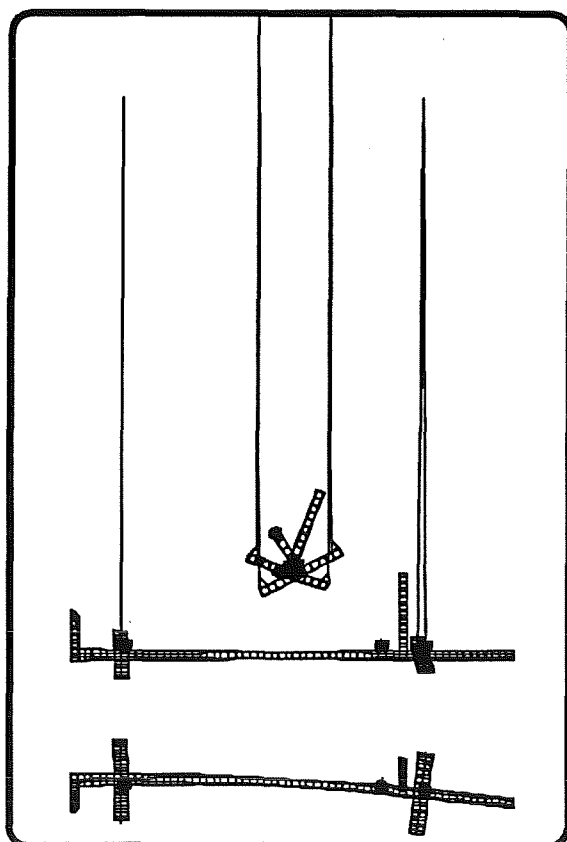


Figure 21. Mode 7, $f=1.7247$ Hz

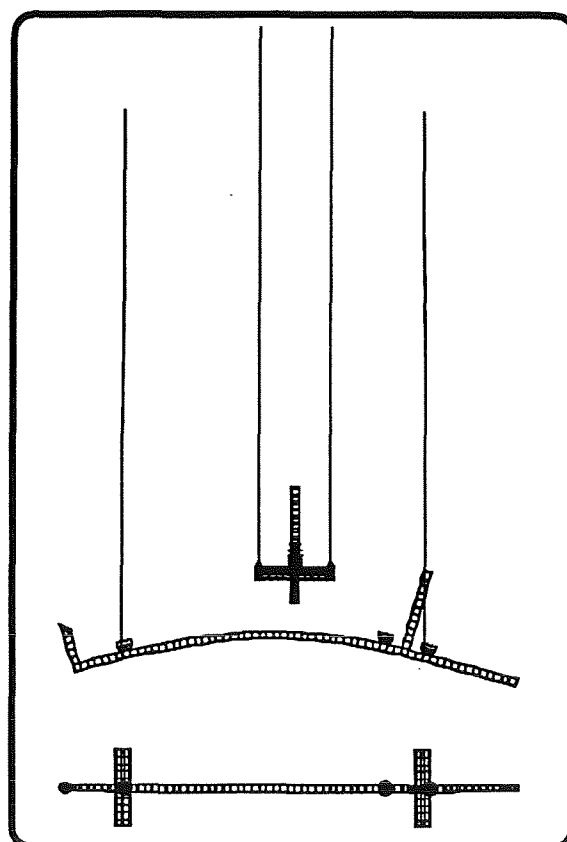
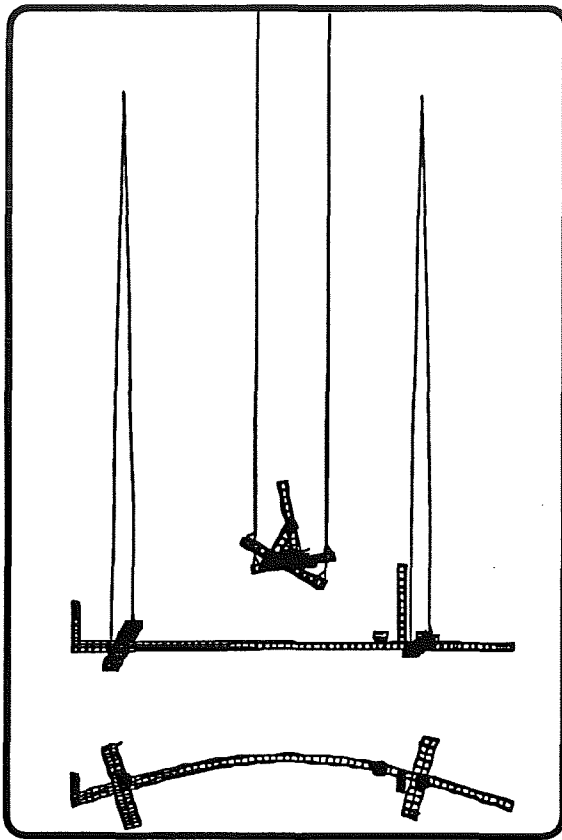
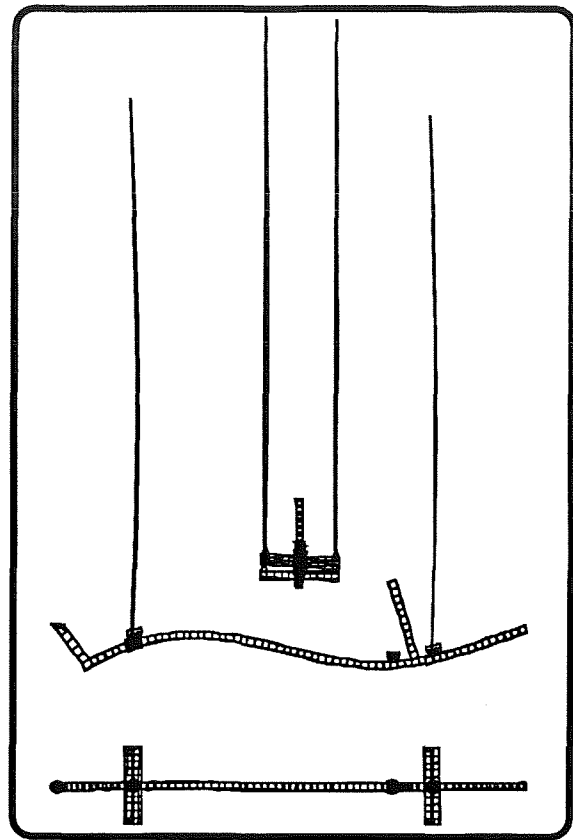
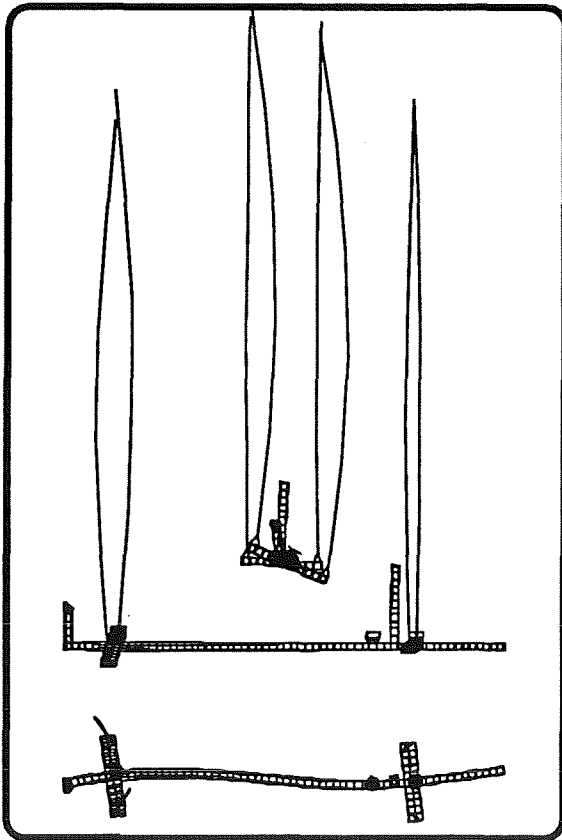
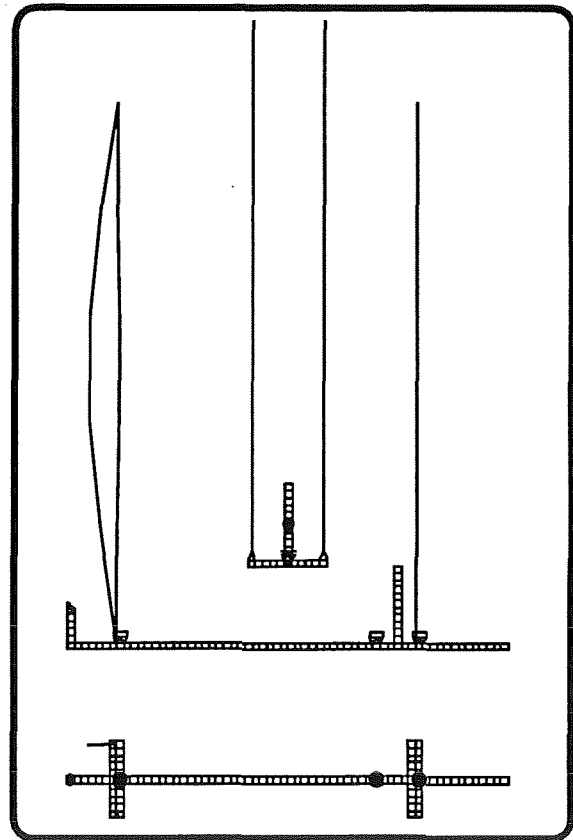


Figure 22. Mode 8, $f=2.4000$ Hz

Figure 23. Mode 9, $f=2.9673$ HzFigure 24. Mode 10, $f=5.4863$ HzFigure 25. Mode 11, $f=5.8503$ HzFigure 26. Mode 12, $f=6.4208$ Hz

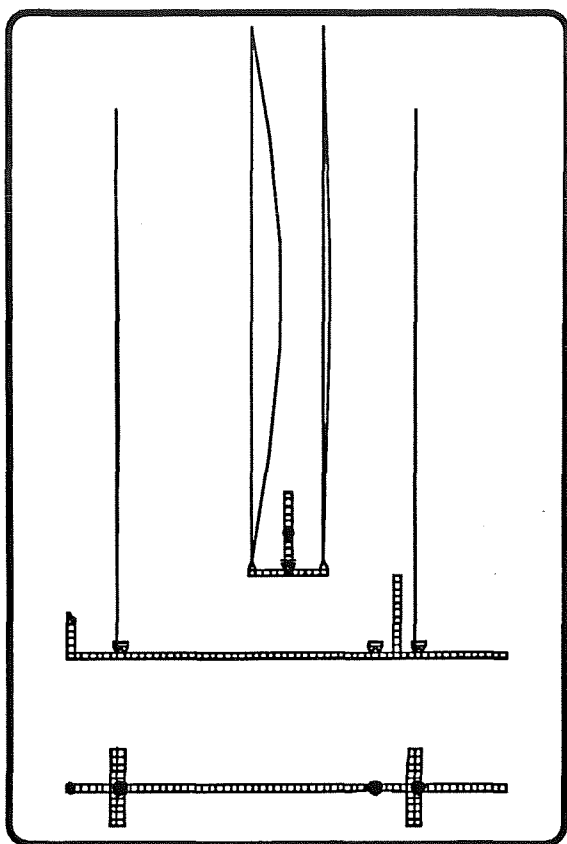


Figure 27. Mode 15, $f=6.5335$ Hz

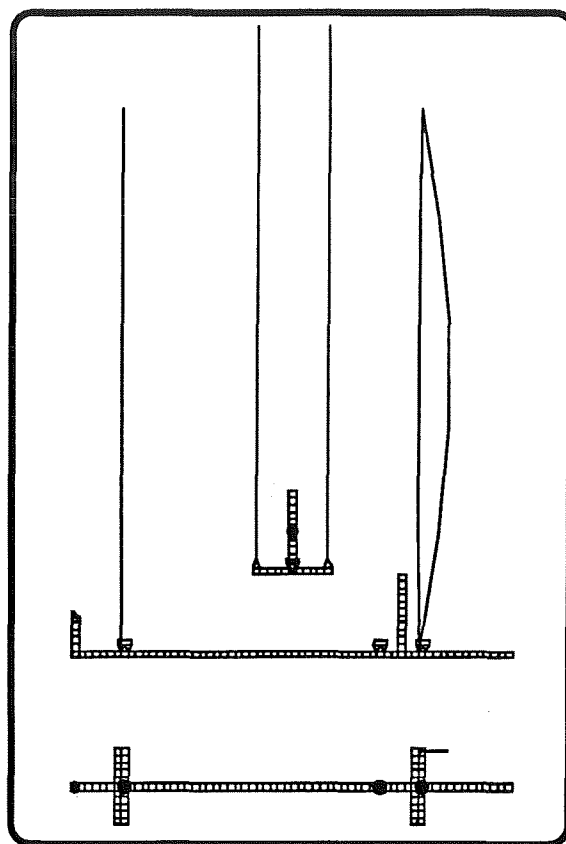


Figure 28. Mode 16, $f=6.9233$ Hz

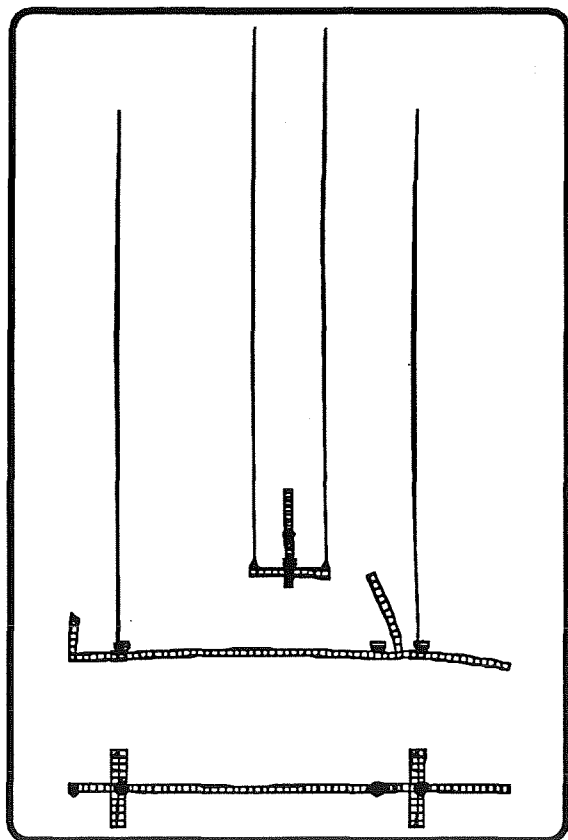


Figure 29. Mode 20, $f=7.6844$ Hz

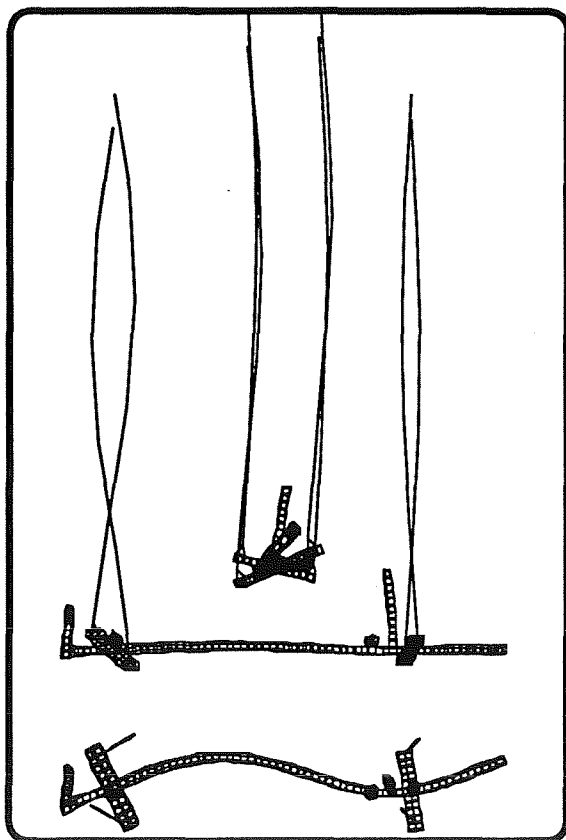


Figure 30. Mode 21, $f=8.4046$ Hz

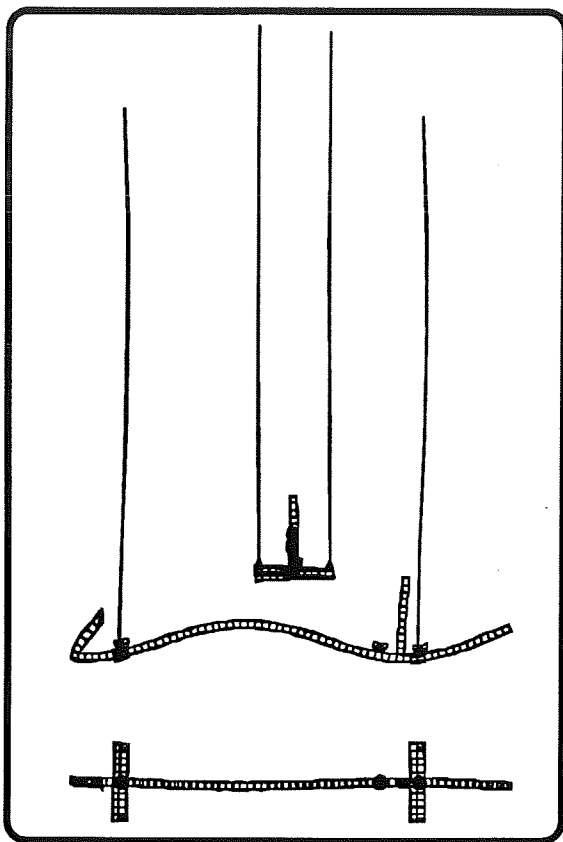


Figure 31. Mode 22, $f=9.0020$ Hz

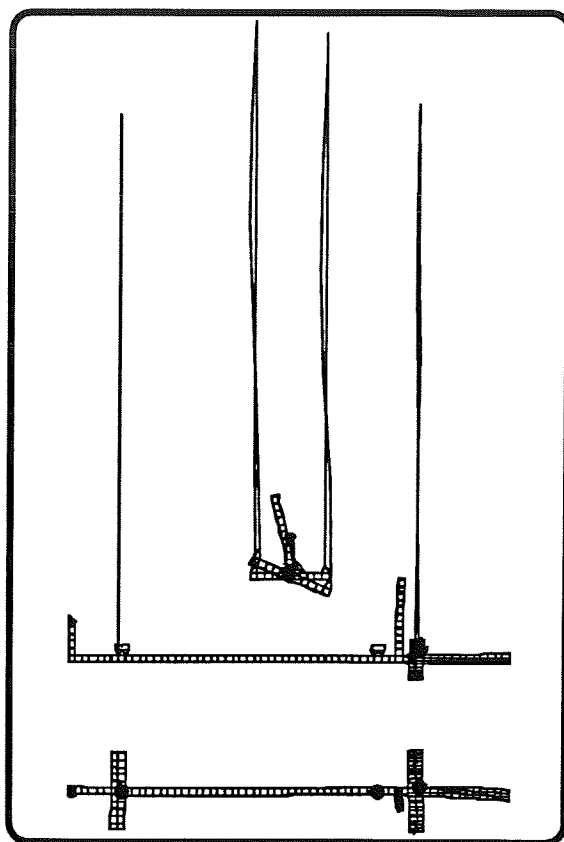


Figure 32. Mode 23, $f=10.0418$ Hz

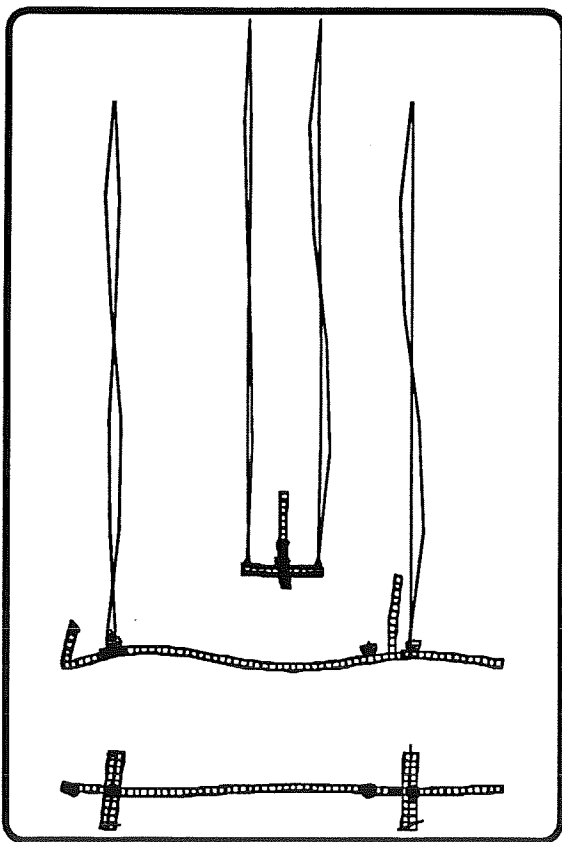


Figure 33. Mode 33, $f=13.5509$ Hz

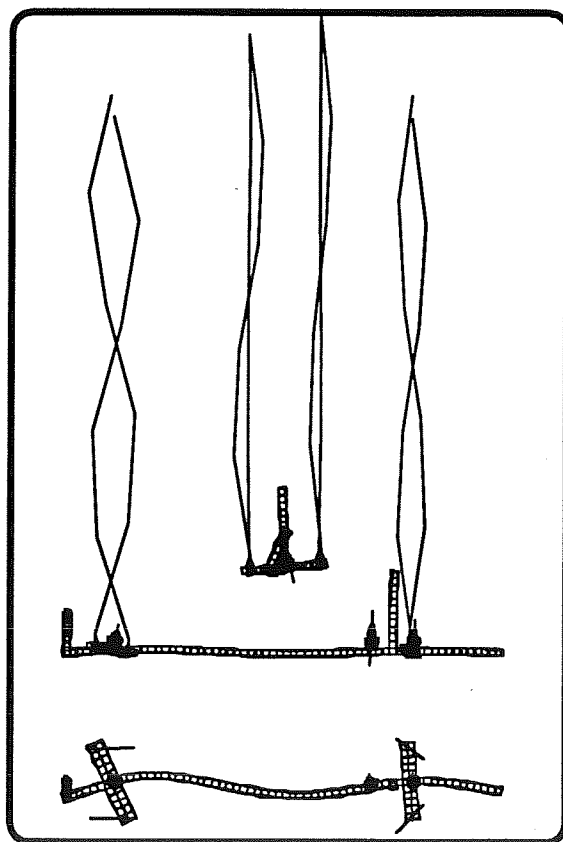


Figure 34. Mode 34, $f=13.6346$ Hz

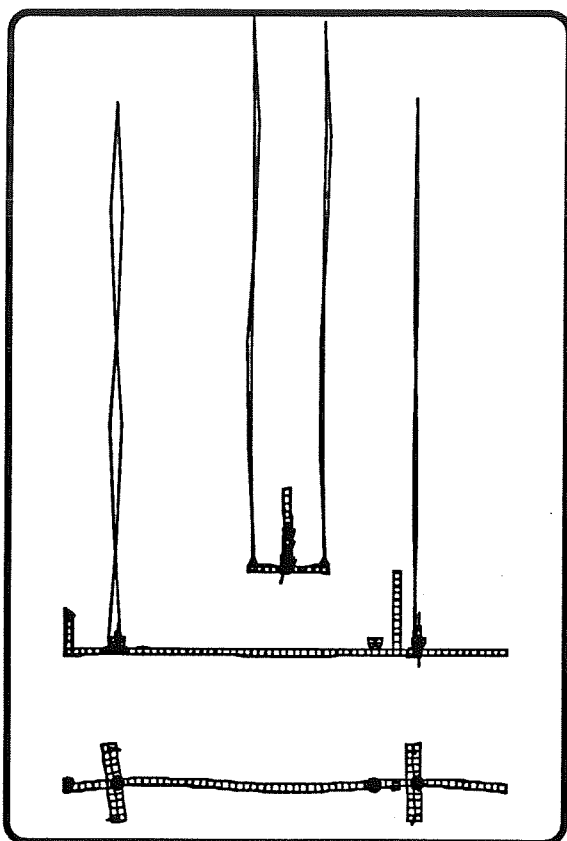


Figure 35. Mode 36, $f=14.2675$ Hz

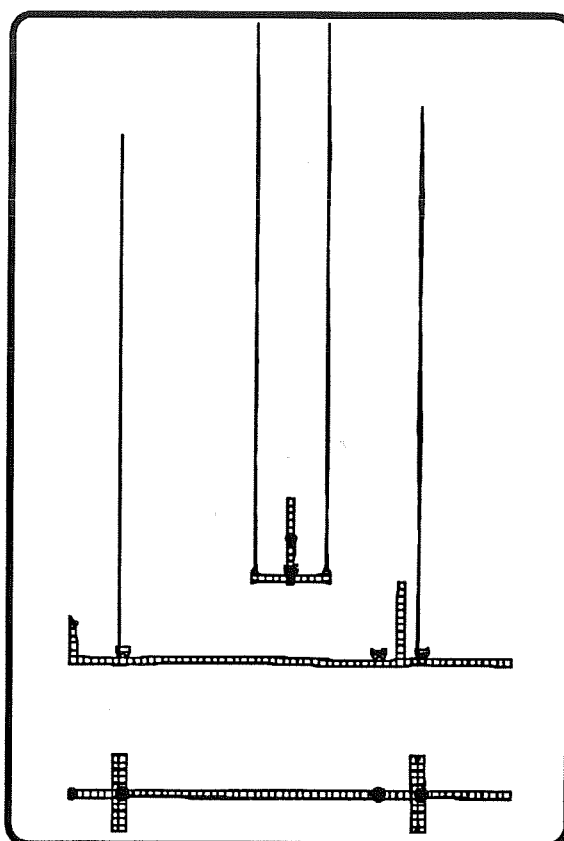


Figure 36. Mode 37, $f=15.0536$ Hz

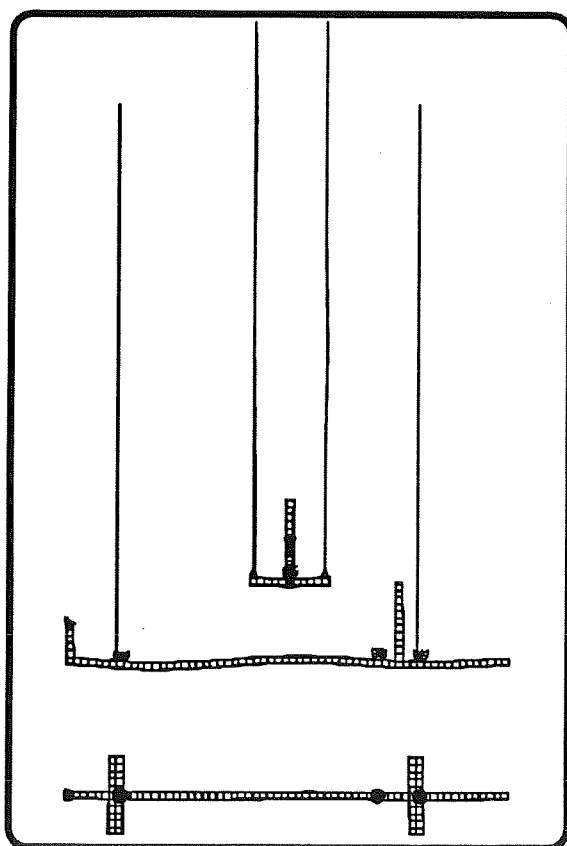


Figure 37. Mode 38, $f=15.6685$ Hz

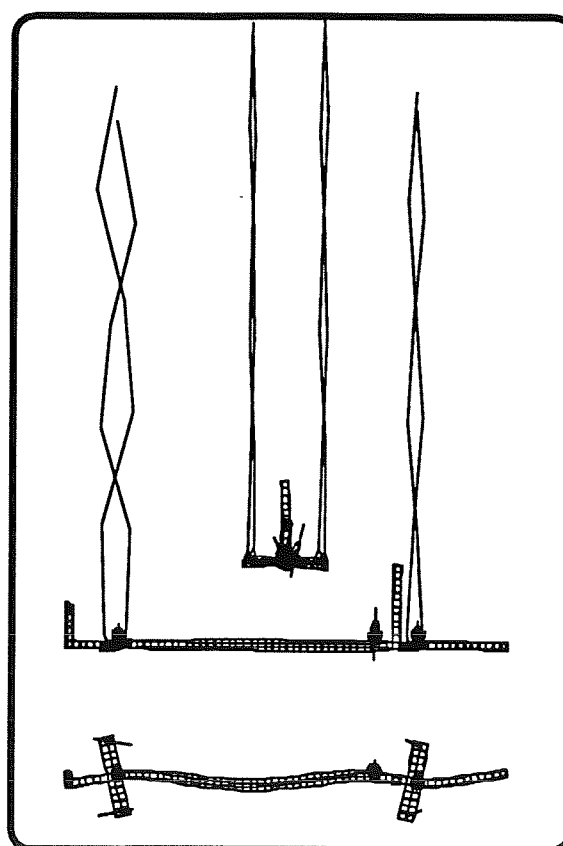


Figure 38. Mode 39, $f=16.3021$ Hz

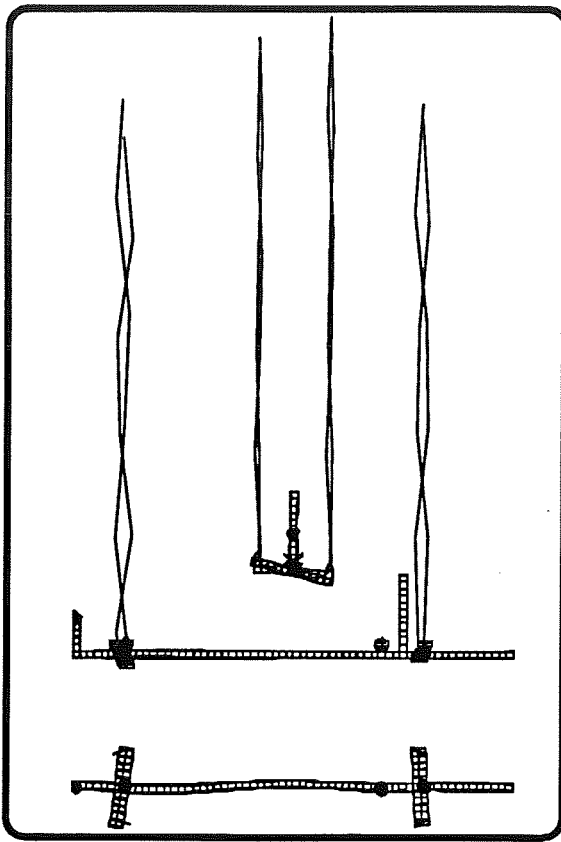


Figure 39. Mode 44, $f=17.8175$ Hz

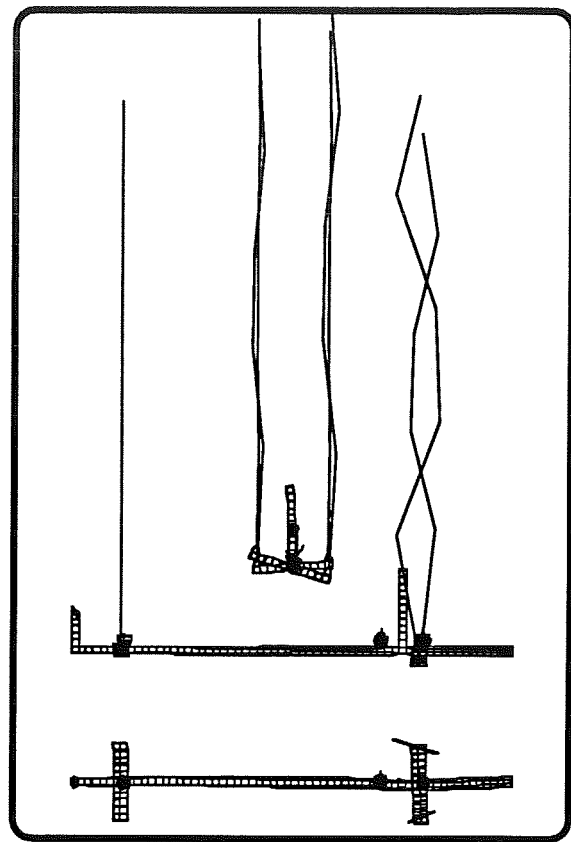


Figure 40. Mode 45, $f=18.1644$ Hz

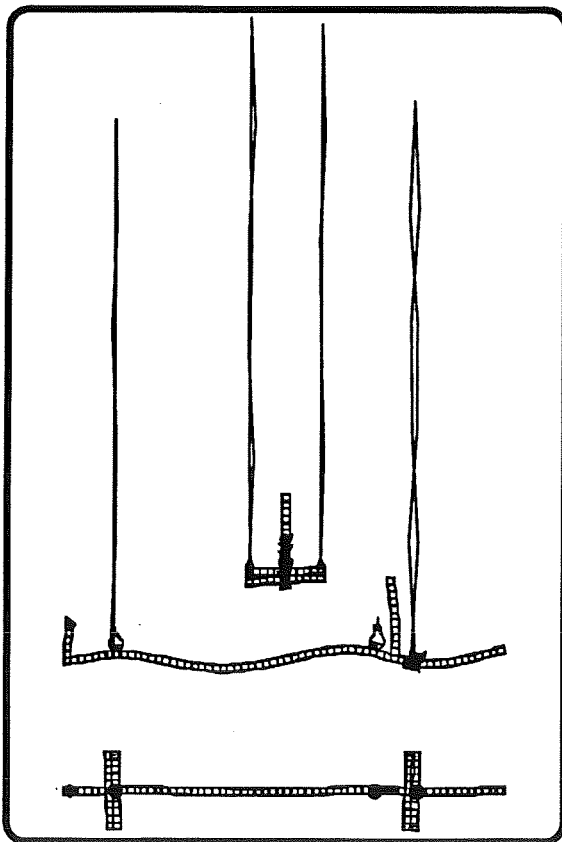


Figure 41. Mode 50, $f=18.7388$ Hz

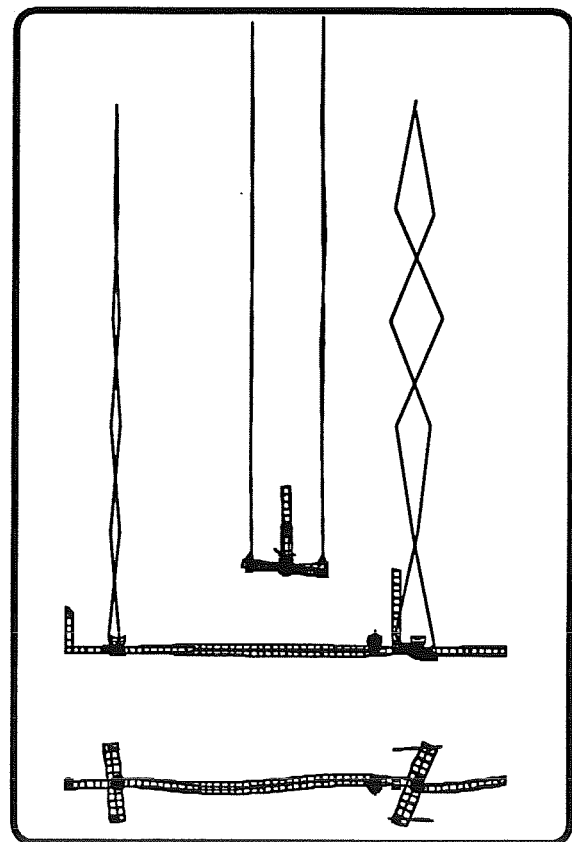


Figure 42. Mode 55, $f=20.9209$ Hz

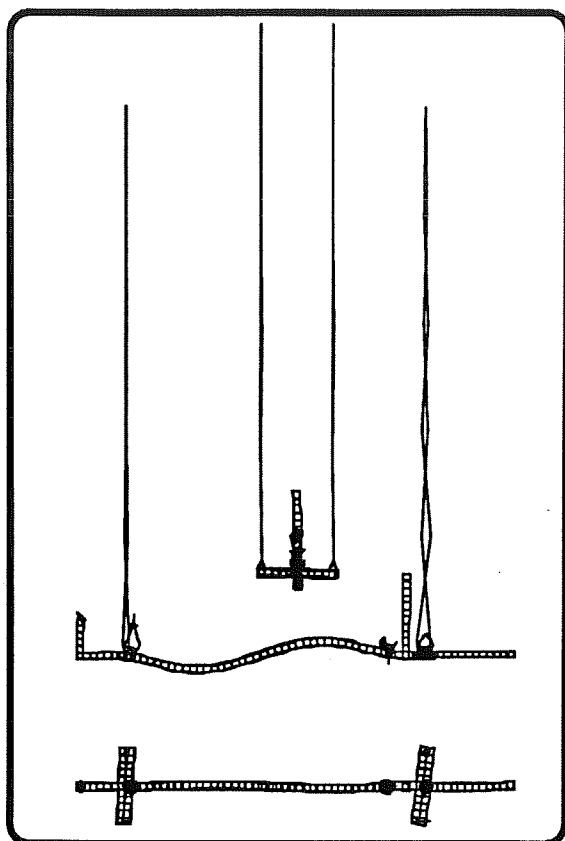


Figure 43. Mode 60, $f=23.185$ Hz

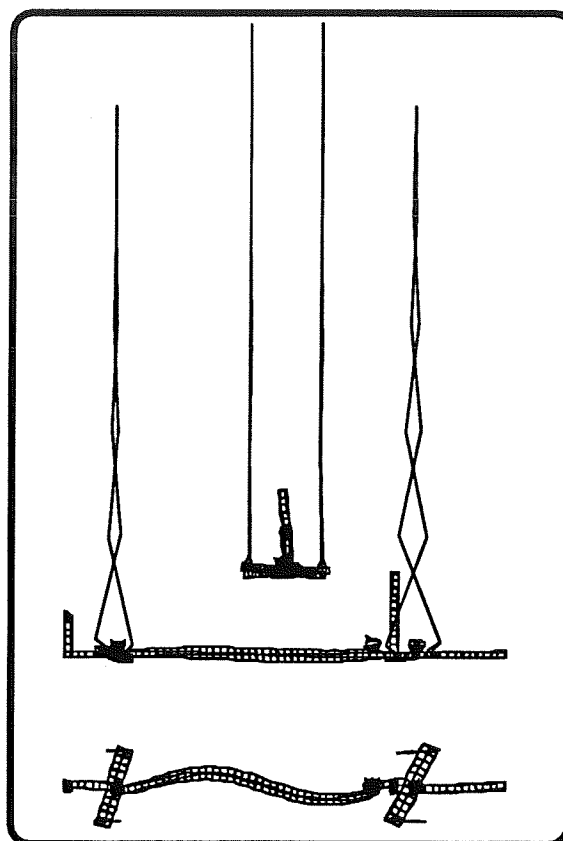


Figure 44. Mode 61, $f=23.9101$ Hz

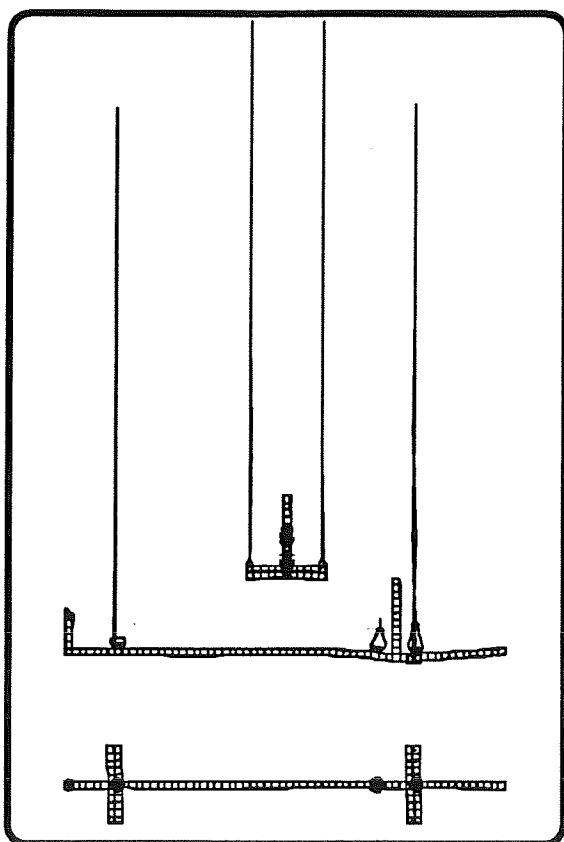


Figure 45. Mode 62, $f=24.8246$ Hz

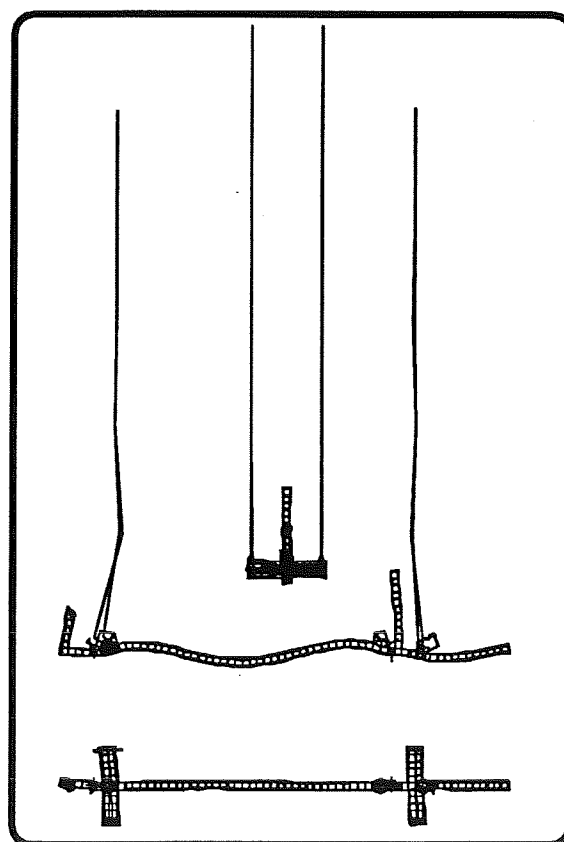


Figure 46. Mode 63, $f=25.7520$ Hz

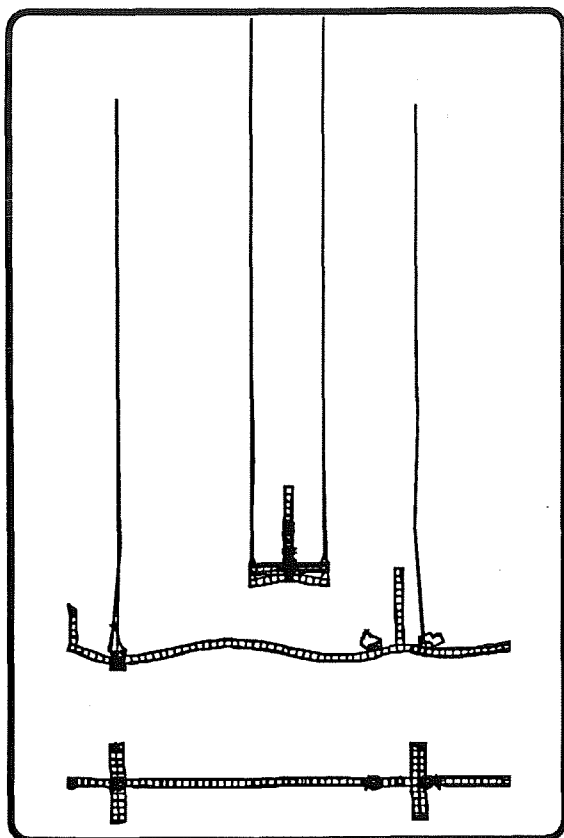


Figure 47. Mode 64, $f=27.5750$ Hz

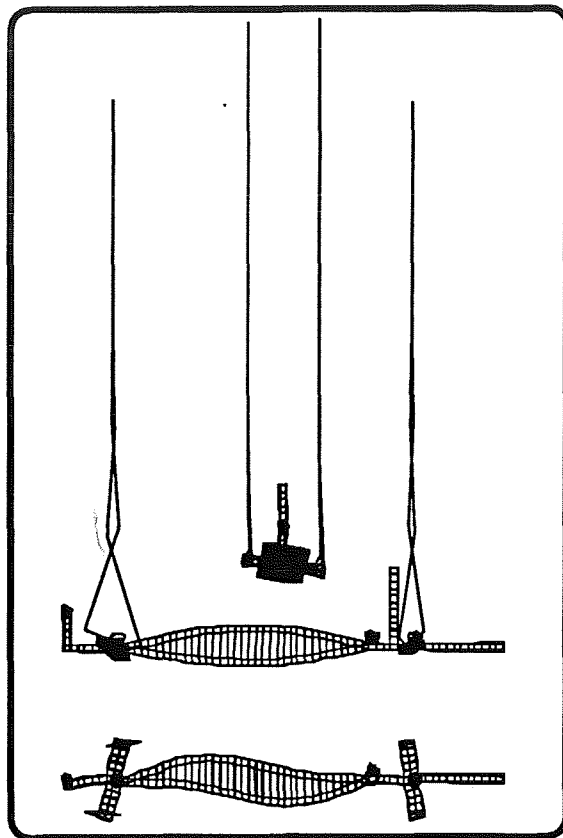


Figure 48. Mode 65, $f=28.4333$ Hz

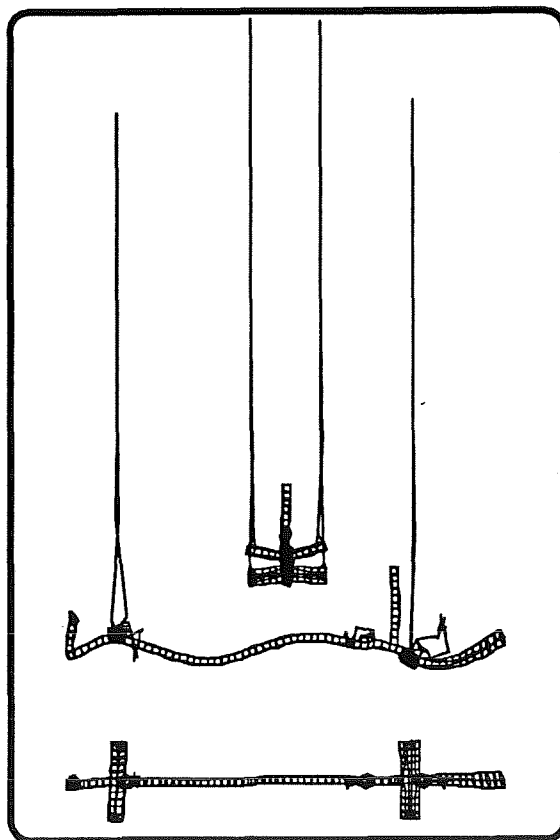


Figure 49. Mode 66, $f=28.9849$ Hz

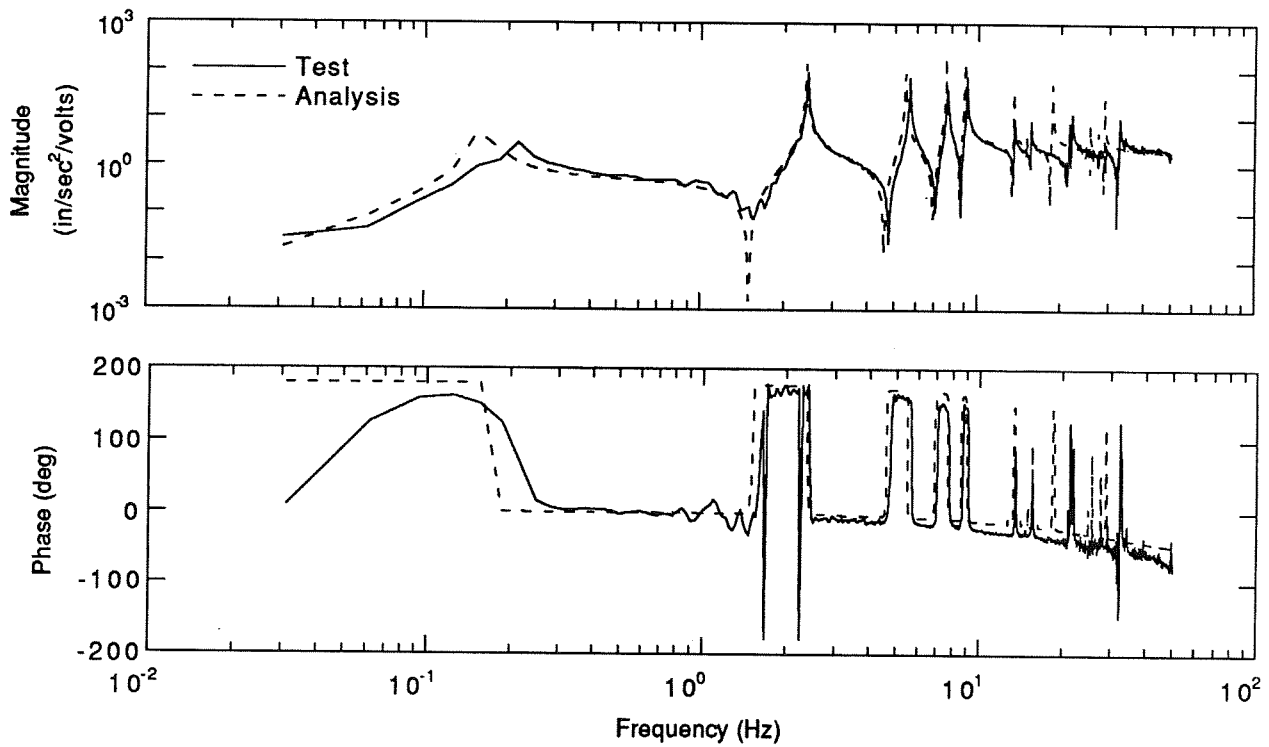
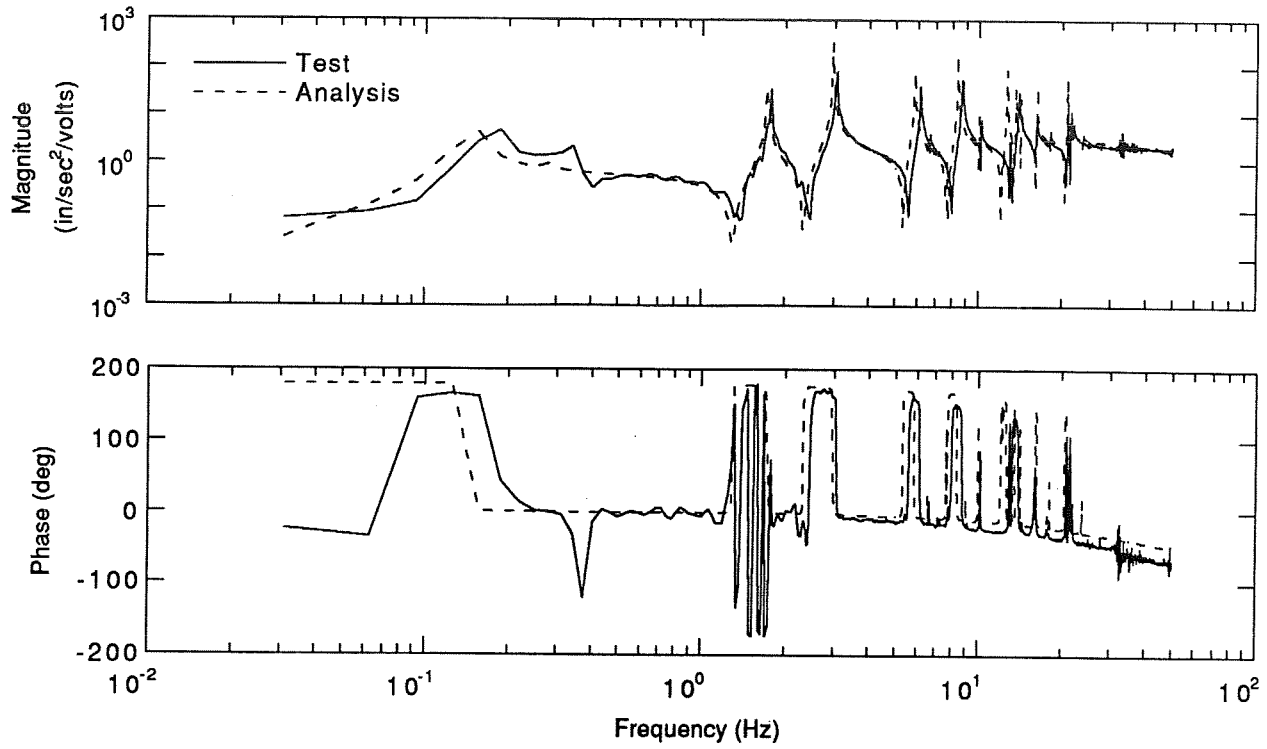
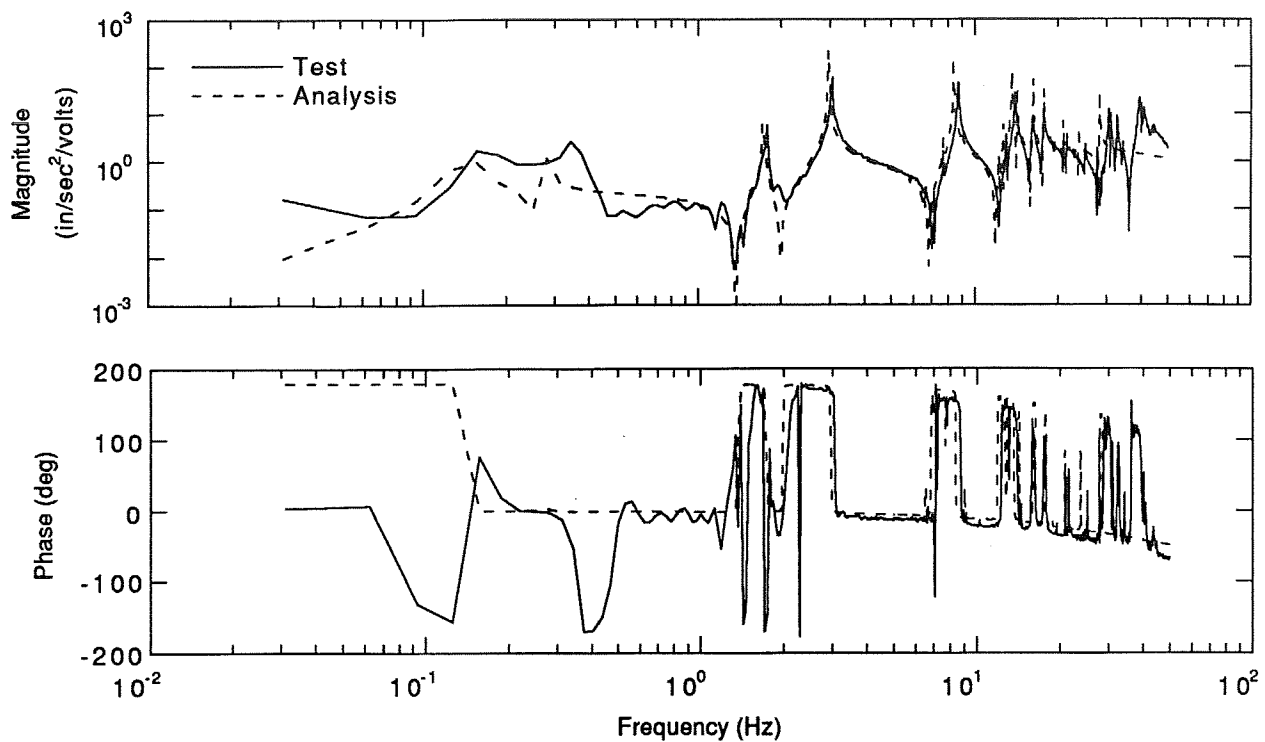
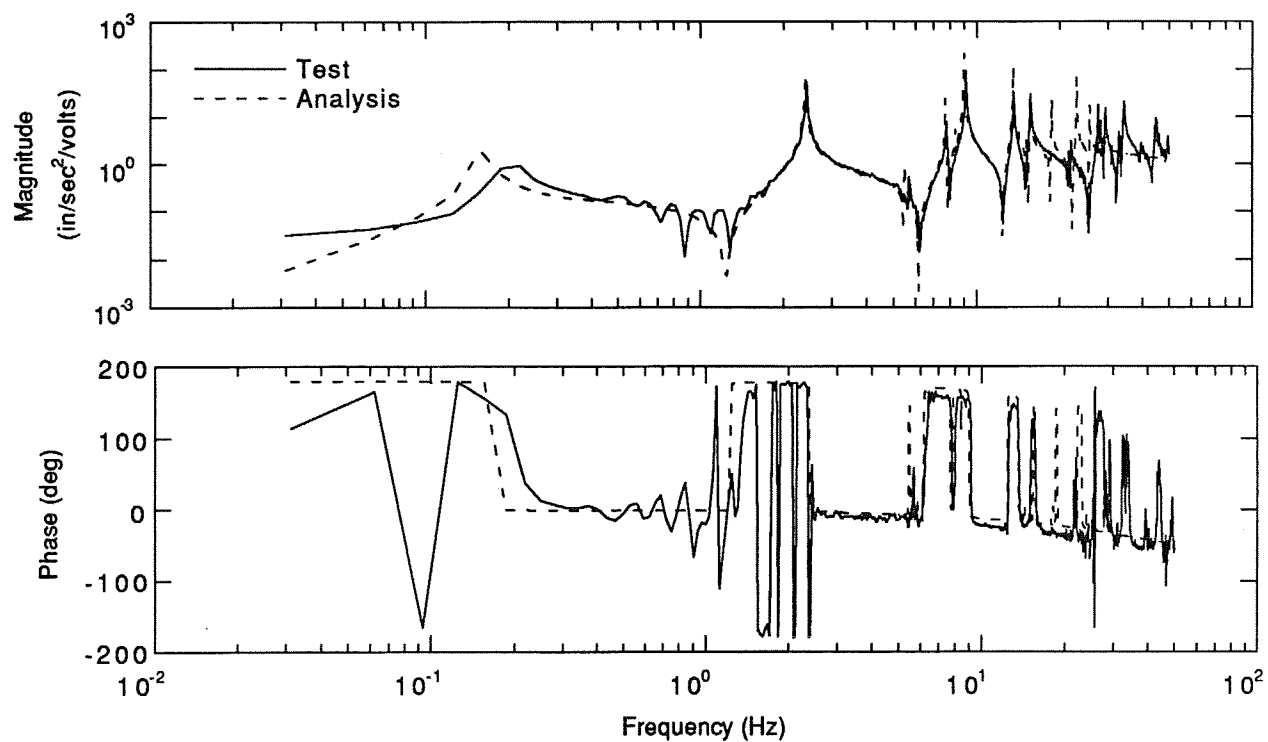


Figure 50. Transfer function for Accelerometer 1 / Thruster 1 and Accelerometer 2 / Thruster 2

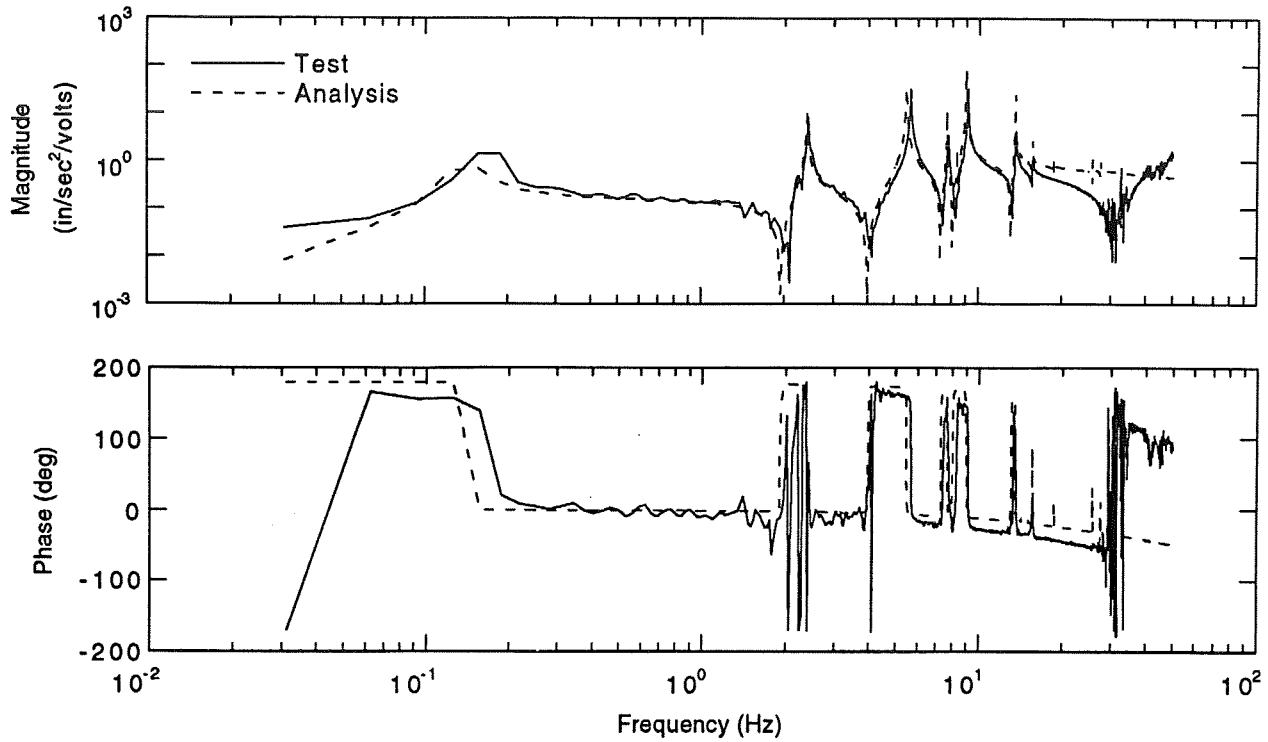


a) Accelerometer 3 / Thruster 3

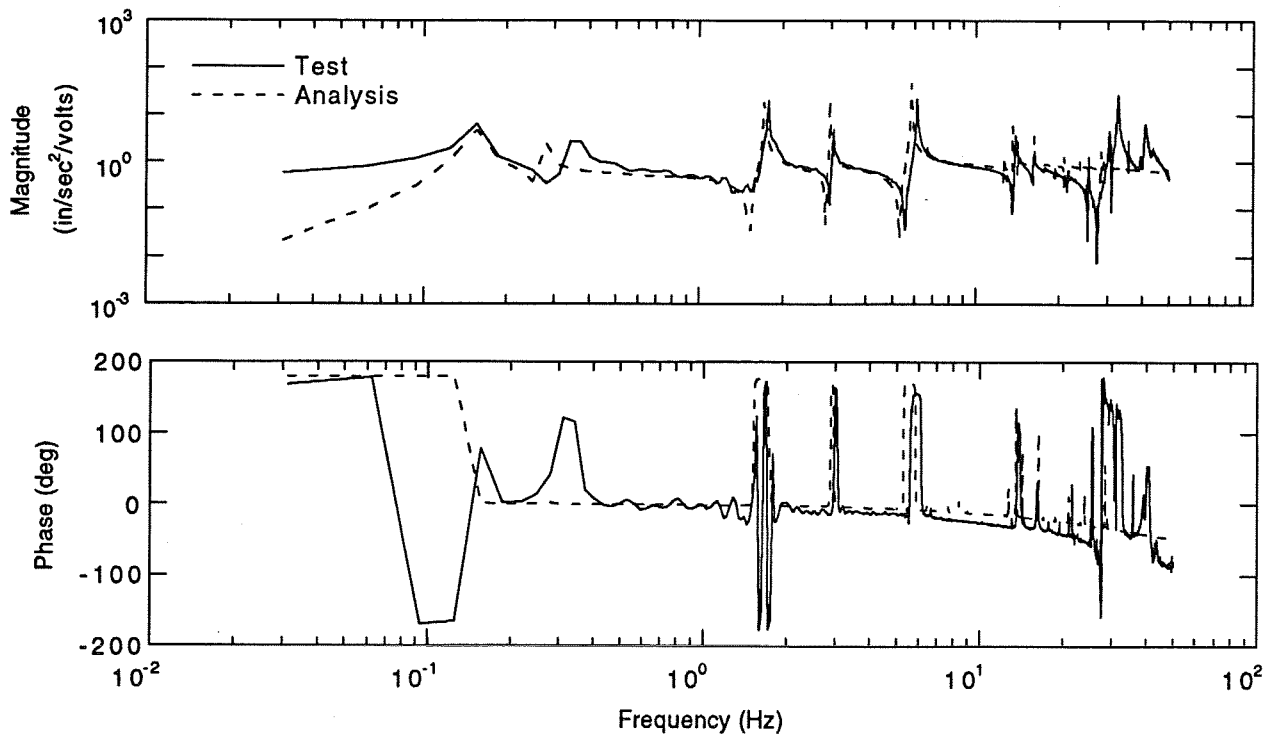


b) Accelerometer 4 / Thruster 4

Figure 51. Transfer function for Accelerometer 3 / Thruster 3 and Accelerometer 4 / Thruster 4

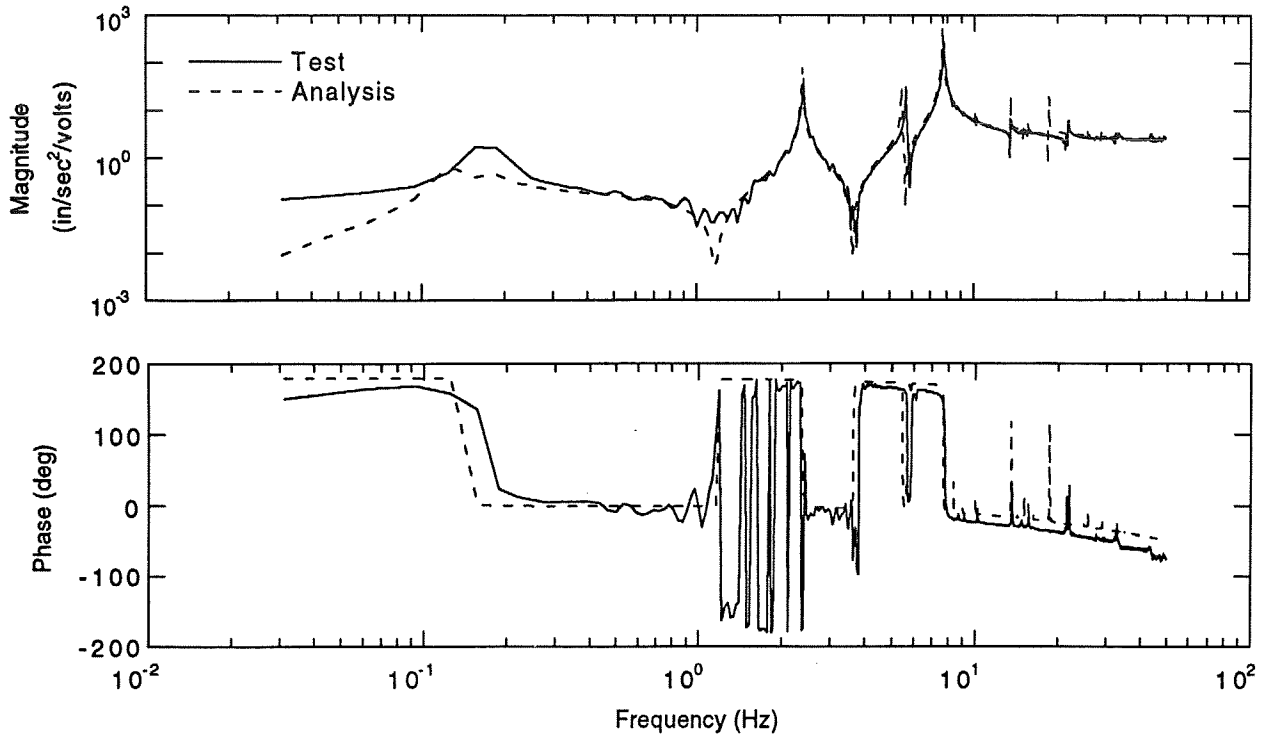


a) Accelerometer 5 / Thruster 5

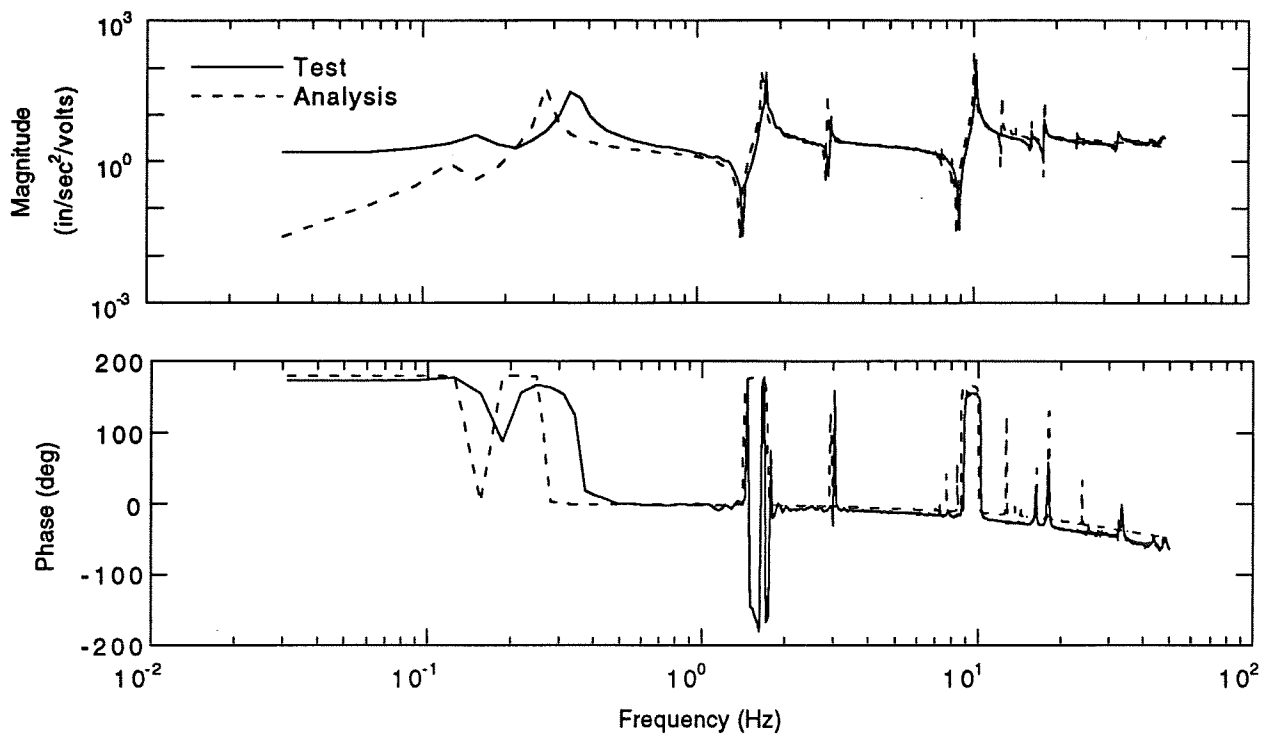


b) Accelerometer 6 / Thruster 6

Figure 52. Transfer function for Accelerometer 5 / Thruster 5 and Accelerometer 6 / Thruster 6



a) Accelerometer 7 / Thruster 7



b) Accelerometer 8 / Thruster 8

Figure 53. Transfer function for Accelerometer 7 / Thruster 7 and Accelerometer 8 / Thruster 8

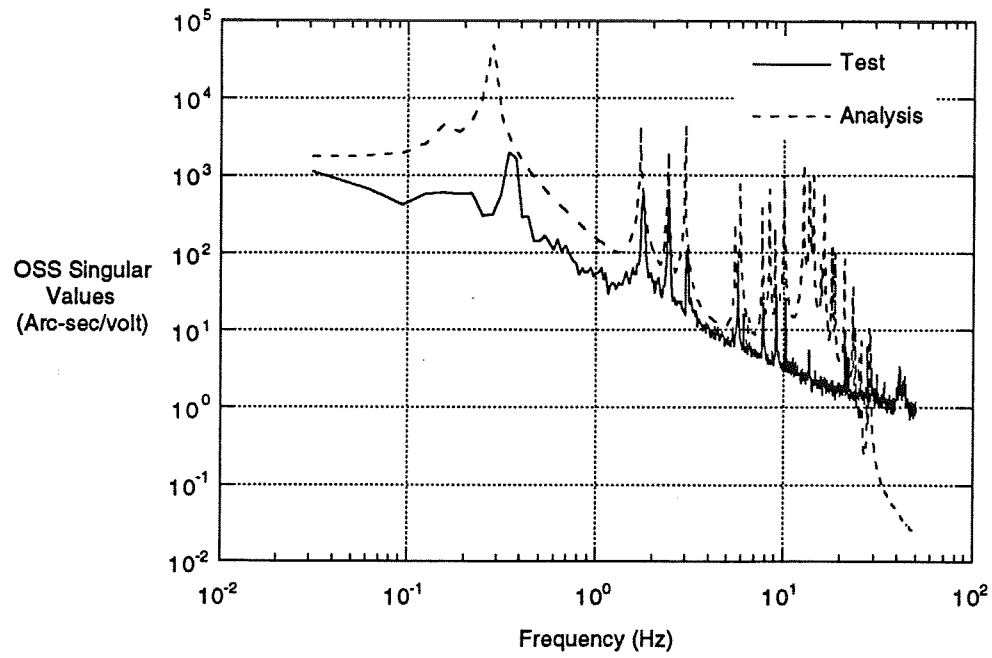


Figure 54. Comparison of maximum singular values of OSS / thruster transfer function

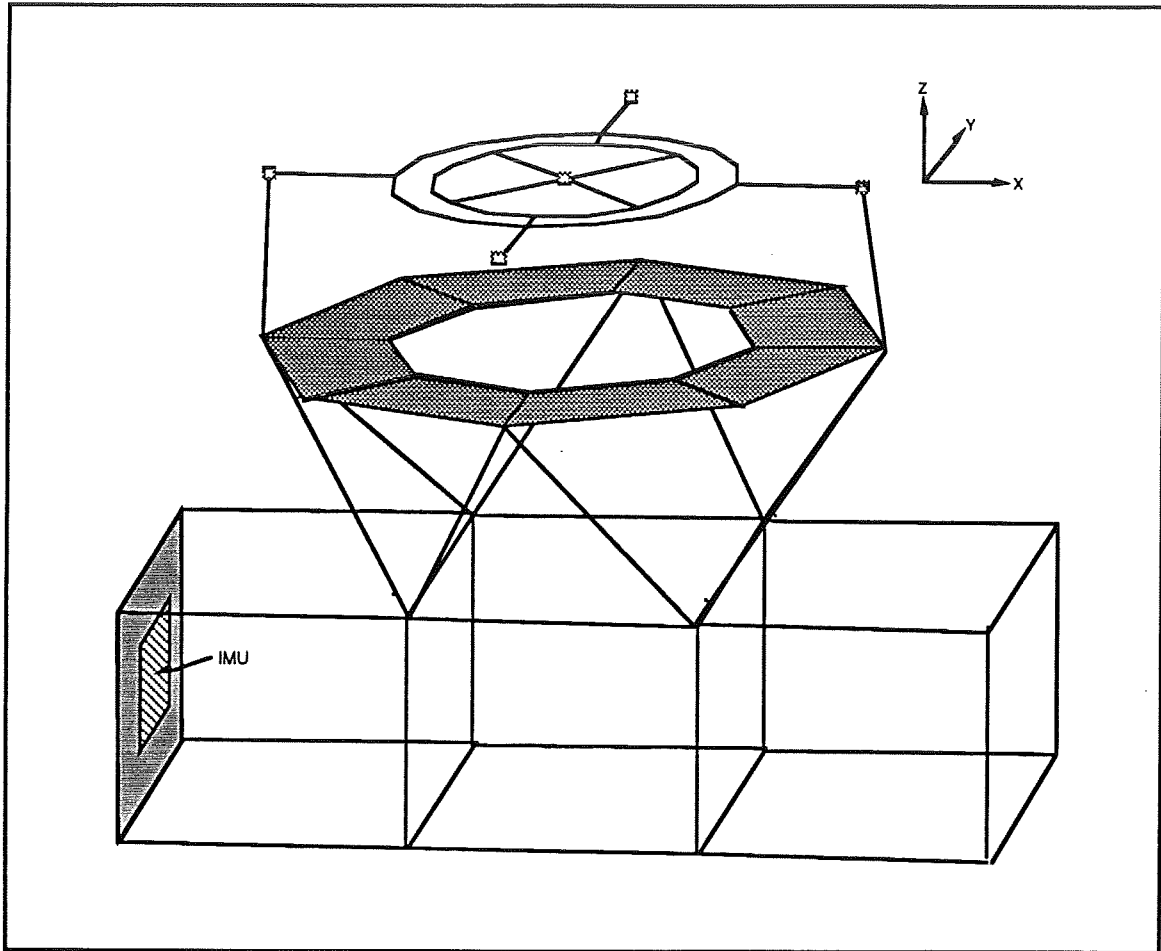


Figure 55. Gimbal and base on Phase-2 model

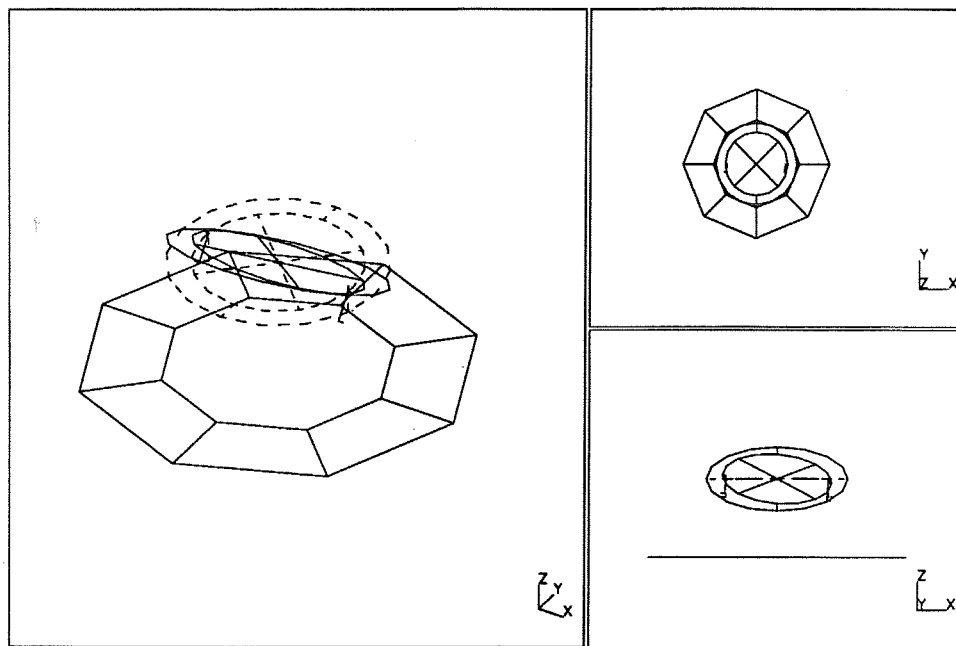


Figure 56. Gimbal mode 1, $f = 3.6317 \times 10^{-6}$ Hz

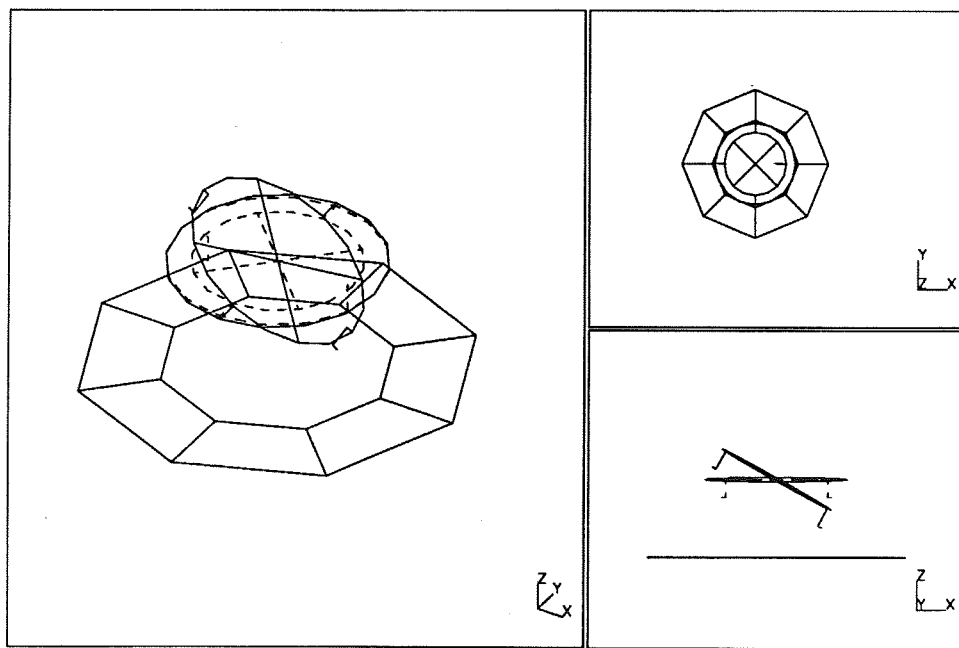


Figure 57. Gimbal mode 2, $f = 8.1948 \times 10^{-6}$ Hz

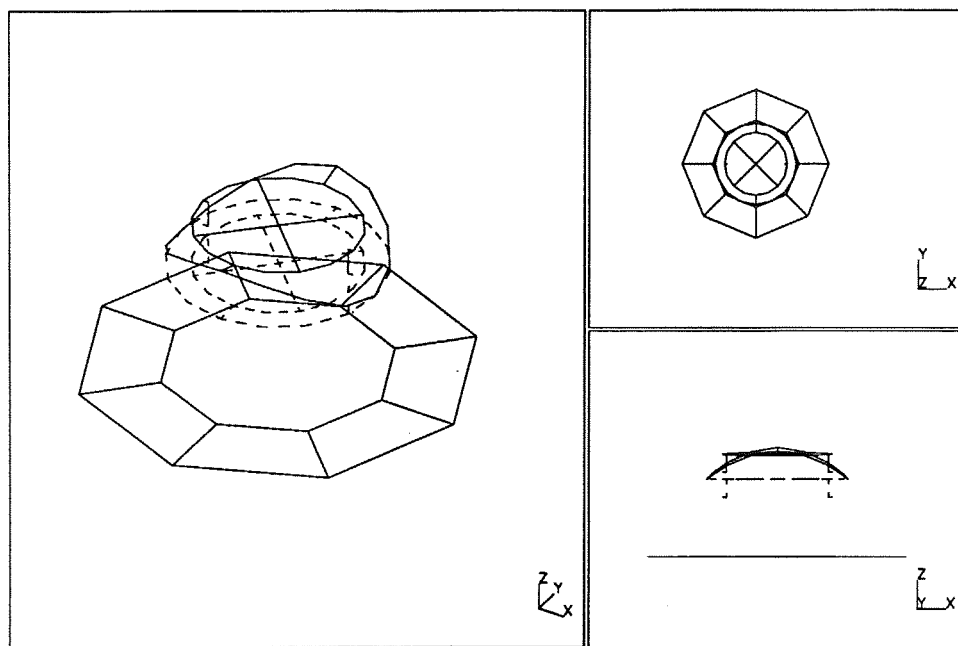


Figure 58. Gimbal mode 3, $f = 47.3233$ Hz

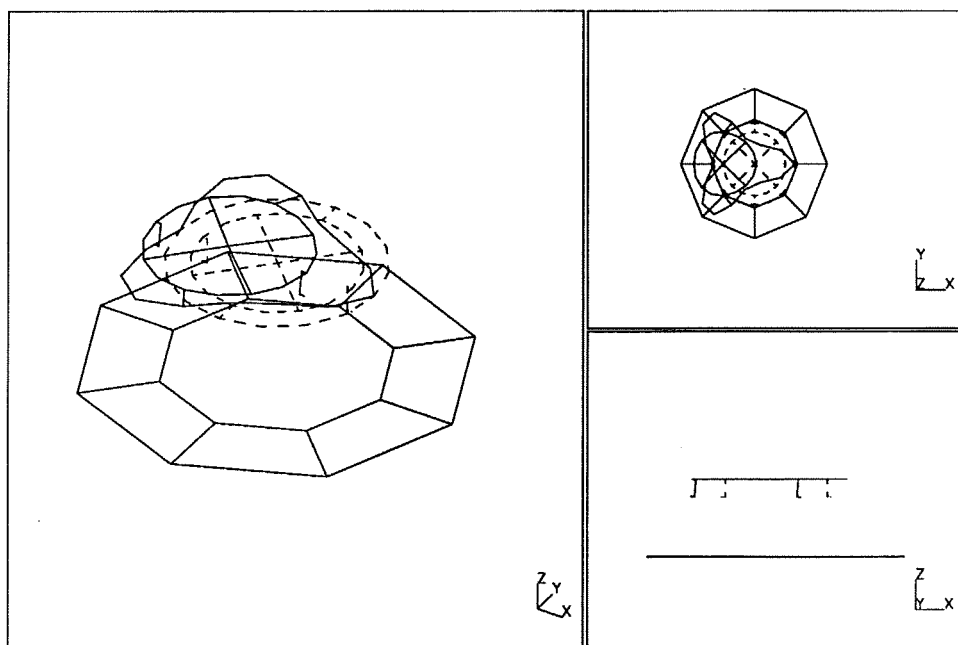


Figure 59. Gimbal mode 4, $f = 108.0121$ Hz

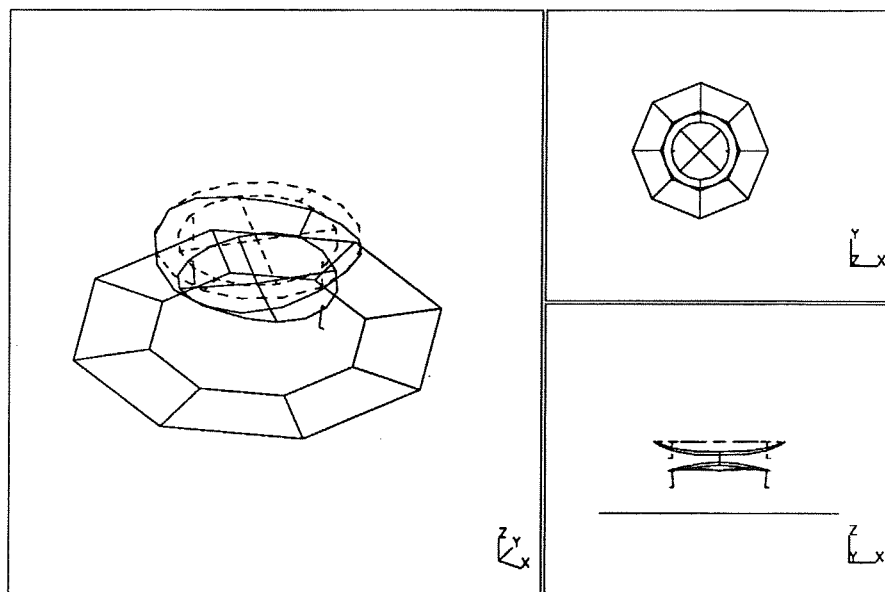
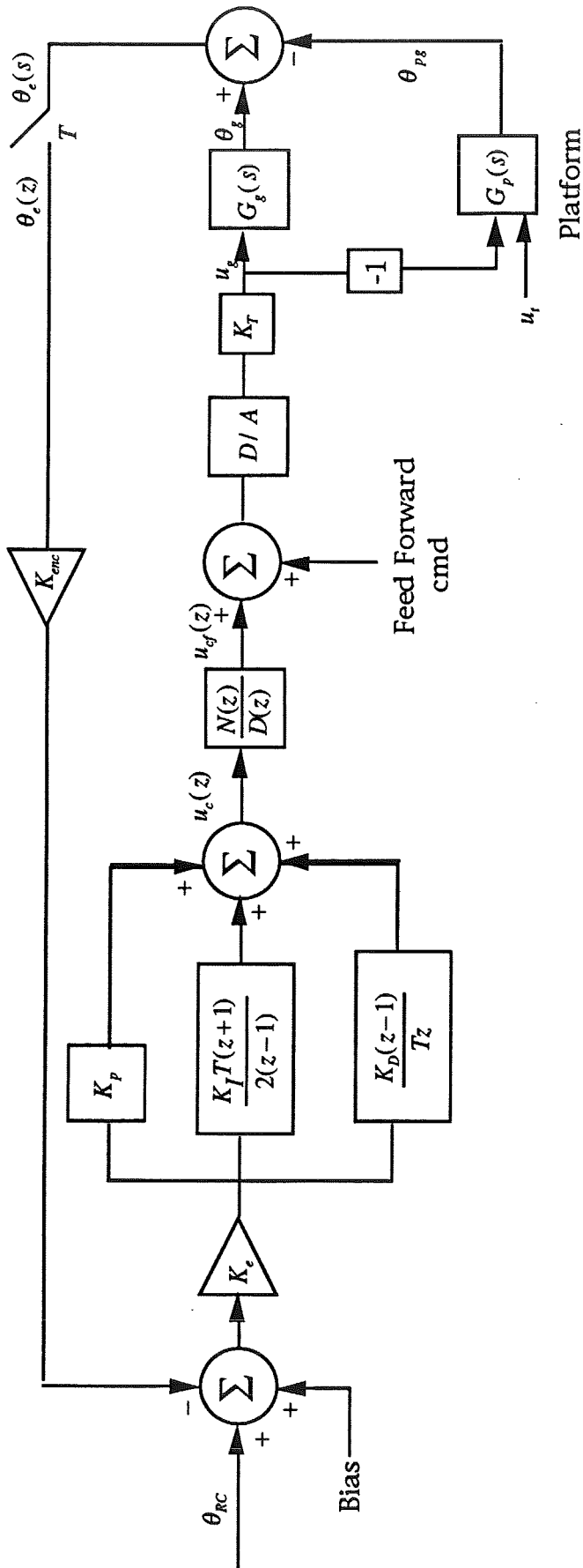


Figure 60. Gimbal mode 5, $f= 117.5721$ Hz



Constants

$$K_p = 8$$

$$K_I = 32$$

$$K_D = 0.125$$

$$K_e = 0.05 \text{ outer}$$

$$K_e = 0.052 \text{ inner}$$

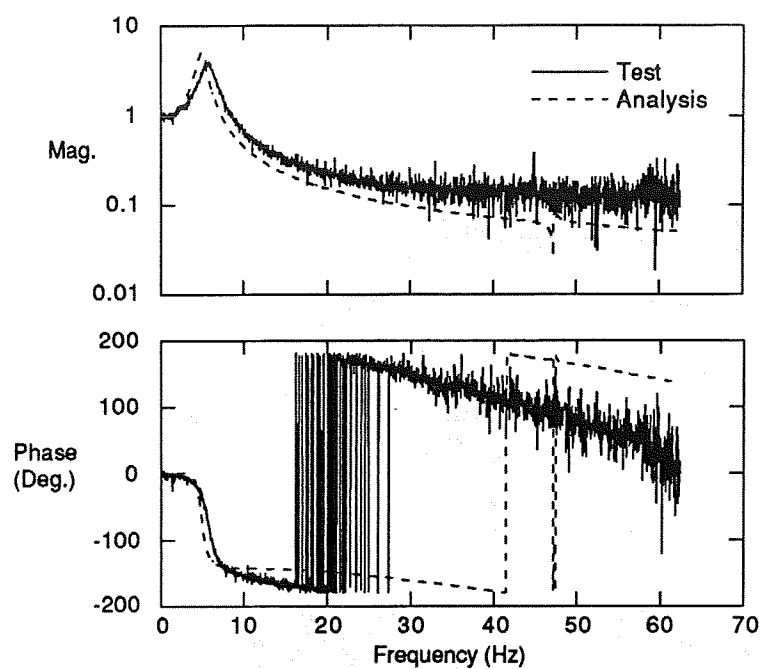
$$K_T = 146.5\text{E-}06 \text{ ft-lb/count}$$

$$K_{enc} = 132.0\text{E+}05 \text{ counts}$$

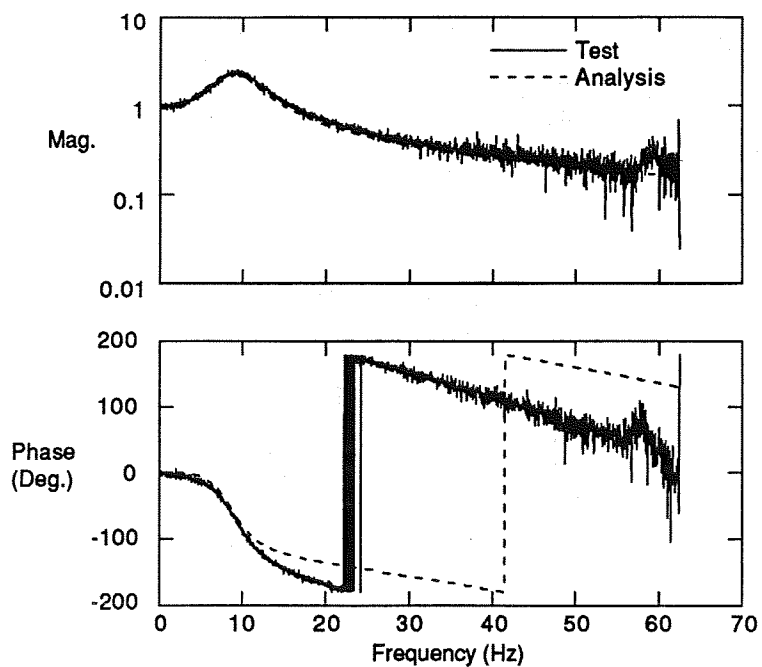
$$64 \text{ counts} = 1 \text{ arc-sec}$$

$$\frac{u_d(z)}{u_e(z)} = \frac{0.0074z^4 + 0.0296z^3 + 0.0444z^2 + 0.0296z + 0.0074}{z^4 - 2.333z^3 + 2.386z^2 - 1.202z + 0.267}$$

Figure 61. Gimbal controller



a) Outer gimbal



b) Inner gimbal

Figure 62. Bench test results for gimbal system with FEM model

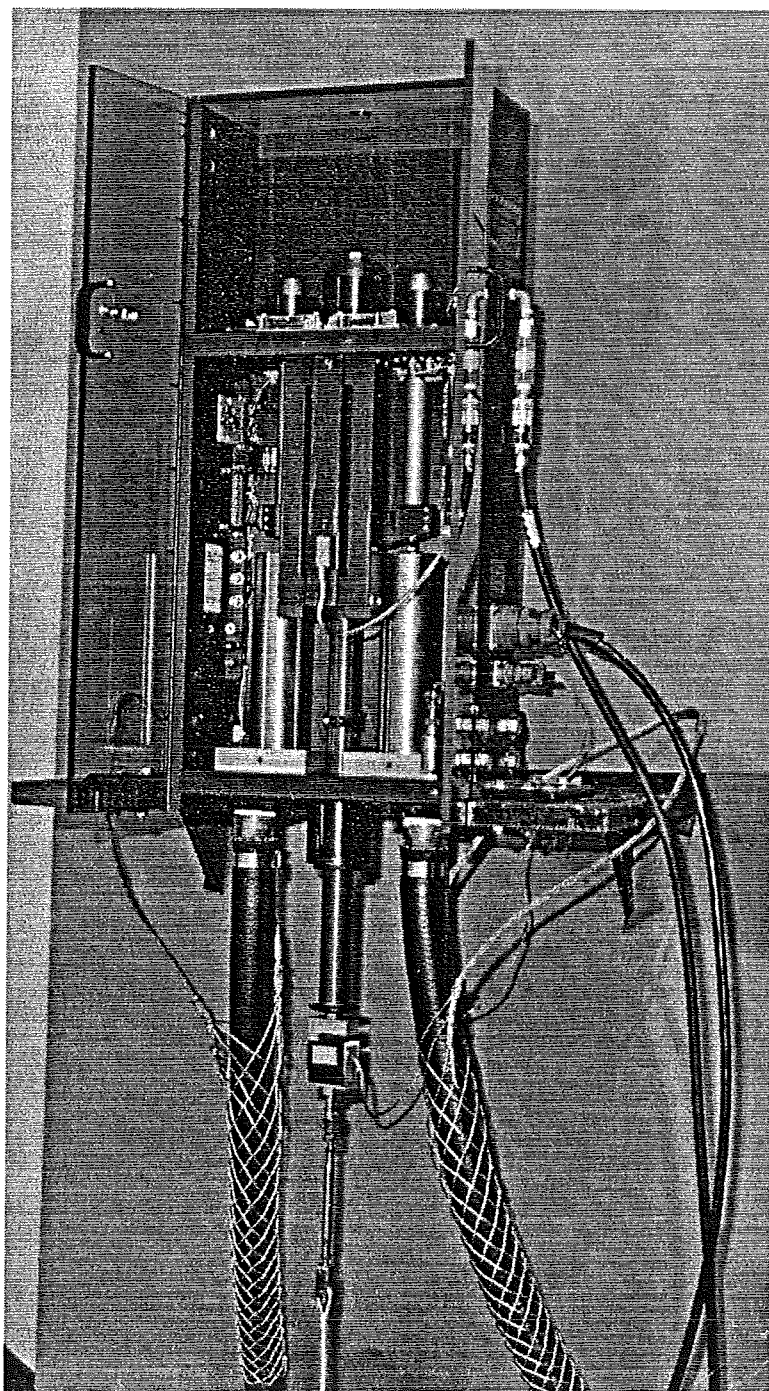


Figure 63. Photograph of suspension mechanism

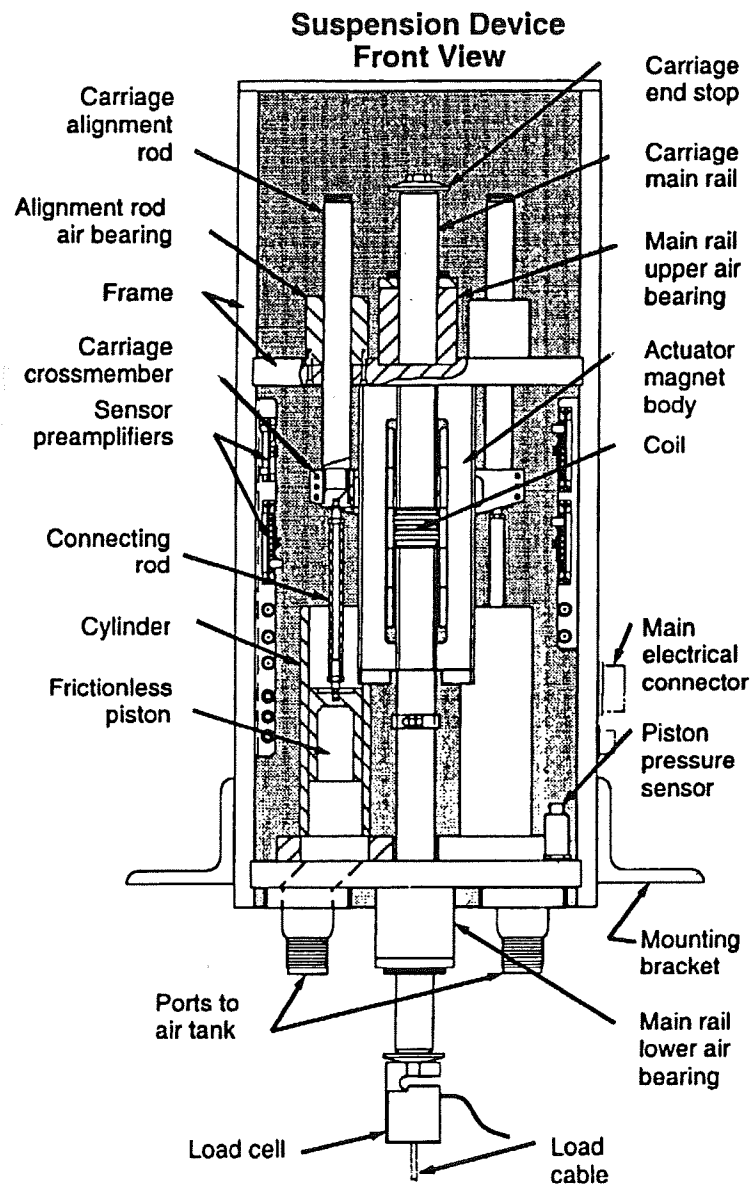


Figure 64. Schematic of suspension system device

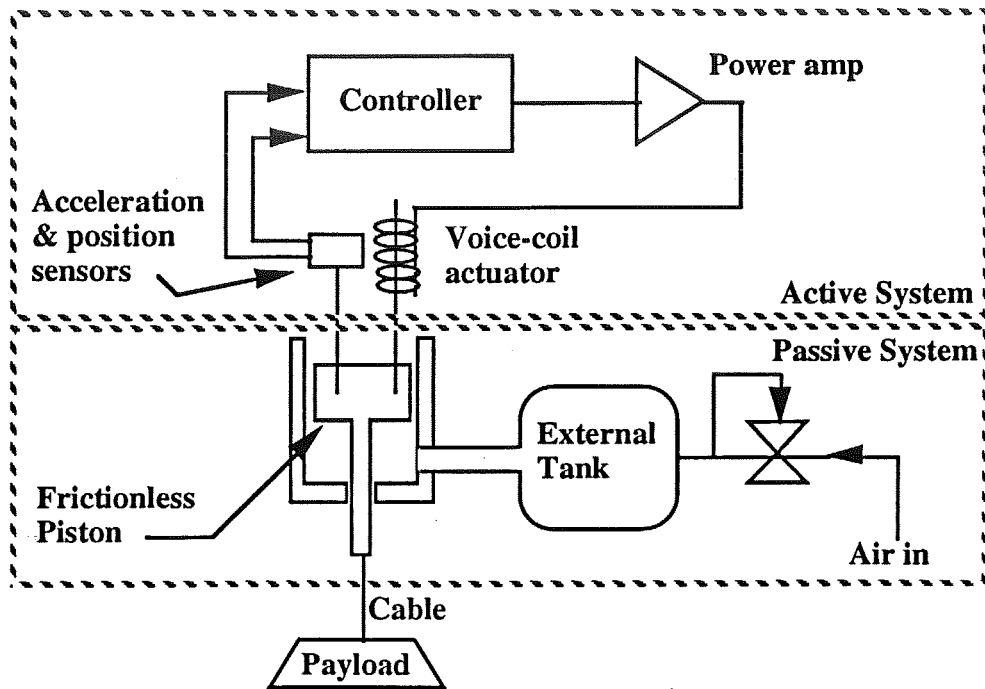


Figure 65. Suspension device operating principle

Appendix A

The following data is the NASTRAN runstream for the Phase-2 CEM model used to compute the mass matrix and the stiffness matrix including differential stiffness due to gravity preload. This data runs under MSC/NASTRAN Version 66, Rigid Format 66.

```

NASTRAN REAL=0, HICORE=1000000
ID PHASE-TWO, CSI EVOLUTIONARY FEM
APP DISPLACEMENT
SOL 66
TIME 12000
CEND
TITLE = CSI GROUND TEST BEAM, P2JULY2693 (july 26,1993)
SUBTITLE = SOL 66
ECHO=UNSORT
LINE = 35
SPC = 100
MPC = 1
SEALL=ALL
LOAD = 200
NLPARM = 100
OUTPUT(PLOT)
CSCALE=1.8
PLOTTER NAST
SET 1 = 1 THRU 500,812 THRU 899,955 THRU 986,1007 THRU 1166,
      1267 THRU 1426,1527 THRU 1550, 1590 THRU 2048,
      2051 THRU 2058
AXES = X,Y,Z
VIEW = 214.27,23.17,0.
FIND SCALE ORIGIN 1 SET 1
PLOT SET 1 ORIGIN 1
PLOT STATIC DEFORMATION SET 1 ORIGIN 1 SHAPE
$
$ 4 REDESIGNED AREAS OF THE TRUSS.
$ AREA # 1 - MAIN TRUSS BAYS 1 THRU 20
$ AREA # 2 - THE FWD & AFT SUSPENSION TRUSS, + RFL TRUSS
$ AREA # 3 - THE LASER TOWER
$ AREA # 4 - MAIN TRUSS BAYS 21 THRU 62
$ ALL BATTENS HAVE THE SAME A(eff) and MASS DENSITY 91/12/07
$ ALL DIAGONALS HAVE THE SAME A(eff) and MASS DENSITY 91/12/07
$ UPDATED TRUSS STRUT AREAS AND DENSITIES FROM LOCKHEED TESTS 92/03/11
$ CONSTRAINED BOTTOM OF SPRING
$ THRUSTER AIR TUBING SPRINGS ARE ON
$ PUT SPC ON PLATES WITHOUT NORMAL RESTRAINTS
$ TOOK J OFF SUSPENSION CABLES
$ SUSPENSION CABLE BROKEN INTO 5 ELEMENTS 92/04/14
$ ADDED WEIGHTLESS BEAMS BEHIND THRUSTER PLATES CBEAM 1700 T 1737
$ UPDATE 92/07/25
$ UPDATE 92/08/17
$ UPDATE 92/09/01 ADDED IMU MASS
$ CORRECTED RFL PLATE GRID DISPL COORD 92/09/03
$ ADDED 6 LB MASS AT BOTTOM OF SUSPENSION SPRING 92/09/09
$ CORRECTED DIAGONALS 672 AND 674 92/09/09
BEGIN BULK
$
CORD2C      3      0 615.00 0.00000 56.110 590.22 0.00000 86.707+CS  3
+CS  3 645.60 0.00000 80.885
PARAM,LGDISP,1
NLPARM,100,4,,SEMI,1,30,
PARAM,GRDPNT,0
PARAM,MAXRATIO,1.E+8

```

PARAM,COUPMASS,1
GRAV,200,0,386.,0.,0.,-1.

\$

SPC1 100 123456 508 509 518 519
SPC1 100 123456 528 529 538 539
SPC1 100 456 510 511 512 513 514
SPC1 100 456 520 521 522 523 524
SPC1 100 456 530 531 532 533 534
SPC1 100 456 540 541 542 543 544

\$ Multipoint Constraint for Skewed Shaker Locations

\$MPC 1 901 2 1.0 3 2 -0.707 +CS 7
\$+CS 7 3 3 -0.707
\$MPC 1 901 3 1.0 3 2 0.707 +CS 8
\$+CS 8 3 3 -0.707
\$MPC 1 902 2 1.0 131 2 -0.707 +CS 9
\$+CS 9 131 3 -0.707
\$MPC 1 902 3 1.0 131 2 0.707 +CT 1
\$+CT 1 131 3 -0.707
\$MPC 1 903 1 1.0 372 1 -0.707 +CT 2
\$+CT 2 372 3 0.707
\$MPC 1 903 3 1.0 372 1 -0.707 +CT 3
\$+CT 3 372 3 -0.707
\$MPC 1 904 1 1.0 456 1 -0.707 +CT 4
\$+CT 4 456 3 0.707
\$MPC 1 904 3 1.0 456 1 -0.707 +CT 5
\$+CT 5 456 3 -0.707

\$ MAIN TRUSS GRID POINTS

GRID, 1, 0, 0.0000, 5.0000, 5.0000
GRID, 2, 0, 0.0000, -5.0000, 5.0000
GRID, 3, 0, 0.0000, -5.0000, -5.0000
GRID, 4, 0, 0.0000, 5.0000, -5.0000
GRID, 5, 0, 10.0000, 5.0000, 5.0000
GRID, 6, 0, 10.0000, -5.0000, 5.0000
GRID, 7, 0, 10.0000, -5.0000, -5.0000
GRID, 8, 0, 10.0000, 5.0000, -5.0000
GRID, 9, 0, 20.0000, 5.0000, 5.0000
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GRID, 13, 0, 30.0000, 5.0000, 5.0000
GRID, 14, 0, 30.0000, -5.0000, 5.0000
GRID, 15, 0, 30.0000, -5.0000, -5.0000
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GRID, 18, 0, 40.0000, -5.0000, 5.0000
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GRID, 20, 0, 40.0000, 5.0000, -5.0000
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GRID, 29, 0, 70.0000, 5.0000, 5.0000
GRID, 30, 0, 70.0000, -5.0000, 5.0000
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GRID, 32, 0, 70.0000, 5.0000, -5.0000
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GRID, 34, 0, 80.0000, -5.0000, 5.0000
GRID, 35, 0, 80.0000, -5.0000, -5.0000
GRID, 36, 0, 80.0000, 5.0000, -5.0000

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GRID, 38, 0, 90.0000, -5.0000, 5.0000
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GRID, 43, 0, 100.0000, -5.0000, -5.0000
GRID, 44, 0, 100.0000, 5.0000, -5.0000
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\$ REFLECTOR TRUSS
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\$ TOWER TRUSS
 GRID, 269, 0,150.0000, 5.0000, 15.0000
 GRID, 270, 0,150.0000, -5.0000, 15.0000
 GRID, 271, 0,160.0000, -5.0000, 15.0000
 GRID, 272, 0,160.0000, 5.0000, 15.0000
 GRID, 273, 0,150.0000, 5.0000, 25.0000
 GRID, 274, 0,150.0000, -5.0000, 25.0000
 GRID, 275, 0,160.0000, -5.0000, 25.0000
 GRID, 276, 0,160.0000, 5.0000, 25.0000
 GRID, 277, 0,150.0000, 5.0000, 35.0000
 GRID, 278, 0,150.0000, -5.0000, 35.0000
 GRID, 279, 0,160.0000, -5.0000, 35.0000
 GRID, 280, 0,160.0000, 5.0000, 35.0000
 GRID, 281, 0,150.0000, 5.0000, 45.0000
 GRID, 282, 0,150.0000, -5.0000, 45.0000
 GRID, 283, 0,160.0000, -5.0000, 45.0000
 GRID, 284, 0,160.0000, 5.0000, 45.0000
 GRID, 285, 0,150.0000, 5.0000, 55.0000
 GRID, 286, 0,150.0000, -5.0000, 55.0000
 GRID, 287, 0,160.0000, -5.0000, 55.0000
 GRID, 288, 0,160.0000, 5.0000, 55.0000
 GRID, 289, 0,150.0000, 5.0000, 65.0000
 GRID, 290, 0,150.0000, -5.0000, 65.0000
 GRID, 291, 0,160.0000, -5.0000, 65.0000
 GRID, 292, 0,160.0000, 5.0000, 65.0000
 GRID, 293, 0,150.0000, 5.0000, 75.0000
 GRID, 294, 0,150.0000, -5.0000, 75.0000
 GRID, 295, 0,160.0000, -5.0000, 75.0000
 GRID, 296, 0,160.0000, 5.0000, 75.0000
 GRID, 297, 0,150.0000, 5.0000, 85.0000
 GRID, 298, 0,150.0000, -5.0000, 85.0000
 GRID, 299, 0,160.0000, -5.0000, 85.0000
 GRID, 300, 0,160.0000, 5.0000, 85.0000
 GRID, 301, 0,150.0000, 5.0000, 95.0000
 GRID, 302, 0,150.0000, -5.0000, 95.0000
 GRID, 303, 0,160.0000, -5.0000, 95.0000
 GRID, 304, 0,160.0000, 5.0000, 95.0000
 GRID, 305, 0,150.0000, 5.0000, 105.0000
 GRID, 306, 0,150.0000, -5.0000, 105.0000
 GRID, 307, 0,160.0000, -5.0000, 105.0000
 GRID, 308, 0,160.0000, 5.0000, 105.0000
 GRID, 309, 0,150.0000, 5.0000, 115.0000
 GRID, 310, 0,150.0000, -5.0000, 115.0000
 GRID, 311, 0,160.0000, -5.0000, 115.0000
 GRID, 312, 0,160.0000, 5.0000, 115.0000
\$ FORWARD SUSPENSION TRUSS
 GRID, 313, 0,120.0000, 15.0000, 5.0000
 GRID, 314, 0,130.0000, 15.0000, 5.0000
 GRID, 315, 0,130.0000, 15.0000, -5.0000
 GRID, 316, 0,120.0000, 15.0000, -5.0000
 GRID, 317, 0,120.0000, -15.0000, 5.0000
 GRID, 318, 0,130.0000, -15.0000, 5.0000
 GRID, 319, 0,130.0000, -15.0000, -5.0000
 GRID, 320, 0,120.0000, -15.0000, -5.0000
 GRID, 321, 0,120.0000, 25.0000, 5.0000
 GRID, 322, 0,130.0000, 25.0000, 5.0000
 GRID, 323, 0,130.0000, 25.0000, -5.0000
 GRID, 324, 0,120.0000, 25.0000, -5.0000
 GRID, 325, 0,120.0000, -25.0000, 5.0000
 GRID, 326, 0,130.0000, -25.0000, 5.0000

GRID, 327, 0,130.0000,-25.0000, -5.0000
 GRID, 328, 0,120.0000,-25.0000, -5.0000
 GRID, 329, 0,120.0000, 35.0000, 5.0000
 GRID, 330, 0,130.0000, 35.0000, 5.0000
 GRID, 331, 0,130.0000, 35.0000, -5.0000
 GRID, 332, 0,120.0000, 35.0000, -5.0000
 GRID, 333, 0,120.0000,-35.0000, 5.0000
 GRID, 334, 0,130.0000,-35.0000, 5.0000
 GRID, 335, 0,130.0000,-35.0000, -5.0000
 GRID, 336, 0,120.0000,-35.0000, -5.0000
 GRID, 337, 0,120.0000, 45.0000, 5.0000
 GRID, 338, 0,130.0000, 45.0000, 5.0000
 GRID, 339, 0,130.0000, 45.0000, -5.0000
 GRID, 340, 0,120.0000, 45.0000, -5.0000
 GRID, 341, 0,120.0000,-45.0000, 5.0000
 GRID, 342, 0,130.0000,-45.0000, 5.0000
 GRID, 343, 0,130.0000,-45.0000, -5.0000
 GRID, 344, 0,120.0000,-45.0000, -5.0000
 GRID, 345, 0,120.0000, 55.0000, 5.0000
 GRID, 346, 0,130.0000, 55.0000, 5.0000
 GRID, 347, 0,130.0000, 55.0000, -5.0000
 GRID, 348, 0,120.0000, 55.0000, -5.0000
 GRID, 349, 0,120.0000,-55.0000, 5.0000
 GRID, 350, 0,130.0000,-55.0000, 5.0000
 GRID, 351, 0,130.0000,-55.0000, -5.0000
 GRID, 352, 0,120.0000,-55.0000, -5.0000
 GRID, 353, 0,140.0000, 15.0000, 5.0000
 GRID, 354, 0,140.0000, 15.0000, -5.0000
 GRID, 355, 0,140.0000,-15.0000, 5.0000
 GRID, 356, 0,140.0000,-15.0000, -5.0000
 GRID, 357, 0,140.0000, 25.0000, 5.0000
 GRID, 358, 0,140.0000, 25.0000, -5.0000
 GRID, 359, 0,140.0000,-25.0000, 5.0000
 GRID, 360, 0,140.0000,-25.0000, -5.0000
 GRID, 361, 0,140.0000, 35.0000, 5.0000
 GRID, 362, 0,140.0000, 35.0000, -5.0000
 GRID, 363, 0,140.0000,-35.0000, 5.0000
 GRID, 364, 0,140.0000,-35.0000, -5.0000
 GRID, 365, 0,140.0000, 45.0000, 5.0000
 GRID, 366, 0,140.0000, 45.0000, -5.0000
 GRID, 367, 0,140.0000,-45.0000, 5.0000
 GRID, 368, 0,140.0000,-45.0000, -5.0000
 GRID, 369, 0,140.0000, 55.0000, 5.0000
 GRID, 370, 0,140.0000, 55.0000, -5.0000
 GRID, 371, 0,140.0000,-55.0000, 5.0000
 GRID, 372, 0,140.0000,-55.0000, -5.0000
 \$ BACK SUSPENSION TRUSS
 GRID, 397, 0,550.0000, 15.0000, 5.0000
 GRID, 398, 0,560.0000, 15.0000, 5.0000
 GRID, 399, 0,560.0000, 15.0000, -5.0000
 GRID, 400, 0,550.0000, 15.0000, -5.0000
 GRID, 401, 0,550.0000,-15.0000, 5.0000
 GRID, 402, 0,560.0000,-15.0000, 5.0000
 GRID, 403, 0,560.0000,-15.0000, -5.0000
 GRID, 404, 0,550.0000,-15.0000, -5.0000
 GRID, 405, 0,550.0000, 25.0000, 5.0000
 GRID, 406, 0,560.0000, 25.0000, 5.0000
 GRID, 407, 0,560.0000, 25.0000, -5.0000
 GRID, 408, 0,550.0000, 25.0000, -5.0000
 GRID, 409, 0,550.0000,-25.0000, 5.0000
 GRID, 410, 0,560.0000,-25.0000, 5.0000
 GRID, 411, 0,560.0000,-25.0000, -5.0000
 GRID, 412, 0,550.0000,-25.0000, -5.0000
 GRID, 413, 0,550.0000, 35.0000, 5.0000

GRID, 414, 0,560.0000, 35.0000, 5.0000
 GRID, 415, 0,560.0000, 35.0000, -5.0000
 GRID, 416, 0,550.0000, 35.0000, -5.0000
 GRID, 417, 0,550.0000,-35.0000, 5.0000
 GRID, 418, 0,560.0000,-35.0000, 5.0000
 GRID, 419, 0,560.0000,-35.0000, -5.0000
 GRID, 420, 0,550.0000,-35.0000, -5.0000
 GRID, 421, 0,550.0000, 45.0000, 5.0000
 GRID, 422, 0,560.0000, 45.0000, 5.0000
 GRID, 423, 0,560.0000, 45.0000, -5.0000
 GRID, 424, 0,550.0000, 45.0000, -5.0000
 GRID, 425, 0,550.0000,-45.0000, 5.0000
 GRID, 426, 0,560.0000,-45.0000, 5.0000
 GRID, 427, 0,560.0000,-45.0000, -5.0000
 GRID, 428, 0,550.0000,-45.0000, -5.0000
 GRID, 429, 0,550.0000, 55.0000, 5.0000
 GRID, 430, 0,560.0000, 55.0000, 5.0000
 GRID, 431, 0,560.0000, 55.0000, -5.0000
 GRID, 432, 0,550.0000, 55.0000, -5.0000
 GRID, 433, 0,550.0000,-55.0000, 5.0000
 GRID, 434, 0,560.0000,-55.0000, 5.0000
 GRID, 435, 0,560.0000,-55.0000, -5.0000
 GRID, 436, 0,550.0000,-55.0000, -5.0000
 GRID, 437, 0,540.0000, 15.0000, 5.0000
 GRID, 438, 0,540.0000, 15.0000, -5.0000
 GRID, 439, 0,540.0000,-15.0000, 5.0000
 GRID, 440, 0,540.0000,-15.0000, -5.0000
 GRID, 441, 0,540.0000, 25.0000, 5.0000
 GRID, 442, 0,540.0000, 25.0000, -5.0000
 GRID, 443, 0,540.0000,-25.0000, 5.0000
 GRID, 444, 0,540.0000,-25.0000, -5.0000
 GRID, 445, 0,540.0000, 35.0000, 5.0000
 GRID, 446, 0,540.0000, 35.0000, -5.0000
 GRID, 447, 0,540.0000,-35.0000, 5.0000
 GRID, 448, 0,540.0000,-35.0000, -5.0000
 GRID, 449, 0,540.0000, 45.0000, 5.0000
 GRID, 450, 0,540.0000, 45.0000, -5.0000
 GRID, 451, 0,540.0000,-45.0000, 5.0000
 GRID, 452, 0,540.0000,-45.0000, -5.0000
 GRID, 453, 0,540.0000, 55.0000, 5.0000
 GRID, 454, 0,540.0000, 55.0000, -5.0000
 GRID, 455, 0,540.0000,-55.0000, 5.0000
 GRID, 456, 0,540.0000,-55.0000, -5.0000
 \$ REFLECTOR SUPPORT BRACKETS
 GRID, 485, 0,610.0000, 5.0000, 52.0600
 GRID, 486, 0,610.0000, -5.0000, 52.0600
 GRID, 487, 0,620.0000, -5.0000, 60.1600
 GRID, 488, 0,620.0000, 5.0000, 60.1600
 \$ ADDED FOLLOWING GRID PTS. 90/11/28
 \$ THRUSTERS GRID POINTS
 \$ FORWARD THRUSTER
 GRID, 489, 0, 5.0, 0.0, 5.0
 GRID, 490, 0, 5.0, -5.0, 0.0
 GRID, 491, 0, 5.0, 0.0, -5.0
 GRID, 492, 0, 5.0, 5.0, 0.0
 \$ TOWER THRUSTER
 GRID, 493, 0,155.0, 5.0,100.0
 GRID, 494, 0,160.0, 0.0,100.0
 GRID, 495, 0,155.0, -5.0,100.0
 GRID, 496, 0,150.0, 0.0,100.0
 \$ LASER GRID POINT
 GRID, 497, 0,155.0, 0.0,115.0

\$ MIDDLE THRUSTER

GRID, 498, 0,325.0, 0.0, 5.0	GRID	563	0	119.125	0.000	12.707	0
GRID, 499, 0,325.0, -5.0, 0.0	GRID	564	0	117.929	7.071	12.707	0
GRID, 500, 0,325.0, 0.0, -5.0	GRID	565	0	120.846	4.154	12.707	0
GRID, 501, 0,325.0, 5.0, 0.0	GRID	566	0	125.000	5.500	18.707	0
\$ REFLECTOR TRUSS THRUSTER	GRID	567	0	125.000	4.250	18.707	0
GRID, 502, 0,615.0, 5.0, 40.0	GRID	568	0	127.105	5.081	18.707	0
GRID, 503, 0,620.0, 0.0, 40.0	GRID	569	0	126.626	3.926	18.707	0
GRID, 504, 0,615.0, -5.0, 40.0	GRID	570	0	128.889	3.889	18.707	0
GRID, 505, 0,610.0, 0.0, 40.0	GRID	571	0	128.005	3.005	18.707	0
\$ FRONT SUSPENSION CABLE, +Y	GRID	572	0	130.081	2.105	18.707	0
GRID, 508, 0,130.0000, 50.0000,803.5000	GRID	573	0	128.926	1.626	18.707	0
GRID, 509, 0,130.0000, 50.0000,777.0000	GRID	574	0	130.500	0.000	18.707	0
GRID, 510, 0,130.0, 50.0,625.	GRID	575	0	129.250	0.000	18.707	0
GRID, 511, 0,130.0, 50.0,473.	GRID	576	0	130.081	-2.105	18.707	0
GRID, 512, 0,130.0, 50.0,321.	GRID	577	0	128.926	-1.626	18.707	0
GRID, 513, 0,130.0, 50.0,169.	GRID	578	0	128.889	-3.889	18.707	0
GRID, 514, 0,130.0, 50.0, 17.48	GRID	579	0	128.005	-3.005	18.707	0
GRID, 515, 0,130.0, 45.0, 6.78	GRID	580	0	127.105	-5.081	18.707	0
GRID, 516, 0,130.0, 55.0, 6.78	GRID	581	0	126.626	-3.926	18.707	0
\$ FRONT SUSPENSION CABLE, -Y	GRID	582	0	125.000	-5.500	18.707	0
GRID, 518, 0,130.0000,-50.0000,803.5000	GRID	583	0	125.000	-4.250	18.707	0
GRID, 519, 0,130.0000,-50.0000,777.0000	GRID	584	0	122.895	-5.081	18.707	0
GRID, 520, 0,130.0,-50.0,625.	GRID	585	0	123.374	-3.926	18.707	0
GRID, 521, 0,130.0,-50.0,473.	GRID	586	0	121.111	-3.889	18.707	0
GRID, 522, 0,130.0,-50.0,321.	GRID	587	0	121.995	-3.005	18.707	0
GRID, 523, 0,130.0,-50.0,169.	GRID	588	0	119.919	-2.105	18.707	0
GRID, 524, 0,130.0,-50.0, 17.48	GRID	589	0	121.074	-1.626	18.707	0
GRID, 525, 0,130.0,-45.0, 6.78	GRID	590	0	119.500	0.000	18.707	0
GRID, 526, 0,130.0,-55.0, 6.78	GRID	591	0	120.750	0.000	18.707	0
\$ BACK SUSPENSION CABLE, +Y	GRID	592	0	119.919	2.105	18.707	0
GRID, 528, 0,550.0000, 50.0000,803.5000	GRID	593	0	121.074	1.626	18.707	0
GRID, 529, 0,550.0000, 50.0000,777.0000	GRID	594	0	121.111	3.889	18.707	0
GRID, 530, 0,550.0, 50.0,625.	GRID	595	0	121.995	3.005	18.707	0
GRID, 531, 0,550.0, 50.0,473.	GRID	596	0	122.895	5.081	18.707	0
GRID, 532, 0,550.0, 50.0,321.	GRID	597	0	123.374	3.926	18.707	0
GRID, 533, 0,550.0, 50.0,169.	GRID	598	0	134.500	0.000	18.707	0
GRID, 534, 0,550.0, 50.0, 17.48	GRID	599	0	115.500	0.000	18.707	0
GRID, 535, 0,550.0, 45.0, 6.78	GRID	600	0	125.000	9.500	18.707	0
GRID, 536, 0,550.0, 55.0, 6.78	GRID	601	0	125.000	-9.500	18.707	0
\$ BACK SUSPENSION CABLE, -Y	GRID	602	0	125.000	0.000	18.707	0
GRID, 538, 0,550.0000,-50.0000,803.5000	GRID	605	0	140.000	0.000	0.000	0
GRID, 539, 0,550.0000,-50.0000,777.0000	\$ START GIMBAL#2						
GRID, 540, 0,550.0,-50.0,625.	GRID	650	0	185.000	10.000	12.707	0
GRID, 541, 0,550.0,-50.0,473.	GRID	651	0	185.000	5.875	12.707	0
GRID, 542, 0,550.0,-50.0,321.	GRID	652	0	192.071	7.071	12.707	0
GRID, 543, 0,550.0,-50.0,169.	GRID	653	0	189.154	4.154	12.707	0
GRID, 544, 0,550.0,-50.0, 17.48	GRID	654	0	195.000	0.000	12.707	0
GRID, 545, 0,550.0,-45.0, 6.78	GRID	655	0	190.875	0.000	12.707	0
GRID, 546, 0,550.0,-55.0, 6.78	GRID	656	0	192.071	-7.071	12.707	0
\$ START GIMBAL GRIDS	GRID	657	0	189.154	-4.154	12.707	0
\$ GIMBAL#1 - FORWARD	GRID	658	0	185.000	-10.000	12.707	0
GRID 550 0 125.000 10.000 12.707 0	GRID	659	0	185.000	-5.875	12.707	0
GRID 551 0 125.000 5.875 12.707 0	GRID	660	0	177.929	-7.071	12.707	0
GRID 552 0 132.071 7.071 12.707 0	GRID	661	0	180.846	-4.154	12.707	0
GRID 553 0 129.154 4.154 12.707 0	GRID	662	0	175.000	0.000	12.707	0
GRID 554 0 135.000 0.000 12.707 0	GRID	663	0	179.125	0.000	12.707	0
GRID 555 0 130.875 0.000 12.707 0	GRID	664	0	177.929	7.071	12.707	0
GRID 556 0 132.071 -7.071 12.707 0	GRID	665	0	180.846	4.154	12.707	0
GRID 557 0 129.154 -4.154 12.707 0	GRID	666	0	185.000	5.500	18.707	0
GRID 558 0 125.000 -10.000 12.707 0	GRID	667	0	185.000	4.250	18.707	0
GRID 559 0 125.000 -5.875 12.707 0	GRID	668	0	187.105	5.081	18.707	0
GRID 560 0 117.929 -7.071 12.707 0	GRID	669	0	186.626	3.926	18.707	0
GRID 561 0 120.846 -4.154 12.707 0	GRID	670	0	188.889	3.889	18.707	0
GRID 562 0 115.000 0.000 12.707 0	GRID	671	0	188.005	3.005	18.707	0

GRID	672	0	190.081	2.105	18.707	0	GRID	781	0	546.626	-3.926	18.707	0
GRID	673	0	188.926	1.626	18.707	0	GRID	782	0	545.000	-5.500	18.707	0
GRID	674	0	190.500	0.000	18.707	0	GRID	783	0	545.000	-4.250	18.707	0
GRID	675	0	189.250	0.000	18.707	0	GRID	784	0	542.895	-5.081	18.707	0
GRID	676	0	190.081	-2.105	18.707	0	GRID	785	0	543.374	-3.926	18.707	0
GRID	677	0	188.926	-1.626	18.707	0	GRID	786	0	541.111	-3.889	18.707	0
GRID	678	0	188.889	-3.889	18.707	0	GRID	787	0	541.995	-3.005	18.707	0
GRID	679	0	188.005	-3.005	18.707	0	GRID	788	0	539.919	-2.105	18.707	0
GRID	680	0	187.105	-5.081	18.707	0	GRID	789	0	541.074	-1.626	18.707	0
GRID	681	0	186.626	-3.926	18.707	0	GRID	790	0	539.500	0.000	18.707	0
GRID	682	0	185.000	-5.500	18.707	0	GRID	791	0	540.750	0.000	18.707	0
GRID	683	0	185.000	-4.250	18.707	0	GRID	792	0	539.919	2.105	18.707	0
GRID	684	0	182.895	-5.081	18.707	0	GRID	793	0	541.074	1.626	18.707	0
GRID	685	0	183.374	-3.926	18.707	0	GRID	794	0	541.111	3.889	18.707	0
GRID	686	0	181.111	-3.889	18.707	0	GRID	795	0	541.995	3.005	18.707	0
GRID	687	0	181.995	-3.005	18.707	0	GRID	796	0	542.895	5.081	18.707	0
GRID	688	0	179.919	-2.105	18.707	0	GRID	797	0	543.374	3.926	18.707	0
GRID	689	0	181.074	-1.626	18.707	0	GRID	798	0	554.500	0.000	18.707	0
GRID	690	0	179.500	0.000	18.707	0	GRID	799	0	535.500	0.000	18.707	0
GRID	691	0	180.750	0.000	18.707	0	GRID	800	0	545.000	9.500	18.707	0
GRID	692	0	179.919	2.105	18.707	0	GRID	801	0	545.000	-9.500	18.707	0
GRID	693	0	181.074	1.626	18.707	0	GRID	802	0	545.000	0.000	18.707	0
GRID	694	0	181.111	3.889	18.707	0	GRID	805	0	560.000	0.000	0.000	0
GRID	695	0	181.995	3.005	18.707	0	\$ REFLECTOR 86.4# SPACER PLATE GRID POINTS						
GRID	696	0	182.895	5.081	18.707	0	GRID,851, 3, 8.1500, 0.0000, 0.811, 0						
GRID	697	0	183.374	3.926	18.707	0	GRID,852, 3, 8.1500, 37.8428, 0.811, 0						
GRID	698	0	194.500	0.000	18.707	0	GRID,853, 3, 8.1500, 90.0000, 0.811, 0						
GRID	699	0	175.500	0.000	18.707	0	GRID,854, 3, 8.1500, 142.1572, 0.811, 0						
GRID	700	0	185.000	9.500	18.707	0	GRID,855, 3, 8.1500, 180.0000, 0.811, 0						
GRID	701	0	185.000	-9.500	18.707	0	GRID,856, 3, 8.1500, 217.8428, 0.811, 0						
GRID	702	0	185.000	0.000	18.707	0	GRID,857, 3, 8.1500, 270.0000, 0.811, 0						
GRID	705	0	200.000	0.000	0.000	0	GRID,858, 3, 8.1500, 322.1572, 0.811, 0						
\$ START GIMBAL#3							GRID,859, 3, 0.0000, 0.0000, 0.811, 0						
GRID	750	0	545.000	10.000	12.707	0	\$ SHAKER GRID POINTS ADDED (JWG 01/06/92)						
GRID	751	0	545.000	5.875	12.707	0	GRID,901, 0, 0.0000, -5.000, -5.00						
GRID	752	0	552.071	7.071	12.707	0	GRID,902, 0, 320.00, -5.000, -5.00						
GRID	753	0	549.154	4.154	12.707	0	GRID,903, 0, 140.00, -55.000, -5.00						
GRID	754	0	555.000	0.000	12.707	0	GRID,904, 0, 540.00, -55.000, -5.00						
GRID	755	0	550.875	0.000	12.707	0	\$ START ELEMENTS						
GRID	756	0	552.071	-7.071	12.707	0	\$ MAIN TRUSS, 20 BAYS, LONGERONS, PID 101						
GRID	757	0	549.154	-4.154	12.707	0	CBEAM, 1,101, 1, 5,0,1,1.						
GRID	758	0	545.000	-10.000	12.707	0	CBEAM, 2,101, 2, 6,0,1,1.						
GRID	759	0	545.000	-5.875	12.707	0	CBEAM, 3,101, 3, 7,0,1,1.						
GRID	760	0	537.929	-7.071	12.707	0	CBEAM, 4,101, 4, 8,0,1,1.						
GRID	761	0	540.846	-4.154	12.707	0	CBEAM, 5,101, 5, 9,0,1,1.						
GRID	762	0	535.000	0.000	12.707	0	CBEAM, 6,101, 6, 10,0,1,1.						
GRID	763	0	539.125	0.000	12.707	0	CBEAM, 7,101, 7, 11,0,1,1.						
GRID	764	0	537.929	7.071	12.707	0	CBEAM, 8,101, 8, 12,0,1,1.						
GRID	765	0	540.846	4.154	12.707	0	CBEAM, 9,101, 9, 13,0,1,1.						
GRID	766	0	545.000	5.500	18.707	0	CBEAM, 10,101, 10, 14,0,1,1.						
GRID	767	0	545.000	4.250	18.707	0	CBEAM, 11,101, 11, 15,0,1,1.						
GRID	768	0	547.105	5.081	18.707	0	CBEAM, 12,101, 12, 16,0,1,1.						
GRID	769	0	546.626	3.926	18.707	0	CBEAM, 13,101, 13, 17,0,1,1.						
GRID	770	0	548.889	3.889	18.707	0	CBEAM, 14,101, 14, 18,0,1,1.						
GRID	771	0	548.005	3.005	18.707	0	CBEAM, 15,101, 15, 19,0,1,1.						
GRID	772	0	550.081	2.105	18.707	0	CBEAM, 16,101, 16, 20,0,1,1.						
GRID	773	0	548.926	1.626	18.707	0	CBEAM, 17,101, 17, 21,0,1,1.						
GRID	774	0	550.500	0.000	18.707	0	CBEAM, 18,101, 18, 22,0,1,1.						
GRID	775	0	549.250	0.000	18.707	0	CBEAM, 19,101, 19, 23,0,1,1.						
GRID	776	0	550.081	-2.105	18.707	0	CBEAM, 20,101, 20, 24,0,1,1.						
GRID	777	0	548.926	-1.626	18.707	0	CBEAM, 21,101, 21, 25,0,1,1.						
GRID	778	0	548.889	-3.889	18.707	0	CBEAM, 22,101, 22, 26,0,1,1.						
GRID	779	0	548.005	-3.005	18.707	0	CBEAM, 23,101, 23, 27,0,1,1.						
GRID	780	0	547.105	-5.081	18.707	0	CBEAM, 24,101, 24, 28,0,1,1.						

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 CBEAM, 500,402, 252, 249,1,0,1.
 \$ MAIN TRUSS,20 BAYS,BATTEN
 DIAGONALS,PID 103
 CBEAM, 501,103, 1, 3,1,0,1.
 CBEAM, 502,103, 6, 8,1,0,1.
 CBEAM, 503,103, 9, 11,1,0,1.
 CBEAM, 504,103, 14, 16,1,0,1.
 CBEAM, 505,103, 17, 19,1,0,1.
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 CBEAM, 511,103, 41, 43,1,0,1.
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 CBEAM, 514,103, 54, 56,1,0,1.
 CBEAM, 515,103, 57, 59,1,0,1.
 CBEAM, 516,103, 62, 64,1,0,1.
 CBEAM, 517,103, 65, 67,1,0,1.
 CBEAM, 518,103, 70, 72,1,0,1.
 CBEAM, 519,103, 73, 75,1,0,1.
 CBEAM, 520,103, 78, 80,1,0,1.
 CBEAM, 521,103, 81, 83,1,0,1.
 \$ MAIN TRUSS,42 BAYS,BATTEN
 DIAGONALS,PID 403
 CBEAM, 522,403, 86, 88,1,0,1.
 CBEAM, 523,403, 89, 91,1,0,1.
 CBEAM, 524,403, 94, 96,1,0,1.
 CBEAM, 525,403, 97, 99,1,0,1.
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 CBEAM, 528,403, 110, 112,1,0,1.
 CBEAM, 529,403, 113, 115,1,0,1.

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 CBEAM, 532,403, 126, 128,1,0,1.
 CBEAM, 533,403, 129, 131,1,0,1.
 CBEAM, 534,403, 134, 136,1,0,1.
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 CBEAM, 562,403, 246, 248,1,0,1.
 CBEAM, 563,403, 249, 251,1,0,1.
 \$ MAIN TRUSS ,20 BAYS,TOP AND BOTTOM
 DIAGONALS,PID 103
 CBEAM, 566,103, 6, 9,1,0,1.
 CBEAM, 567,103, 8, 11,1,0,1.
 CBEAM, 568,103, 9, 14,1,0,1.
 CBEAM, 569,103, 11, 16,1,0,1.
 CBEAM, 570,103, 14, 17,1,0,1.
 CBEAM, 571,103, 16, 19,1,0,1.
 CBEAM, 572,103, 17, 22,1,0,1.
 CBEAM, 573,103, 19, 24,1,0,1.
 CBEAM, 574,103, 22, 25,1,0,1.
 CBEAM, 575,103, 24, 27,1,0,1.
 CBEAM, 576,103, 25, 30,1,0,1.
 CBEAM, 577,103, 27, 32,1,0,1.
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 CBEAM, 582,103, 38, 41,1,0,1.
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 CBEAM, 584,103, 41, 46,1,0,1.
 CBEAM, 585,103, 43, 48,1,0,1.
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 CBEAM, 587,103, 48, 51,1,0,1.
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 CBEAM, 590,103, 54, 57,1,0,1.
 CBEAM, 591,103, 56, 59,1,0,1.
 CBEAM, 592,103, 57, 62,1,0,1.
 CBEAM, 593,103, 59, 64,1,0,1.

CBEAM, 594,103, 62, 65,1,0,1.
 CBEAM, 595,103, 64, 67,1,0,1.
 CBEAM, 596,103, 65, 70,1,0,1.
 CBEAM, 597,103, 67, 72,1,0,1.
 CBEAM, 598,103, 70, 73,1,0,1.
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 CBEAM, 602,103, 78, 81,1,0,1.
 CBEAM, 603,103, 80, 83,1,0,1.
 \$ MAIN TRUSS,42 BAYS,TOP AND BOTTOM
 DIAGONALS,PID 403
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 CBEAM, 605,403, 83, 88,1,0,1.
 CBEAM, 606,403, 86, 89,1,0,1.
 CBEAM, 607,403, 88, 91,1,0,1.
 CBEAM, 608,403, 89, 94,1,0,1.
 CBEAM, 609,403, 91, 96,1,0,1.
 CBEAM, 610,403, 94, 97,1,0,1.
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 CBEAM, 613,403, 99, 104,1,0,1.
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 CBEAM, 616,403, 105, 110,1,0,1.
 CBEAM, 617,403, 107, 112,1,0,1.
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 CBEAM, 621,403, 115, 120,1,0,1.
 CBEAM, 622,403, 118, 121,1,0,1.
 CBEAM, 623,403, 120, 123,1,0,1.
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 CBEAM, 626,403, 126, 129,1,0,1.
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 CBEAM, 686,403, 246, 249,1,0,1.
 CBEAM, 687,403, 248, 251,1,0,1.
 \$ MAIN TRUSS,20 BAYS,SIDE DIAGONALS,
 PID 103
 CBEAM, 690,103, 7, 10,0,1,1.
 CBEAM, 691,103, 5, 12,0,1,1.
 CBEAM, 692,103, 10, 15,0,1,1.
 CBEAM, 693,103, 12, 13,0,1,1.
 CBEAM, 694,103, 15, 18,0,1,1.
 CBEAM, 695,103, 13, 20,0,1,1.
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 CBEAM, 699,103, 21, 28,0,1,1.
 CBEAM, 700,103, 26, 31,0,1,1.
 CBEAM, 701,103, 28, 29,0,1,1.
 CBEAM, 702,103, 31, 34,0,1,1.
 CBEAM, 703,103, 29, 36,0,1,1.
 CBEAM, 704,103, 34, 39,0,1,1.
 CBEAM, 705,103, 36, 37,0,1,1.
 CBEAM, 706,103, 39, 42,0,1,1.
 CBEAM, 707,103, 37, 44,0,1,1.
 CBEAM, 708,103, 42, 47,0,1,1.
 CBEAM, 709,103, 44, 45,0,1,1.
 CBEAM, 710,103, 47, 50,0,1,1.
 CBEAM, 711,103, 45, 52,0,1,1.
 CBEAM, 712,103, 50, 55,0,1,1.
 CBEAM, 713,103, 52, 53,0,1,1.
 CBEAM, 714,103, 55, 58,0,1,1.
 CBEAM, 715,103, 53, 60,0,1,1.
 CBEAM, 716,103, 58, 63,0,1,1.
 CBEAM, 717,103, 60, 61,0,1,1.
 CBEAM, 718,103, 63, 66,0,1,1.
 CBEAM, 719,103, 61, 68,0,1,1.
 CBEAM, 720,103, 66, 71,0,1,1.
 CBEAM, 721,103, 68, 69,0,1,1.

CBEAM, 722,103, 71, 74,0,1,1.
 CBEAM, 723,103, 69, 76,0,1,1.
 CBEAM, 724,103, 74, 79,0,1,1.
 CBEAM, 725,103, 76, 77,0,1,1.
 CBEAM, 726,103, 79, 82,0,1,1.
 CBEAM, 727,103, 77, 84,0,1,1.
 \$ MAIN TRUSS ,42 BAYS,SIDE DIAGONALS,
 PID 403
 CBEAM, 728,403, 82, 87,0,1,1.
 CBEAM, 729,403, 84, 85,0,1,1.
 CBEAM, 730,403, 87, 90,0,1,1.
 CBEAM, 731,403, 85, 92,0,1,1.
 CBEAM, 732,403, 90, 95,0,1,1.
 CBEAM, 733,403, 92, 93,0,1,1.
 CBEAM, 734,403, 95, 98,0,1,1.
 CBEAM, 735,403, 93, 100,0,1,1.
 CBEAM, 736,403, 98, 103,0,1,1.
 CBEAM, 737,403, 100, 101,0,1,1.
 CBEAM, 738,403, 103, 106,0,1,1.
 CBEAM, 739,403, 101, 108,0,1,1.
 CBEAM, 740,403, 106, 111,0,1,1.
 CBEAM, 741,403, 108, 109,0,1,1.
 CBEAM, 742,403, 111, 114,0,1,1.
 CBEAM, 743,403, 109, 116,0,1,1.
 CBEAM, 744,403, 114, 119,0,1,1.
 CBEAM, 745,403, 116, 117,0,1,1.
 CBEAM, 746,403, 119, 122,0,1,1.
 CBEAM, 747,403, 117, 124,0,1,1.
 CBEAM, 748,403, 122, 127,0,1,1.
 CBEAM, 749,403, 124, 125,0,1,1.
 CBEAM, 750,403, 127, 130,0,1,1.
 CBEAM, 751,403, 125, 132,0,1,1.
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 CBEAM, 756,403, 138, 143,0,1,1.
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 CBEAM, 773,403, 172, 173,0,1,1.
 CBEAM, 774,403, 175, 178,0,1,1.
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 CBEAM, 776,403, 178, 183,0,1,1.
 CBEAM, 777,403, 180, 181,0,1,1.
 CBEAM, 778,403, 183, 186,0,1,1.
 CBEAM, 779,403, 181, 188,0,1,1.
 CBEAM, 780,403, 186, 191,0,1,1.
 CBEAM, 781,403, 188, 189,0,1,1.
 CBEAM, 782,403, 191, 194,0,1,1.
 CBEAM, 783,403, 189, 196,0,1,1.
 CBEAM, 784,403, 194, 199,0,1,1.
 CBEAM, 785,403, 196, 197,0,1,1.

CBEAM, 786,403, 199, 202,0,1,1.
 CBEAM, 787,403, 197, 204,0,1,1.
 CBEAM, 788,403, 202, 207,0,1,1.
 CBEAM, 789,403, 204, 205,0,1,1.
 CBEAM, 790,403, 207, 210,0,1,1.
 CBEAM, 791,403, 205, 212,0,1,1.
 CBEAM, 792,403, 210, 215,0,1,1.
 CBEAM, 793,403, 212, 213,0,1,1.
 CBEAM, 794,403, 215, 218,0,1,1.
 CBEAM, 795,403, 213, 220,0,1,1.
 CBEAM, 796,403, 218, 223,0,1,1.
 CBEAM, 797,403, 220, 221,0,1,1.
 CBEAM, 798,403, 223, 226,0,1,1.
 CBEAM, 799,403, 221, 228,0,1,1.
 CBEAM, 800,403, 226, 231,0,1,1.
 CBEAM, 801,403, 228, 229,0,1,1.
 CBEAM, 802,403, 231, 234,0,1,1.
 CBEAM, 803,403, 229, 236,0,1,1.
 CBEAM, 804,403, 234, 239,0,1,1.
 CBEAM, 805,403, 236, 237,0,1,1.
 CBEAM, 806,403, 239, 242,0,1,1.
 CBEAM, 807,403, 237, 244,0,1,1.
 CBEAM, 808,403, 242, 247,0,1,1.
 CBEAM, 809,403, 244, 245,0,1,1.
 CBEAM, 810,403, 247, 250,0,1,1.
 CBEAM, 811,403, 245, 252,0,1,1.
 \$ TOWER TRUSS, LONGERONS, PID 301
 CBEAM, 812,301, 61, 269,1,1,0.
 CBEAM, 813,301, 62, 270,1,1,0.
 CBEAM, 814,301, 66, 271,1,1,0.
 CBEAM, 815,301, 65, 272,1,1,0.
 CBEAM, 816,301, 269, 273,1,1,0.
 CBEAM, 817,301, 270, 274,1,1,0.
 CBEAM, 818,301, 271, 275,1,1,0.
 CBEAM, 819,301, 272, 276,1,1,0.
 CBEAM, 820,301, 273, 277,1,1,0.
 CBEAM, 821,301, 274, 278,1,1,0.
 CBEAM, 822,301, 275, 279,1,1,0.
 CBEAM, 823,301, 276, 280,1,1,0.
 CBEAM, 824,301, 277, 281,1,1,0.
 CBEAM, 825,301, 278, 282,1,1,0.
 CBEAM, 826,301, 279, 283,1,1,0.
 CBEAM, 827,301, 280, 284,1,1,0.
 CBEAM, 828,301, 281, 285,1,1,0.
 CBEAM, 829,301, 282, 286,1,1,0.
 CBEAM, 830,301, 283, 287,1,1,0.
 CBEAM, 831,301, 284, 288,1,1,0.
 CBEAM, 832,301, 285, 289,1,1,0.
 CBEAM, 833,301, 286, 290,1,1,0.
 CBEAM, 834,301, 287, 291,1,1,0.
 CBEAM, 835,301, 288, 292,1,1,0.
 CBEAM, 836,301, 289, 293,1,1,0.
 CBEAM, 837,301, 290, 294,1,1,0.
 CBEAM, 838,301, 291, 295,1,1,0.
 CBEAM, 839,301, 292, 296,1,1,0.
 CBEAM, 840,301, 293, 297,1,1,0.
 CBEAM, 841,301, 294, 298,1,1,0.
 CBEAM, 842,301, 295, 299,1,1,0.
 CBEAM, 843,301, 296, 300,1,1,0.
 CBEAM, 844,301, 297, 301,1,1,0.
 CBEAM, 845,301, 298, 302,1,1,0.
 CBEAM, 846,301, 299, 303,1,1,0.
 CBEAM, 847,301, 300, 304,1,1,0.
 CBEAM, 848,301, 301, 305,1,1,0.

CBEAM, 849,301, 302, 306,1,1,0.
 CBEAM, 850,301, 303, 307,1,1,0.
 CBEAM, 851,301, 304, 308,1,1,0.
 CBEAM, 852,301, 305, 309,1,1,0.
 CBEAM, 853,301, 306, 310,1,1,0.
 CBEAM, 854,301, 307, 311,1,1,0.
 CBEAM, 855,301, 308, 312,1,1,0.
 \$ TOWER TRUSS, BATTENS, PID 302
 CBEAM, 856,302, 269, 270,1,0,1.
 CBEAM, 857,302, 270, 271,1,0,1.
 CBEAM, 858,302, 271, 272,1,0,1.
 CBEAM, 859,302, 272, 269,1,0,1.
 CBEAM, 860,302, 273, 274,1,0,1.
 CBEAM, 861,302, 274, 275,1,0,1.
 CBEAM, 862,302, 275, 276,1,0,1.
 CBEAM, 863,302, 276, 273,1,0,1.
 CBEAM, 864,302, 277, 278,1,0,1.
 CBEAM, 865,302, 278, 279,1,0,1.
 CBEAM, 866,302, 279, 280,1,0,1.
 CBEAM, 867,302, 280, 277,1,0,1.
 CBEAM, 868,302, 281, 282,1,0,1.
 CBEAM, 869,302, 282, 283,1,0,1.
 CBEAM, 870,302, 283, 284,1,0,1.
 CBEAM, 871,302, 284, 281,1,0,1.
 CBEAM, 872,302, 285, 286,1,0,1.
 CBEAM, 873,302, 286, 287,1,0,1.
 CBEAM, 874,302, 287, 288,1,0,1.
 CBEAM, 875,302, 288, 285,1,0,1.
 CBEAM, 876,302, 289, 290,1,0,1.
 CBEAM, 877,302, 290, 291,1,0,1.
 CBEAM, 878,302, 291, 292,1,0,1.
 CBEAM, 879,302, 292, 289,1,0,1.
 CBEAM, 880,302, 293, 294,1,0,1.
 CBEAM, 881,302, 294, 295,1,0,1.
 CBEAM, 882,302, 295, 296,1,0,1.
 CBEAM, 883,302, 296, 293,1,0,1.
 CBEAM, 884,302, 297, 298,1,0,1.
 CBEAM, 885,302, 298, 299,1,0,1.
 CBEAM, 886,302, 299, 300,1,0,1.
 CBEAM, 887,302, 300, 297,1,0,1.
 CBEAM, 888,302, 301, 302,1,0,1.
 CBEAM, 889,302, 302, 303,1,0,1.
 CBEAM, 890,302, 303, 304,1,0,1.
 CBEAM, 891,302, 304, 301,1,0,1.
 CBEAM, 892,302, 305, 306,1,0,1.
 CBEAM, 893,302, 306, 307,1,0,1.
 CBEAM, 894,302, 307, 308,1,0,1.
 CBEAM, 895,302, 308, 305,1,0,1.
 CBEAM, 896,302, 309, 310,1,0,1.
 CBEAM, 897,302, 310, 311,1,0,1.
 CBEAM, 898,302, 311, 312,1,0,1.
 CBEAM, 899,302, 312, 309,1,0,1.
 \$ TOWER TRUSS, BATTEN DIAGONALS, PID 303
 CBEAM, 900,303, 270, 272,1,0,1.
 CBEAM, 901,303, 273, 275,1,0,1.
 CBEAM, 902,303, 278, 280,1,0,1.
 CBEAM, 903,303, 281, 283,1,0,1.
 CBEAM, 904,303, 286, 288,1,0,1.
 CBEAM, 905,303, 289, 291,1,0,1.
 CBEAM, 906,303, 294, 296,1,0,1.
 CBEAM, 907,303, 297, 299,1,0,1.
 CBEAM, 908,303, 302, 304,1,0,1.
 CBEAM, 909,303, 305, 307,1,0,1.

\$ TOWER TRUSS, FRONT AND BACK
DIAGONALS, PID 303

CBEAM, 911,303, 61, 272,0.,1.,1.
CBEAM, 912,303, 66, 270,0.,1.,1.
CBEAM, 913,303, 270, 275,0.,1.,1.
CBEAM, 914,303, 272, 273,0.,1.,1.
CBEAM, 915,303, 275, 278,0.,1.,1.
CBEAM, 916,303, 273, 280,0.,1.,1.
CBEAM, 917,303, 278, 283,0.,1.,1.
CBEAM, 918,303, 280, 281,0.,1.,1.
CBEAM, 919,303, 283, 286,0.,1.,1.
CBEAM, 920,303, 281, 288,0.,1.,1.
CBEAM, 921,303, 286, 291,0.,1.,1.
CBEAM, 922,303, 288, 289,0.,1.,1.
CBEAM, 923,303, 291, 294,0.,1.,1.
CBEAM, 924,303, 289, 296,0.,1.,1.
CBEAM, 925,303, 294, 299,0.,1.,1.
CBEAM, 926,303, 296, 297,0.,1.,1.
CBEAM, 927,303, 299, 302,0.,1.,1.
CBEAM, 928,303, 297, 304,0.,1.,1.

\$ BAY BREAK FOR THRUSTER

CBEAM, 931,303, 307, 310,0.,1.,1.
CBEAM, 932,303, 305, 312,0.,1.,1.

\$ TOWER TRUSS, SIDE DIAGONALS, PID 303

CBEAM, 933,303, 62, 269,1.,0.,1.
CBEAM, 934,303, 65, 271,1.,0.,1.
CBEAM, 935,303, 269, 274,1.,0.,1.
CBEAM, 936,303, 271, 276,1.,0.,1.
CBEAM, 937,303, 274, 277,1.,0.,1.
CBEAM, 938,303, 276, 279,1.,0.,1.
CBEAM, 939,303, 277, 282,1.,0.,1.
CBEAM, 940,303, 279, 284,1.,0.,1.
CBEAM, 941,303, 282, 285,1.,0.,1.
CBEAM, 942,303, 284, 287,1.,0.,1.
CBEAM, 943,303, 285, 290,1.,0.,1.
CBEAM, 944,303, 287, 292,1.,0.,1.
CBEAM, 945,303, 290, 293,1.,0.,1.
CBEAM, 946,303, 292, 295,1.,0.,1.
CBEAM, 947,303, 293, 298,1.,0.,1.
CBEAM, 948,303, 295, 300,1.,0.,1.
CBEAM, 949,303, 298, 301,1.,0.,1.
CBEAM, 950,303, 300, 303,1.,0.,1.

\$ BAY BREAK FOR THRUSTER

CBEAM, 953,303, 306, 309,1.,0.,1.
CBEAM, 954,303, 308, 311,1.,0.,1.

\$ REFLECTOR TRUSS, LONGERONS, PID 201

CBEAM, 955,201, 245, 253,1.,1.,0.
CBEAM, 956,201, 246, 254,1.,1.,0.
CBEAM, 957,201, 250, 255,1.,1.,0.
CBEAM, 958,201, 249, 256,1.,1.,0.
CBEAM, 959,201, 253, 257,1.,1.,0.
CBEAM, 960,201, 254, 258,1.,1.,0.
CBEAM, 961,201, 255, 259,1.,1.,0.
CBEAM, 962,201, 256, 260,1.,1.,0.
CBEAM, 963,201, 257, 261,1.,1.,0.
CBEAM, 964,201, 258, 262,1.,1.,0.
CBEAM, 965,201, 259, 263,1.,1.,0.
CBEAM, 966,201, 260, 264,1.,1.,0.
CBEAM, 967,201, 261, 265,1.,1.,0.
CBEAM, 968,201, 262, 266,1.,1.,0.
CBEAM, 969,201, 263, 267,1.,1.,0.
CBEAM, 970,201, 264, 268,1.,1.,0.

\$ REFLECTOR TRUSS, BATTENS, PID 202

CBEAM, 971,202, 253, 254,1.,0.,1.

CBEAM, 972,202, 254, 255,1.,0.,1.
CBEAM, 973,202, 255, 256,1.,0.,1.
CBEAM, 974,202, 256, 253,1.,0.,1.
CBEAM, 975,202, 257, 258,1.,0.,1.
CBEAM, 976,202, 258, 259,1.,0.,1.
CBEAM, 977,202, 259, 260,1.,0.,1.
CBEAM, 978,202, 260, 257,1.,0.,1.
CBEAM, 979,202, 261, 262,1.,0.,1.
CBEAM, 980,202, 262, 263,1.,0.,1.
CBEAM, 981,202, 263, 264,1.,0.,1.
CBEAM, 982,202, 264, 261,1.,0.,1.
CBEAM, 983,202, 265, 266,1.,0.,1.
CBEAM, 984,202, 266, 267,1.,0.,1.
CBEAM, 985,202, 267, 268,1.,0.,1.
CBEAM, 986,202, 268, 265,1.,0.,1.

\$ REFLECTOR TRUSS, BATTEN DIAGONALS,
PID 203

CBEAM, 987,203, 253, 255,1.,0.,1.
CBEAM, 988,203, 258, 260,1.,0.,1.
CBEAM, 989,203, 261, 263,1.,0.,1.
CBEAM, 990,203, 266, 268,1.,0.,1.

\$ REFLECTOR TRUSS, SIDE DIAGONALS, PID 203

CBEAM, 991,203, 245, 256,0.,1.,1.
CBEAM, 992,203, 250, 254,0.,1.,1.
CBEAM, 993,203, 256, 257,0.,1.,1.
CBEAM, 994,203, 254, 259,0.,1.,1.
CBEAM, 995,203, 257, 264,0.,1.,1.
CBEAM, 996,203, 259, 262,0.,1.,1.

\$ REFLECTOR TRUSS, FRONT AND BACK
DIAGONALS, PID 203

CBEAM, 999,203, 246, 253,1.,0.,1.
CBEAM, 1000,203, 249, 255,1.,0.,1.
CBEAM, 1001,203, 253, 258,1.,0.,1.
CBEAM, 1002,203, 255, 260,1.,0.,1.
CBEAM, 1003,203, 258, 261,1.,0.,1.
CBEAM, 1004,203, 260, 263,1.,0.,1.

\$ FRONT SUSPENSION TRUSS, LONGERONS, +Y,
PID 201

CBEAM, 1007,201, 49, 313,1.,0.,1.
CBEAM, 1008,201, 53, 314,1.,0.,1.
CBEAM, 1009,201, 56, 315,1.,0.,1.
CBEAM, 1010,201, 52, 316,1.,0.,1.
CBEAM, 1011,201, 313, 321,1.,0.,1.
CBEAM, 1012,201, 314, 322,1.,0.,1.
CBEAM, 1013,201, 315, 323,1.,0.,1.
CBEAM, 1014,201, 316, 324,1.,0.,1.
CBEAM, 1015,201, 321, 329,1.,0.,1.
CBEAM, 1016,201, 322, 330,1.,0.,1.
CBEAM, 1017,201, 323, 331,1.,0.,1.
CBEAM, 1018,201, 324, 332,1.,0.,1.
CBEAM, 1019,201, 329, 337,1.,0.,1.
CBEAM, 1020,201, 330, 338,1.,0.,1.
CBEAM, 1021,201, 331, 339,1.,0.,1.
CBEAM, 1022,201, 332, 340,1.,0.,1.
CBEAM, 1023,201, 337, 345,1.,0.,1.
CBEAM, 1024,201, 338, 346,1.,0.,1.
CBEAM, 1025,201, 339, 347,1.,0.,1.
CBEAM, 1026,201, 340, 348,1.,0.,1.
CBEAM, 1027,201, 57, 353,1.,0.,1.
CBEAM, 1028,201, 60, 354,1.,0.,1.
CBEAM, 1029,201, 353, 357,1.,0.,1.
CBEAM, 1030,201, 354, 358,1.,0.,1.
CBEAM, 1031,201, 357, 361,1.,0.,1.
CBEAM, 1032,201, 358, 362,1.,0.,1.

CBEAM, 1033,201, 361, 365,1.,0.,1.
 CBEAM, 1034,201, 362, 366,1.,0.,1.
 CBEAM, 1035,201, 365, 369,1.,0.,1.
 CBEAM, 1036,201, 366, 370,1.,0.,1.
 \$ FRONT SUSPENSION TRUSS, LONGERONS, -Y,
 PID 201

CBEAM, 1037,201, 58, 355,1.,0.,1.
 CBEAM, 1038,201, 59, 356,1.,0.,1.
 CBEAM, 1039,201, 355, 359,1.,0.,1.
 CBEAM, 1040,201, 356, 360,1.,0.,1.
 CBEAM, 1041,201, 359, 363,1.,0.,1.
 CBEAM, 1042,201, 360, 364,1.,0.,1.
 CBEAM, 1043,201, 363, 367,1.,0.,1.
 CBEAM, 1044,201, 364, 368,1.,0.,1.
 CBEAM, 1045,201, 367, 371,1.,0.,1.
 CBEAM, 1046,201, 368, 372,1.,0.,1.
 CBEAM, 1047,201, 50, 317,1.,0.,1.
 CBEAM, 1048,201, 54, 318,1.,0.,1.
 CBEAM, 1049,201, 55, 319,1.,0.,1.
 CBEAM, 1050,201, 51, 320,1.,0.,1.
 CBEAM, 1051,201, 317, 325,1.,0.,1.
 CBEAM, 1052,201, 318, 326,1.,0.,1.
 CBEAM, 1053,201, 319, 327,1.,0.,1.
 CBEAM, 1054,201, 320, 328,1.,0.,1.
 CBEAM, 1055,201, 325, 333,1.,0.,1.
 CBEAM, 1056,201, 326, 334,1.,0.,1.
 CBEAM, 1057,201, 327, 335,1.,0.,1.
 CBEAM, 1058,201, 328, 336,1.,0.,1.
 CBEAM, 1059,201, 333, 341,1.,0.,1.
 CBEAM, 1060,201, 334, 342,1.,0.,1.
 CBEAM, 1061,201, 335, 343,1.,0.,1.
 CBEAM, 1062,201, 336, 344,1.,0.,1.
 CBEAM, 1063,201, 341, 349,1.,0.,1.
 CBEAM, 1064,201, 342, 350,1.,0.,1.
 CBEAM, 1065,201, 343, 351,1.,0.,1.
 CBEAM, 1066,201, 344, 352,1.,0.,1.
 \$ FRONT SUSPENSION TRUSS, BATTENS, +Y,
 PID 202

CBEAM, 1072,202, 314, 353,0.,1.,1.
 CBEAM, 1073,202, 353, 354,0.,1.,1.
 CBEAM, 1074,202, 354, 315,0.,1.,1.
 CBEAM, 1075,202, 322, 357,0.,1.,1.
 CBEAM, 1076,202, 357, 358,0.,1.,1.
 CBEAM, 1077,202, 358, 323,0.,1.,1.
 CBEAM, 1078,202, 330, 361,0.,1.,1.
 CBEAM, 1079,202, 361, 362,0.,1.,1.
 CBEAM, 1080,202, 362, 331,0.,1.,1.
 CBEAM, 1081,202, 338, 365,0.,1.,1.
 CBEAM, 1082,202, 365, 366,0.,1.,1.
 CBEAM, 1083,202, 366, 339,0.,1.,1.
 CBEAM, 1084,202, 346, 369,0.,1.,1.
 CBEAM, 1085,202, 369, 370,0.,1.,1.
 CBEAM, 1086,202, 370, 347,0.,1.,1.
 \$ NEW
 CBEAM, 1087,202, 313, 314,0.,1.,1.
 CBEAM, 1088,202, 314, 315,0.,1.,1.
 CBEAM, 1089,202, 315, 316,0.,1.,1.
 CBEAM, 1090,202, 316, 313,0.,1.,1.
 CBEAM, 1091,202, 321, 322,0.,1.,1.
 CBEAM, 1092,202, 322, 323,0.,1.,1.
 CBEAM, 1093,202, 323, 324,0.,1.,1.
 CBEAM, 1094,202, 324, 321,0.,1.,1.
 CBEAM, 1095,202, 329, 330,0.,1.,1.
 CBEAM, 1096,202, 330, 331,0.,1.,1.

CBEAM, 1097,202, 331, 332,0.,1.,1.
 CBEAM, 1098,202, 332, 329,0.,1.,1.
 CBEAM, 1099,202, 337, 338,0.,1.,1.
 CBEAM, 1100,202, 338, 339,0.,1.,1.
 CBEAM, 1101,202, 339, 340,0.,1.,1.
 CBEAM, 1102,202, 340, 337,0.,1.,1.
 CBEAM, 1103,202, 345, 346,0.,1.,1.
 CBEAM, 1104,202, 346, 347,0.,1.,1.
 CBEAM, 1105,202, 347, 348,0.,1.,1.
 CBEAM, 1106,202, 348, 345,0.,1.,1.
 \$ FRONT SUSPENSION TRUSS, BATTENS, -Y,
 PID 202

CBEAM, 1112,202, 318, 355,0.,1.,1.
 CBEAM, 1113,202, 355, 356,0.,1.,1.
 CBEAM, 1114,202, 356, 319,0.,1.,1.
 CBEAM, 1115,202, 326, 359,0.,1.,1.
 CBEAM, 1116,202, 359, 360,0.,1.,1.
 CBEAM, 1117,202, 360, 327,0.,1.,1.
 CBEAM, 1118,202, 334, 363,0.,1.,1.
 CBEAM, 1119,202, 363, 364,0.,1.,1.
 CBEAM, 1120,202, 364, 335,0.,1.,1.
 CBEAM, 1121,202, 342, 367,0.,1.,1.
 CBEAM, 1122,202, 367, 368,0.,1.,1.
 CBEAM, 1123,202, 368, 343,0.,1.,1.
 CBEAM, 1124,202, 350, 371,0.,1.,1.
 CBEAM, 1125,202, 371, 372,0.,1.,1.
 CBEAM, 1126,202, 372, 351,0.,1.,1.
 CBEAM, 1127,202, 317, 318,0.,1.,1.
 CBEAM, 1128,202, 318, 319,0.,1.,1.
 CBEAM, 1129,202, 319, 320,0.,1.,1.
 CBEAM, 1130,202, 320, 317,0.,1.,1.
 CBEAM, 1131,202, 325, 326,0.,1.,1.
 CBEAM, 1132,202, 326, 327,0.,1.,1.
 CBEAM, 1133,202, 327, 328,0.,1.,1.
 CBEAM, 1134,202, 328, 325,0.,1.,1.
 CBEAM, 1135,202, 333, 334,0.,1.,1.
 CBEAM, 1136,202, 334, 335,0.,1.,1.
 CBEAM, 1137,202, 335, 336,0.,1.,1.
 CBEAM, 1138,202, 336, 333,0.,1.,1.
 CBEAM, 1139,202, 341, 342,0.,1.,1.
 CBEAM, 1140,202, 342, 343,0.,1.,1.
 CBEAM, 1141,202, 343, 344,0.,1.,1.
 CBEAM, 1142,202, 344, 341,0.,1.,1.
 CBEAM, 1143,202, 349, 350,0.,1.,1.
 CBEAM, 1144,202, 350, 351,0.,1.,1.
 CBEAM, 1145,202, 351, 352,0.,1.,1.
 CBEAM, 1146,202, 352, 349,0.,1.,1.
 \$ FRONT SUSPENSION TRUSS, BATTEN
 DIAGONALS, +Y, PID 203
 CBEAM, 1167,203, 313, 315,0.,1.,1.
 CBEAM, 1168,203, 322, 324,0.,1.,1.
 CBEAM, 1169,203, 329, 331,0.,1.,1.
 CBEAM, 1170,203, 338, 340,0.,1.,1.
 CBEAM, 1171,203, 345, 347,0.,1.,1.
 CBEAM, 1172,203, 353, 315,0.,1.,1.
 CBEAM, 1173,203, 322, 358,0.,1.,1.
 CBEAM, 1174,203, 361, 331,0.,1.,1.
 CBEAM, 1175,203, 338, 366,0.,1.,1.
 CBEAM, 1176,203, 369, 347,0.,1.,1.
 \$ FRONT SUSPENSION TRUSS, BATTEN
 DIAGONALS, -Y, PID 203
 CBEAM, 1177,203, 318, 320,0.,1.,1.
 CBEAM, 1178,203, 327, 325,0.,1.,1.
 CBEAM, 1179,203, 334, 336,0.,1.,1.

CBEAM, 1180,203, 341, 343,0.,1.,1.
 CBEAM, 1181,203, 350, 352,0.,1.,1.
 CBEAM, 1182,203, 318, 356,0.,1.,1.
 CBEAM, 1183,203, 327, 359,0.,1.,1.
 CBEAM, 1184,203, 334, 364,0.,1.,1.
 CBEAM, 1185,203, 367, 343,0.,1.,1.
 CBEAM, 1186,203, 350, 372,0.,1.,1.
 \$ FRONT SUSPENSION TRUSS, FRONT AND BACK
 DIAGONALS, +Y, PID 203
 CBEAM, 1187,203, 49, 316,1.,0.,1.
 CBEAM, 1188,203, 56, 314,1.,0.,1.
 CBEAM, 1189,203, 316, 321,1.,0.,1.
 CBEAM, 1190,203, 314, 323,1.,0.,1.
 CBEAM, 1191,203, 321, 332,1.,0.,1.
 CBEAM, 1192,203, 323, 330,1.,0.,1.
 CBEAM, 1193,203, 332, 337,1.,0.,1.
 CBEAM, 1194,203, 330, 339,1.,0.,1.
 CBEAM, 1195,203, 337, 348,1.,0.,1.
 CBEAM, 1196,203, 339, 346,1.,0.,1.
 CBEAM, 1197,203, 57, 354,1.,0.,1.
 CBEAM, 1198,203, 354, 357,1.,0.,1.
 CBEAM, 1199,203, 357, 362,1.,0.,1.
 CBEAM, 1200,203, 362, 365,1.,0.,1.
 CBEAM, 1201,203, 365, 370,1.,0.,1.
 \$ FRONT SUSPENSION TRUSS, FRONT AND BACK
 DIAGONALS, -Y, PID 203
 CBEAM, 1207,203, 51, 317,1.,0.,1.
 CBEAM, 1208,203, 54, 319,1.,0.,1.
 CBEAM, 1209,203, 317, 328,1.,0.,1.
 CBEAM, 1210,203, 319, 326,1.,0.,1.
 CBEAM, 1211,203, 328, 333,1.,0.,1.
 CBEAM, 1212,203, 326, 335,1.,0.,1.
 CBEAM, 1213,203, 333, 344,1.,0.,1.
 CBEAM, 1214,203, 335, 342,1.,0.,1.
 CBEAM, 1215,203, 344, 349,1.,0.,1.
 CBEAM, 1216,203, 342, 351,1.,0.,1.
 CBEAM, 1217,203, 59, 355,1.,0.,1.
 CBEAM, 1218,203, 355, 360,1.,0.,1.
 CBEAM, 1219,203, 360, 363,1.,0.,1.
 CBEAM, 1220,203, 363, 368,1.,0.,1.
 CBEAM, 1221,203, 368, 371,1.,0.,1.
 \$ FRONT SUSPENSION TRUSS, TOP AND BOTTOM
 DIAGONALS, +Y, PID 203
 CBEAM, 1227,203, 49, 314,1.,0.,1.
 CBEAM, 1228,203, 56, 316,1.,0.,1.
 CBEAM, 1229,203, 314, 321,1.,0.,1.
 CBEAM, 1230,203, 316, 323,1.,0.,1.
 CBEAM, 1231,203, 321, 330,1.,0.,1.
 CBEAM, 1232,203, 323, 332,1.,0.,1.
 CBEAM, 1233,203, 330, 337,1.,0.,1.
 CBEAM, 1234,203, 332, 339,1.,0.,1.
 CBEAM, 1235,203, 337, 346,1.,0.,1.
 CBEAM, 1236,203, 339, 348,1.,0.,1.
 CBEAM, 1237,203, 57, 314,1.,0.,1.
 CBEAM, 1238,203, 56, 354,1.,0.,1.
 CBEAM, 1239,203, 314, 357,1.,0.,1.
 CBEAM, 1240,203, 354, 323,1.,0.,1.
 CBEAM, 1241,203, 357, 330,1.,0.,1.
 CBEAM, 1242,203, 323, 362,1.,0.,1.
 CBEAM, 1243,203, 330, 365,1.,0.,1.
 CBEAM, 1244,203, 362, 339,1.,0.,1.
 CBEAM, 1245,203, 365, 346,1.,0.,1.
 CBEAM, 1246,203, 339, 370,1.,0.,1.

\$ FRONT SUSPENSION TRUSS, TOP AND BOTTOM
 DIAGONALS, -Y, PID 203
 CBEAM, 1247,203, 54, 317,1.,0.,1.
 CBEAM, 1248,203, 51, 319,1.,0.,1.
 CBEAM, 1249,203, 317, 326,1.,0.,1.
 CBEAM, 1250,203, 319, 328,1.,0.,1.
 CBEAM, 1251,203, 326, 333,1.,0.,1.
 CBEAM, 1252,203, 328, 335,1.,0.,1.
 CBEAM, 1253,203, 333, 342,1.,0.,1.
 CBEAM, 1254,203, 335, 344,1.,0.,1.
 CBEAM, 1255,203, 342, 349,1.,0.,1.
 CBEAM, 1256,203, 344, 351,1.,0.,1.
 CBEAM, 1257,203, 54, 355,1.,0.,1.
 CBEAM, 1258,203, 59, 319,1.,0.,1.
 CBEAM, 1259,203, 355, 326,1.,0.,1.
 CBEAM, 1260,203, 319, 360,1.,0.,1.
 CBEAM, 1261,203, 326, 363,1.,0.,1.
 CBEAM, 1262,203, 360, 335,1.,0.,1.
 CBEAM, 1263,203, 363, 342,1.,0.,1.
 CBEAM, 1264,203, 335, 368,1.,0.,1.
 CBEAM, 1265,203, 342, 371,1.,0.,1.
 CBEAM, 1266,203, 368, 351,1.,0.,1.
 \$ START AFT SUSPENSION TRUSS
 \$ BACK SUSPENSION TRUSS, LONGERONS, +Y,
 PID 201
 CBEAM, 1267,201, 221, 397,1.,0.,1.
 CBEAM, 1268,201, 225, 398,1.,0.,1.
 CBEAM, 1269,201, 228, 399,1.,0.,1.
 CBEAM, 1270,201, 224, 400,1.,0.,1.
 CBEAM, 1271,201, 397, 405,1.,0.,1.
 CBEAM, 1272,201, 398, 406,1.,0.,1.
 CBEAM, 1273,201, 399, 407,1.,0.,1.
 CBEAM, 1274,201, 400, 408,1.,0.,1.
 CBEAM, 1275,201, 405, 413,1.,0.,1.
 CBEAM, 1276,201, 406, 414,1.,0.,1.
 CBEAM, 1277,201, 407, 415,1.,0.,1.
 CBEAM, 1278,201, 408, 416,1.,0.,1.
 CBEAM, 1279,201, 413, 421,1.,0.,1.
 CBEAM, 1280,201, 414, 422,1.,0.,1.
 CBEAM, 1281,201, 415, 423,1.,0.,1.
 CBEAM, 1282,201, 416, 424,1.,0.,1.
 CBEAM, 1283,201, 421, 429,1.,0.,1.
 CBEAM, 1284,201, 422, 430,1.,0.,1.
 CBEAM, 1285,201, 423, 431,1.,0.,1.
 CBEAM, 1286,201, 424, 432,1.,0.,1.
 CBEAM, 1287,201, 217, 437,1.,0.,1.
 CBEAM, 1288,201, 220, 438,1.,0.,1.
 CBEAM, 1289,201, 437, 441,1.,0.,1.
 CBEAM, 1290,201, 438, 442,1.,0.,1.
 CBEAM, 1291,201, 441, 445,1.,0.,1.
 CBEAM, 1292,201, 442, 446,1.,0.,1.
 CBEAM, 1293,201, 445, 449,1.,0.,1.
 CBEAM, 1294,201, 446, 450,1.,0.,1.
 CBEAM, 1295,201, 449, 453,1.,0.,1.
 CBEAM, 1296,201, 450, 454,1.,0.,1.
 \$ BACK SUSPENSION TRUSS, LONGERONS, -Y,
 PID 201
 CBEAM, 1307,201, 222, 401,1.,0.,1.
 CBEAM, 1308,201, 226, 402,1.,0.,1.
 CBEAM, 1309,201, 227, 403,1.,0.,1.
 CBEAM, 1310,201, 223, 404,1.,0.,1.
 CBEAM, 1311,201, 401, 409,1.,0.,1.
 CBEAM, 1312,201, 402, 410,1.,0.,1.
 CBEAM, 1313,201, 403, 411,1.,0.,1.

CBEAM, 1314,201, 404, 412,1.,0.,1.
 CBEAM, 1315,201, 409, 417,1.,0.,1.
 CBEAM, 1316,201, 410, 418,1.,0.,1.
 CBEAM, 1317,201, 411, 419,1.,0.,1.
 CBEAM, 1318,201, 412, 420,1.,0.,1.
 CBEAM, 1319,201, 417, 425,1.,0.,1.
 CBEAM, 1320,201, 418, 426,1.,0.,1.
 CBEAM, 1321,201, 419, 427,1.,0.,1.
 CBEAM, 1322,201, 420, 428,1.,0.,1.
 CBEAM, 1323,201, 425, 433,1.,0.,1.
 CBEAM, 1324,201, 426, 434,1.,0.,1.
 CBEAM, 1325,201, 427, 435,1.,0.,1.
 CBEAM, 1326,201, 428, 436,1.,0.,1.
 CBEAM, 1327,201, 218, 439,1.,0.,1.
 CBEAM, 1328,201, 219, 440,1.,0.,1.
 CBEAM, 1329,201, 439, 443,1.,0.,1.
 CBEAM, 1330,201, 440, 444,1.,0.,1.
 CBEAM, 1331,201, 443, 447,1.,0.,1.
 CBEAM, 1332,201, 444, 448,1.,0.,1.
 CBEAM, 1333,201, 447, 451,1.,0.,1.
 CBEAM, 1334,201, 448, 452,1.,0.,1.
 CBEAM, 1335,201, 451, 455,1.,0.,1.
 CBEAM, 1336,201, 452, 456,1.,0.,1.
 \$ BACK SUSPENSION TRUSS, BATTENS, +Y,
 PID 202
 CBEAM, 1347,202, 397, 398,0.,1.,1.
 CBEAM, 1348,202, 398, 399,0.,1.,1.
 CBEAM, 1349,202, 399, 400,0.,1.,1.
 CBEAM, 1350,202, 400, 397,0.,1.,1.
 CBEAM, 1351,202, 405, 406,0.,1.,1.
 CBEAM, 1352,202, 406, 407,0.,1.,1.
 CBEAM, 1353,202, 407, 408,0.,1.,1.
 CBEAM, 1354,202, 408, 405,0.,1.,1.
 CBEAM, 1355,202, 413, 414,0.,1.,1.
 CBEAM, 1356,202, 414, 415,0.,1.,1.
 CBEAM, 1357,202, 415, 416,0.,1.,1.
 CBEAM, 1358,202, 416, 413,0.,1.,1.
 CBEAM, 1359,202, 421, 422,0.,1.,1.
 CBEAM, 1360,202, 422, 423,0.,1.,1.
 CBEAM, 1361,202, 423, 424,0.,1.,1.
 CBEAM, 1362,202, 424, 421,0.,1.,1.
 CBEAM, 1363,202, 429, 430,0.,1.,1.
 CBEAM, 1364,202, 430, 431,0.,1.,1.
 CBEAM, 1365,202, 431, 432,0.,1.,1.
 CBEAM, 1366,202, 432, 429,0.,1.,1.
 CBEAM, 1367,202, 437, 397,0.,1.,1.
 CBEAM, 1368,202, 400, 438,0.,1.,1.
 CBEAM, 1369,202, 438, 437,0.,1.,1.
 CBEAM, 1370,202, 441, 405,0.,1.,1.
 CBEAM, 1371,202, 408, 442,0.,1.,1.
 CBEAM, 1372,202, 442, 441,0.,1.,1.
 CBEAM, 1373,202, 445, 413,0.,1.,1.
 CBEAM, 1374,202, 416, 446,0.,1.,1.
 CBEAM, 1375,202, 446, 445,0.,1.,1.
 CBEAM, 1376,202, 449, 421,0.,1.,1.
 CBEAM, 1377,202, 424, 450,0.,1.,1.
 CBEAM, 1378,202, 450, 449,0.,1.,1.
 CBEAM, 1379,202, 453, 429,0.,1.,1.
 CBEAM, 1380,202, 432, 454,0.,1.,1.
 CBEAM, 1381,202, 454, 453,0.,1.,1.
 \$ BACK SUSPENSION TRUSS, BATTENS, -Y,
 PID 202
 CBEAM, 1387,202, 401, 402,0.,1.,1.
 CBEAM, 1388,202, 402, 403,0.,1.,1.

CBEAM, 1389,202, 403, 404,0.,1.,1.
 CBEAM, 1390,202, 404, 401,0.,1.,1.
 CBEAM, 1391,202, 409, 410,0.,1.,1.
 CBEAM, 1392,202, 410, 411,0.,1.,1.
 CBEAM, 1393,202, 411, 412,0.,1.,1.
 CBEAM, 1394,202, 412, 409,0.,1.,1.
 CBEAM, 1395,202, 417, 418,0.,1.,1.
 CBEAM, 1396,202, 418, 419,0.,1.,1.
 CBEAM, 1397,202, 419, 420,0.,1.,1.
 CBEAM, 1398,202, 420, 417,0.,1.,1.
 CBEAM, 1399,202, 425, 426,0.,1.,1.
 CBEAM, 1400,202, 426, 427,0.,1.,1.
 CBEAM, 1401,202, 427, 428,0.,1.,1.
 CBEAM, 1402,202, 428, 425,0.,1.,1.
 CBEAM, 1403,202, 433, 434,0.,1.,1.
 CBEAM, 1404,202, 434, 435,0.,1.,1.
 CBEAM, 1405,202, 435, 436,0.,1.,1.
 CBEAM, 1406,202, 436, 433,0.,1.,1.
 CBEAM, 1407,202, 439, 401,0.,1.,1.
 CBEAM, 1408,202, 404, 440,0.,1.,1.
 CBEAM, 1409,202, 440, 439,0.,1.,1.
 CBEAM, 1410,202, 443, 409,0.,1.,1.
 CBEAM, 1411,202, 412, 444,0.,1.,1.
 CBEAM, 1412,202, 444, 443,0.,1.,1.
 CBEAM, 1413,202, 447, 417,0.,1.,1.
 CBEAM, 1414,202, 420, 448,0.,1.,1.
 CBEAM, 1415,202, 448, 447,0.,1.,1.
 CBEAM, 1416,202, 451, 425,0.,1.,1.
 CBEAM, 1417,202, 428, 452,0.,1.,1.
 CBEAM, 1418,202, 452, 451,0.,1.,1.
 CBEAM, 1419,202, 455, 433,0.,1.,1.
 CBEAM, 1420,202, 436, 456,0.,1.,1.
 CBEAM, 1421,202, 456, 455,0.,1.,1.
 \$ BACK SUSPENSION TRUSS, BATTEN
 DIAGONALS, +Y, PID 203
 CBEAM, 1427,203, 398, 400,0.,1.,1.
 CBEAM, 1428,203, 405, 407,0.,1.,1.
 CBEAM, 1429,203, 414, 416,0.,1.,1.
 CBEAM, 1430,203, 421, 423,0.,1.,1.
 CBEAM, 1431,203, 430, 432,0.,1.,1.
 CBEAM, 1432,203, 437, 400,0.,1.,1.
 CBEAM, 1433,203, 405, 442,0.,1.,1.
 CBEAM, 1434,203, 445, 416,0.,1.,1.
 CBEAM, 1435,203, 421, 450,0.,1.,1.
 CBEAM, 1436,203, 453, 432,0.,1.,1.
 \$ BACK SUSPENSION TRUSS, BATTEN
 DIAGONALS, -Y, PID 203
 CBEAM, 1437,203, 401, 403,0.,1.,1.
 CBEAM, 1438,203, 410, 412,0.,1.,1.
 CBEAM, 1439,203, 417, 419,0.,1.,1.
 CBEAM, 1440,203, 426, 428,0.,1.,1.
 CBEAM, 1441,203, 433, 435,0.,1.,1.
 CBEAM, 1442,203, 401, 440,0.,1.,1.
 CBEAM, 1443,203, 443, 412,0.,1.,1.
 CBEAM, 1444,203, 417, 448,0.,1.,1.
 CBEAM, 1445,203, 451, 426,0.,1.,1.
 CBEAM, 1446,203, 433, 456,0.,1.,1.
 \$ BACK SUSPENSION TRUSS, FRONT AND BACK
 DIAGONALS, +Y, PID 203
 CBEAM, 1447,203, 224, 397,1.,0.,1.
 CBEAM, 1448,203, 225, 399,1.,0.,1.
 CBEAM, 1449,203, 397, 408,1.,0.,1.
 CBEAM, 1450,203, 399, 406,1.,0.,1.
 CBEAM, 1451,203, 408, 413,1.,0.,1.

CBEAM, 1452,203, 406, 415,1.,0.,1.
 CBEAM, 1453,203, 413, 424,1.,0.,1.
 CBEAM, 1454,203, 415, 422,1.,0.,1.
 CBEAM, 1455,203, 424, 429,1.,0.,1.
 CBEAM, 1456,203, 422, 431,1.,0.,1.
 CBEAM, 1457,203, 217, 438,1.,0.,1.
 CBEAM, 1458,203, 438, 441,1.,0.,1.
 CBEAM, 1459,203, 441, 446,1.,0.,1.
 CBEAM, 1460,203, 446, 449,1.,0.,1.
 CBEAM, 1461,203, 449, 454,1.,0.,1.
 \$ BACK SUSPENSION TRUSS, FRONT AND BACK
 DIAGONALS, -Y, PID 203
 CBEAM, 1467,203, 222, 404,1.,0.,1.
 CBEAM, 1468,203, 227, 402,1.,0.,1.
 CBEAM, 1469,203, 404, 409,1.,0.,1.
 CBEAM, 1470,203, 402, 411,1.,0.,1.
 CBEAM, 1471,203, 409, 420,1.,0.,1.
 CBEAM, 1472,203, 411, 418,1.,0.,1.
 CBEAM, 1473,203, 420, 425,1.,0.,1.
 CBEAM, 1474,203, 418, 427,1.,0.,1.
 CBEAM, 1475,203, 425, 436,1.,0.,1.
 CBEAM, 1476,203, 427, 434,1.,0.,1.
 CBEAM, 1477,203, 219, 439,1.,0.,1.
 CBEAM, 1478,203, 439, 444,1.,0.,1.
 CBEAM, 1479,203, 444, 447,1.,0.,1.
 CBEAM, 1480,203, 447, 452,1.,0.,1.
 CBEAM, 1481,203, 452, 455,1.,0.,1.
 \$ BACK SUSPENSION TRUSS, TOP AND BOTTOM
 DIAGONALS, +Y, PID 203
 CBEAM, 1487,203, 225, 397,1.,0.,1.
 CBEAM, 1488,203, 224, 399,1.,0.,1.
 CBEAM, 1489,203, 397, 406,1.,0.,1.
 CBEAM, 1490,203, 399, 408,1.,0.,1.
 CBEAM, 1491,203, 406, 413,1.,0.,1.
 CBEAM, 1492,203, 408, 415,1.,0.,1.
 CBEAM, 1493,203, 413, 422,1.,0.,1.
 CBEAM, 1494,203, 415, 424,1.,0.,1.
 CBEAM, 1495,203, 422, 429,1.,0.,1.
 CBEAM, 1496,203, 424, 431,1.,0.,1.
 CBEAM, 1497,203, 217, 397,1.,0.,1.
 CBEAM, 1498,203, 224, 438,1.,0.,1.
 CBEAM, 1499,203, 397, 441,1.,0.,1.
 CBEAM, 1500,203, 438, 408,1.,0.,1.
 CBEAM, 1501,203, 441, 413,1.,0.,1.
 CBEAM, 1502,203, 408, 446,1.,0.,1.
 CBEAM, 1503,203, 413, 449,1.,0.,1.
 CBEAM, 1504,203, 446, 424,1.,0.,1.
 CBEAM, 1505,203, 449, 429,1.,0.,1.
 CBEAM, 1506,203, 424, 454,1.,0.,1.
 \$ BACK SUSPENSION TRUSS, TOP AND BOTTOM
 DIAGONALS, -Y, PID 203
 CBEAM, 1507,203, 222, 402,1.,0.,1.
 CBEAM, 1508,203, 227, 404,1.,0.,1.
 CBEAM, 1509,203, 402, 409,1.,0.,1.
 CBEAM, 1510,203, 404, 411,1.,0.,1.
 CBEAM, 1511,203, 409, 418,1.,0.,1.
 CBEAM, 1512,203, 411, 420,1.,0.,1.
 CBEAM, 1513,203, 418, 425,1.,0.,1.
 CBEAM, 1514,203, 420, 427,1.,0.,1.
 CBEAM, 1515,203, 425, 434,1.,0.,1.
 CBEAM, 1516,203, 427, 436,1.,0.,1.
 CBEAM, 1517,203, 222, 439,1.,0.,1.
 CBEAM, 1518,203, 219, 404,1.,0.,1.
 CBEAM, 1519,203, 439, 409,1.,0.,1.

CBEAM, 1520,203, 404, 444,1.,0.,1.
 CBEAM, 1521,203, 409, 447,1.,0.,1.
 CBEAM, 1522,203, 444, 420,1.,0.,1.
 CBEAM, 1523,203, 447, 425,1.,0.,1.
 CBEAM, 1524,203, 420, 452,1.,0.,1.
 CBEAM, 1525,203, 425, 455,1.,0.,1.
 CBEAM, 1526,203, 452, 436,1.,0.,1.
 \$ START RFL SUPPORT BRACKET BEAMS
 CBEAM, 1531,27, 265, 485,266
 CBEAM, 1532,27, 266, 486,267
 CBEAM, 1533,27, 267, 487,268
 CBEAM, 1534,27, 268, 488,265
 CBEAM, 1535,28, 267, 488,485
 CBEAM, 1536,28, 268, 487,486
 CBEAM, 1537,28, 265, 486,487
 CBEAM, 1538,28, 266, 485,488
 CBEAM, 1539,28, 265, 488,487
 CBEAM, 1540,28, 266, 487,488
 CBEAM, 1541,29, 485, 488,487
 CBEAM, 1542,29, 486, 487,488
 \$ FORWARD SUSPENSION CABLE
 \$.170 KELVAR CABLE, +Y
 CROD, 1551,14, 509, 510
 CROD, 1552,14, 510, 511
 CROD, 1553,14, 511, 512
 CROD, 1554,14, 512, 513
 CROD, 1555,14, 513, 514
 \$ 7X19 .125 STAINLESS STEEL CABLE
 CROD, 1556,13, 514, 515
 CROD, 1557,13, 514, 516
 \$ CABLE STANDOFF
 CBEAM, 1558, 12, 338, 515, 516
 CBEAM, 1559, 12, 346, 516, 515
 \$.170 KELVAR CABLE, -Y
 CROD, 1561,14, 519, 520
 CROD, 1562,14, 520, 521
 CROD, 1563,14, 521, 522
 CROD, 1564,14, 522, 523
 CROD, 1565,14, 523, 524
 \$ 7X19 .125 STAINLESS STEEL CABLE
 CROD, 1566,13, 524, 525
 CROD, 1567,13, 524, 526
 \$ CABLE STANDOFF
 CBEAM, 1568, 12, 342, 525, 526
 CBEAM, 1569, 12, 350, 526, 525
 \$ AFT SUSPENSION CABLE
 \$.170 KELVAR CABLE, +Y
 CROD, 1571,14, 529, 530
 CROD, 1572,14, 530, 531
 CROD, 1573,14, 531, 532
 CROD, 1574,14, 532, 533
 CROD, 1575,14, 533, 534
 \$ 7X19 .125 STAINLESS STEEL CABLE
 CROD, 1576,13, 534, 535
 CROD, 1577,13, 534, 536
 \$ CABLE STANDOFF
 CBEAM, 1578, 12, 421, 535, 536
 CBEAM, 1579, 12, 429, 536, 535
 \$.170 KELVAR CABLE, -Y
 CROD, 1581,14, 539, 540
 CROD, 1582,14, 540, 541
 CROD, 1583,14, 541, 542
 CROD, 1584,14, 542, 543
 CROD, 1585,14, 543, 544

\$ 7X19 .125 STAINLESS STEEL CABLE

CROD, 1586,13, 544, 545

CROD, 1587,13, 544, 546

\$ CABLE STANDOFF

CBEAM, 1588, 12, 425, 545, 546

CBEAM, 1589, 12, 433, 546, 545

\$ START GIMBAL#1

\$ GIMBAL#1 SUPPORT BEAMS

CBEAM	1601	502	49	550	-0.707	0.707
CBEAM	1602	502	49	562	0.707	-0.707
CBEAM	1603	502	53	550	-0.707	-0.707
CBEAM	1604	502	53	554	0.707	0.707
CBEAM	1605	502	54	554	-0.707	0.707
CBEAM	1606	502	54	558	0.707	-0.707
CBEAM	1607	502	50	558	0.707	0.707
CBEAM	1608	502	50	562	-0.707	-0.707

\$ 1/2" X 1" RINGS

CBEAM	1609	4	566	568	-0.195	-0.981
CBEAM	1610	4	568	570	-0.556	-0.831
CBEAM	1611	4	570	572	-0.831	-0.556
CBEAM	1612	4	572	574	-0.981	-0.195
CBEAM	1613	4	574	576	-0.981	0.195
CBEAM	1614	4	576	578	-0.831	0.556
CBEAM	1615	4	578	580	-0.556	0.831
CBEAM	1616	4	580	582	-0.195	0.981
CBEAM	1617	4	582	584	0.195	0.981
CBEAM	1618	4	584	586	0.556	0.831
CBEAM	1619	4	586	588	0.831	0.556
CBEAM	1620	4	588	590	0.981	0.195
CBEAM	1621	4	590	592	0.981	-0.195
CBEAM	1622	4	592	594	0.831	-0.556
CBEAM	1623	4	594	596	0.556	-0.831
CBEAM	1624	4	596	566	0.195	-0.981
CBEAM	1625	4	567	569	-0.195	-0.981
CBEAM	1626	4	569	571	-0.555	-0.832
CBEAM	1627	4	571	573	-0.832	-0.555
CBEAM	1628	4	573	575	-0.981	-0.195
CBEAM	1629	4	575	577	-0.981	0.195
CBEAM	1630	4	577	579	-0.832	0.555
CBEAM	1631	4	579	581	-0.555	0.832
CBEAM	1632	4	581	583	-0.195	0.981
CBEAM	1633	4	583	585	0.195	0.981
CBEAM	1634	4	585	587	0.555	0.832
CBEAM	1635	4	587	589	0.832	0.555
CBEAM	1636	4	589	591	0.981	0.195
CBEAM	1637	4	591	593	0.981	-0.195
CBEAM	1638	4	593	595	0.832	-0.555
CBEAM	1639	4	595	597	0.555	-0.832
CBEAM	1640	4	597	567	0.195	-0.981
CBEAM	1641	4	566	567	1.0	
CBEAM	1642	4	582	583	-1.0	
CBEAM	1643	4	574	598		1.0
CBEAM	1644	4	599	590		1.0
CBEAM	1645	4	600	566	1.0	
CBEAM	1646	4	601	582	-1.0	

\$ 3" X 3" POSTS

CBEAM	1647	5	554	598		1.0
CBEAM	1648	5	562	599		1.0

\$ BEAMS TO SUPPORT GIMBAL#1 LASER

CBEAM	1651	11	602	571	579	
CBEAM	1652	11	602	579	587	
CBEAM	1653	11	602	587	595	
CBEAM	1654	11	602	595	571	

\$ START WEIGHTLESS BACK-UP BEAMS FOR GIMBAL#1 PLATE

CBEAM	1661	17	553	551	561	
CBEAM	1662	17	553	552	554	
CBEAM	1663	17	553	555	561	
CBEAM	1664	17	557	555	565	
CBEAM	1665	17	557	556	558	
CBEAM	1666	17	557	559	565	
CBEAM	1667	17	561	559	553	
CBEAM	1668	17	561	560	562	
CBEAM	1669	17	561	563	553	
CBEAM	1670	17	565	563	557	
CBEAM	1671	17	565	564	550	
CBEAM	1672	17	565	551	557	

\$ GIMBAL#1 PLATE

CQUAD4	1681	1	551	550	552	553
0.0						
CQUAD4	1682	1	553	552	554	555
0.0						
CQUAD4	1683	1	555	554	556	557
0.0						
CQUAD4	1684	1	557	556	558	559
0.0						
CQUAD4	1685	1	559	558	560	561
0.0						
CQUAD4	1686	1	561	560	562	563
0.0						
CQUAD4	1687	1	563	562	564	565
0.0						
CQUAD4	1688	1	565	564	550	551
0.0						

\$ CONTROLLER BOARD PLATES (IMU UNIT PLATE) FOR GIMBAL#1

CTRIA3	1691	15	57	605	58	
CTRIA3	1692	15	58	605	59	
CTRIA3	1693	15	59	605	60	
CTRIA3	1694	15	60	605	57	

\$ START WEIGHTLESS BACK-UP BEAMS FOR GIMBAL#1 CONTROLLER BOARD PLATE

CBEAM	1695	17	57	605	58	
CBEAM	1696	17	58	605	59	
CBEAM	1697	17	59	605	60	
CBEAM	1698	17	60	605	57	

\$ START GIMBAL #2

\$ GIMBAL#2 SUPPORT BEAMS

CBEAM	1701	502	73	650	-0.707	0.707
CBEAM	1702	502	73	662	0.707	-0.707
CBEAM	1703	502	77	650	-0.707	-0.707
CBEAM	1704	502	77	654	0.707	0.707
CBEAM	1705	502	78	654	-0.707	0.707
CBEAM	1706	502	78	658	0.707	-0.707
CBEAM	1707	502	74	658	0.707	0.707
CBEAM	1708	502	74	662	-0.707	-0.707

\$ 1/2" X 1" RINGS

CBEAM	1709	4	666	668	-0.195	-0.981
CBEAM	1710	4	668	670	-0.556	-0.831
CBEAM	1711	4	670	672	-0.831	-0.556
CBEAM	1712	4	672	674	-0.981	-0.195
CBEAM	1713	4	674	676	-0.981	0.195
CBEAM	1714	4	676	678	-0.831	0.556
CBEAM	1715	4	678	680	-0.556	0.831
CBEAM	1716	4	680	682	-0.195	0.981
CBEAM	1717	4	682	684	0.195	0.981
CBEAM	1718	4	684	686	0.556	0.831

CBEAM	1719	4	686	688	0.831	0.556				
CBEAM	1720	4	688	690	0.981	0.195				
CBEAM	1721	4	690	692	0.981	-0.195				
CBEAM	1722	4	692	694	0.831	-0.556				
CBEAM	1723	4	694	696	0.556	-0.831				
CBEAM	1724	4	696	666	0.195	-0.981				
CBEAM	1725	4	667	669	-0.195	-0.981				
CBEAM	1726	4	669	671	-0.555	-0.832				
CBEAM	1727	4	671	673	-0.832	-0.555				
CBEAM	1728	4	673	675	-0.981	-0.195				
CBEAM	1729	4	675	677	-0.981	0.195				
CBEAM	1730	4	677	679	-0.832	0.555				
CBEAM	1731	4	679	681	-0.555	0.832				
CBEAM	1732	4	681	683	-0.195	0.981				
CBEAM	1733	4	683	685	0.195	0.981				
CBEAM	1734	4	685	687	0.555	0.832				
CBEAM	1735	4	687	689	0.832	0.555				
CBEAM	1736	4	689	691	0.981	0.195				
CBEAM	1737	4	691	693	0.981	-0.195				
CBEAM	1738	4	693	695	0.832	-0.555				
CBEAM	1739	4	695	697	0.555	-0.832				
CBEAM	1740	4	697	667	0.195	-0.981				
CBEAM	1741	4	666	667	1.0					
CBEAM	1742	4	682	683	-1.0					
CBEAM	1743	4	674	698		1.0				
CBEAM	1744	4	699	690		1.0				
CBEAM	1745	4	700	666	1.0					
CBEAM	1746	4	701	682	-1.0					
\$ 3" X 3" POSTS										
CBEAM	1747	5	654	698		1.0				
CBEAM	1748	5	662	699		1.0				
\$ BEAMS TO SUPPORT GIMBAL#2 LASER										
CBEAM	1751	11	702	671	679					
CBEAM	1752	11	702	679	687					
CBEAM	1753	11	702	687	695					
CBEAM	1754	11	702	695	671					
\$ START WEIGHTLESS BACK-UP BEAMS FOR GIMBAL#2 PLATE										
CBEAM	1761	17	653	651	661					
CBEAM	1762	17	653	652	654					
CBEAM	1763	17	653	655	661					
CBEAM	1764	17	657	655	665					
CBEAM	1765	17	657	656	658					
CBEAM	1766	17	657	659	665					
CBEAM	1767	17	661	659	653					
CBEAM	1768	17	661	660	662					
CBEAM	1769	17	661	663	653					
CBEAM	1770	17	665	663	657					
CBEAM	1771	17	665	664	650					
CBEAM	1772	17	665	651	657					
\$ GIMBAL#2 PLATES										
CQUAD4	1781	1	651	650	652	653				
0.0										
CQUAD4	1782	1	653	652	654	655				
0.0										
CQUAD4	1783	1	655	654	656	657				
0.0										
CQUAD4	1784	1	657	656	658	659				
0.0										
CQUAD4	1785	1	659	658	660	661				
0.0										
CQUAD4	1786	1	661	660	662	663				
0.0										
CQUAD4	1787	1	663	662	664	665				
0.0										
CQUAD4	1788	1	665	664	650	651				
0.0										
\$ CONTROLLER BOARD PLATES (IMU UNIT PLATE) FOR GIMBAL#2										
CTRIA3	1791	15	81	705	82					
CTRIA3	1792	15	82	705	83					
CTRIA3	1793	15	83	705	84					
CTRIA3	1794	15	84	705	81					
\$ START WEIGHTLESS BACK-UP BEAMS FOR GIMBAL#2 CONTROLLER BOARD PLATE										
CBEAM	1795	17	81	705	82					
CBEAM	1796	17	82	705	83					
CBEAM	1797	17	83	705	84					
CBEAM	1798	17	84	705	85					
\$ START GIMBAL #3										
\$ GIMBAL#3 SUPPORT BEAMS										
CBEAM	1801	502	217	750	-0.707	0.707				
CBEAM	1802	502	217	762	0.707	-0.707				
CBEAM	1803	502	221	750	-0.707	-0.707				
CBEAM	1804	502	221	754	0.707	0.707				
CBEAM	1805	502	222	754	-0.707	0.707				
CBEAM	1806	502	222	758	0.707	-0.707				
CBEAM	1807	502	218	758	0.707	0.707				
CBEAM	1808	502	218	762	-0.707	-0.707				
\$ 1/2" X 1" RINGS										
CBEAM	1809	4	766	768	-0.195	-0.981				
CBEAM	1810	4	768	770	-0.556	-0.831				
CBEAM	1811	4	770	772	-0.831	-0.556				
CBEAM	1812	4	772	774	-0.981	-0.195				
CBEAM	1813	4	774	776	-0.981	0.195				
CBEAM	1814	4	776	778	-0.831	0.556				
CBEAM	1815	4	778	780	-0.556	0.831				
CBEAM	1816	4	780	782	-0.195	0.981				
CBEAM	1817	4	782	784	0.195	0.981				
CBEAM	1818	4	784	786	0.556	0.831				
CBEAM	1819	4	786	788	0.831	0.556				
CBEAM	1820	4	788	790	0.981	0.195				
CBEAM	1821	4	790	792	0.981	-0.195				
CBEAM	1822	4	792	794	0.831	-0.556				
CBEAM	1823	4	794	796	0.556	-0.831				
CBEAM	1824	4	796	766	0.195	-0.981				
CBEAM	1825	4	767	769	-0.195	-0.981				
CBEAM	1826	4	769	771	-0.555	-0.832				
CBEAM	1827	4	771	773	-0.832	-0.555				
CBEAM	1828	4	773	775	-0.981	-0.195				
CBEAM	1829	4	775	777	-0.981	0.195				
CBEAM	1830	4	777	779	-0.832	0.555				
CBEAM	1831	4	779	781	-0.555	0.832				
CBEAM	1832	4	781	783	-0.195	0.981				
CBEAM	1833	4	783	785	0.195	0.981				
CBEAM	1834	4	785	787	0.555	0.832				
CBEAM	1835	4	787	789	0.832	0.555				
CBEAM	1836	4	789	791	0.981	0.195				
CBEAM	1837	4	791	793	0.981	-0.195				
CBEAM	1838	4	793	795	0.832	-0.555				
CBEAM	1839	4	795	797	0.555	-0.832				
CBEAM	1840	4	797	767	0.195	-0.981				
CBEAM	1841	4	766	767	1.0					
CBEAM	1842	4	782	783	-1.0					
CBEAM	1843	4	774	798		1.0				
CBEAM	1844	4	799	790		1.0				
CBEAM	1845	4	800	766	1.0					

CBEAM	1846	4	801	782	-1.0		
\$ 3" X 3" POSTS							
CBEAM	1847	5	754	798		1.0	
CBEAM	1848	5	762	799		1.0	
\$ BEAMS TO SUPPORT GIMBAL#3 LASER							
CBEAM	1851	11	802	771	779		
CBEAM	1852	11	802	779	787		
CBEAM	1853	11	802	787	795		
CBEAM	1854	11	802	795	771		
\$ START WEIGHTLESS BACK-UP BEAMS FOR GIMBAL#3 PLATE							
CBEAM	1861	17	753	751	761		
CBEAM	1862	17	753	752	754		
CBEAM	1863	17	753	755	761		
CBEAM	1864	17	757	755	765		
CBEAM	1865	17	757	756	758		
CBEAM	1866	17	757	759	765		
CBEAM	1867	17	761	759	753		
CBEAM	1868	17	761	760	762		
CBEAM	1869	17	761	763	753		
CBEAM	1870	17	765	763	757		
CBEAM	1871	17	765	764	750		
CBEAM	1872	17	765	751	757		
\$ GIMBAL#3 PLATE							
CQUAD4	1881	1	751	750	752	753	
0.0							
CQUAD4	1882	1	753	752	754	755	
0.0							
CQUAD4	1883	1	755	754	756	757	
0.0							
CQUAD4	1884	1	757	756	758	759	
0.0							
CQUAD4	1885	1	759	758	760	761	
0.0							
CQUAD4	1886	1	761	760	762	763	
0.0							
CQUAD4	1887	1	763	762	764	765	
0.0							
CQUAD4	1888	1	765	764	750	751	
0.0							
\$ CONTROLLER BOARD PLATES (IMU UNIT PLATE) FOR GIMBAL#3							
CTRIA3	1891	15	225	805	226		
CTRIA3	1892	15	226	805	227		
CTRIA3	1893	15	227	805	228		
CTRIA3	1894	15	228	805	225		
\$ START WEIGHTLESS BACK-UP BEAMS FOR GIMBAL#3 CONTROLLER BOARD PLATE							
CBEAM	1895	17	225	805	226		
CBEAM	1896	17	226	805	227		
CBEAM	1897	17	227	805	228		
CBEAM	1898	17	228	805	229		
\$ 14.75# STEEL PLATE							
CQUAD4	1900	40	1	2	3	4	
\$ THRUSTER PLATES FOLLOW							
\$ REVISED 90/11/28							
\$ MAIN TRUSS PLATES, FWD							
CTRIA3	1901	15	1	5,489			
CTRIA3	1902	15	5	6,489			
CTRIA3	1903	15	6	2,489			
CTRIA3	1904	15	2	1,489			
CTRIA3	1905	15	2	6,490			
CTRIA3	1906	15	6	7,490			
CTRIA3	1907	15	7	3,490			
CTRIA3	1908	15	3	2,490			
CTRIA3	1909	15	4	8,491			
CTRIA3	1910	15	8	7,491			
CTRIA3	1911	15	7	3,491			
CTRIA3	1912	15	3	4,491			
CTRIA3	1913	15	1	5,492			
CTRIA3	1914	15	5	8,492			
CTRIA3	1915	15	8	4,492			
CTRIA3	1916	15	4	1,492			
\$ TOWER TRUSS PLATES							
CTRIA3	1921	15	305	308,493			
CTRIA3	1922	15	308	304,493			
CTRIA3	1923	15	304	301,493			
CTRIA3	1924	15	301	305,493			
CTRIA3	1925	15	308	307,494			
CTRIA3	1926	15	307	303,494			
CTRIA3	1927	15	303	304,494			
CTRIA3	1928	15	304	308,494			
CTRIA3	1929	15	307	306,495			
CTRIA3	1930	15	306	302,495			
CTRIA3	1931	15	302	303,495			
CTRIA3	1932	15	303	307,495			
CTRIA3	1933	15	306	305,496			
CTRIA3	1934	15	305	301,496			
CTRIA3	1935	15	301	302,496			
CTRIA3	1936	15	302	306,496			
\$ MAIN TRUSS PLATES, MIDDLE							
CTRIA3	1941	15	129	133,498			
CTRIA3	1942	15	133	134,498			
CTRIA3	1943	15	134	130,498			
CTRIA3	1944	15	130	129,498			
CTRIA3	1945	15	130	131,499			
CTRIA3	1946	15	131	135,499			
CTRIA3	1947	15	135	134,499			
CTRIA3	1948	15	134	130,499			
CTRIA3	1949	15	132	131,500			
CTRIA3	1950	15	131	135,500			
CTRIA3	1951	15	135	136,500			
CTRIA3	1952	15	136	132,500			
CTRIA3	1953	15	129	132,501			
CTRIA3	1954	15	132	136,501			
CTRIA3	1955	15	136	133,501			
CTRIA3	1956	15	133	129,501			
\$ RFL TRUSS PLATES							
CTRIA3	1961	15	265	268,502			
CTRIA3	1962	15	268	264,502			
CTRIA3	1963	15	264	261,502			
CTRIA3	1964	15	261	265,502			
CTRIA3	1965	15	268	267,503			
CTRIA3	1966	15	267	263,503			
CTRIA3	1967	15	263	264,503			
CTRIA3	1968	15	264	268,503			
CTRIA3	1969	15	266	267,504			
CTRIA3	1970	15	267	263,504			
CTRIA3	1971	15	263	262,504			
CTRIA3	1972	15	262	266,504			
CTRIA3	1973	15	266	265,505			
CTRIA3	1974	15	265	261,505			
CTRIA3	1975	15	261	262,505			
CTRIA3	1976	15	262	266,505			
\$ LASER PLATE							
CTRIA3	1981	15	310	311,497			
CTRIA3	1982	15	311	312,497			
CTRIA3	1983	15	312	309,497			

CTRIA3, 1984, 15,309,310,497
\$ THRUSTER CONTROLLER BOARD PLATES
90/09/25

CQUAD4, 1991, 15,101,102,103,104

CQUAD4, 1992, 15,165,166,167,168

\$ START WEIGHLESS BACKUP BEAMS TO
THRUSTER PLATES

\$ FORWARD THRUSTER

CBEAM,2000,17, 1,489,491

CBEAM,2001,17,489, 6,491

CBEAM,2002,17, 2,490,492

CBEAM,2003,17,490, 7,492

CBEAM,2004,17, 3,491,489

CBEAM,2005,17,491, 8,489

CBEAM,2006,17, 4,492,490

CBEAM,2007,17,492, 5,490

\$ TOWER THRUSTER

CBEAM,2010,17,304,493,495

CBEAM,2011,17,493,307,495

CBEAM,2012,17,303,494,496

CBEAM,2013,17,494,306,496

CBEAM,2014,17,301,495,493

CBEAM,2015,17,495,306,493

CBEAM,2016,17,304,496,494

CBEAM,2017,17,496,304,494

CBEAM,2018,17,312,497,309

CBEAM,2019,17,497,310,309

\$ MIDDLE THRUSTER

CBEAM,2020,17,129,498,500

CBEAM,2021,17,498,134,500

CBEAM,2022,17,130,499,501

CBEAM,2023,17,499,135,501

CBEAM,2024,17,131,500,498

CBEAM,2025,17,500,136,498

CBEAM,2026,17,132,501,499

CBEAM,2027,17,501,133,499

\$ REFLECTOR TOWER THRUSTER

CBEAM,2030,17,265,502,504

CBEAM,2031,17,502,264,504

CBEAM,2032,17,268,503,505

CBEAM,2033,17,503,263,505

CBEAM,2034,17,267,504,502

CBEAM,2035,17,504,262,502

CBEAM,2036,17,266,505,503

CBEAM,2037,17,505,261,503

\$ WTLESS BACKUP BEAMS FOR REFLECTOR

SPACER PLATE

CBEAM,2040,17,859,851,852

CBEAM,2041,17,859,853,854

CBEAM,2042,17,859,855,856

CBEAM,2043,17,859,857,858

\$ REFLECTOR SPACER PLATE CONNECTORS TO
BRACKET TRUSS

CBEAM,2045,12,485,854,858

CBEAM,2046,12,486,856,852

CBEAM,2047,12,487,858,854

CBEAM,2048,12,488,852,856

\$ REFLECTOR SPACER PLATE

CTRIA3 2051 25 851 852 859 0.

CTRIA3 2052 25 852 853 859 0.

CTRIA3 2053 25 853 854 859 0.

CTRIA3 2054 25 854 855 859 0.

CTRIA3 2055 25 855 856 859 0.

CTRIA3 2056 25 856 857 859 0.

CTRIA3 2057 25 857 858 859 0.

CTRIA3 2058 25 858 851 859 0.

\$ SPRINGS AT TOP OF SUSPENSION CABLE

\$ CHANGED 92/01/02

CELAS2, 2201, 0.5, 508, 3, 509, 3

CELAS2, 2202, 0.5, 518, 3, 519, 3

CELAS2, 2203, 0.5, 528, 3, 529, 3

CELAS2, 2204, 0.5, 538, 3, 539, 3

\$ air tubing stiffness at thruster locations

CELAS2, 2241, .175, 1, 1

CELAS2, 2242, .127, 1, 2

CELAS2, 2243, .200, 1, 3

CELAS2, 2244, .175, 129, 1

CELAS2, 2245, .2606, 129, 2

CELAS2, 2246, .200, 129, 3

CELAS2, 2247, .175, 265, 1

CELAS2, 2248, .2606, 265, 2

CELAS2, 2249, .200, 265, 3

CELAS2, 2250, .175, 309, 1

CELAS2, 2251, .127, 309, 2

CELAS2, 2252, .200, 309, 3

\$ START JOINT LUMPED MASSES

\$ joint mass = ball mass (4.12E-04 lb-s**2/in)

CONM2, 3001, 1, 0, 4.12E-04

CONM2, 3002, 2, 0, 4.12E-04

CONM2, 3003, 3, 0, 4.12E-04

CONM2, 3004, 4, 0, 4.12E-04

CONM2, 3005, 5, 0, 4.12E-04

CONM2, 3006, 6, 0, 4.12E-04

CONM2, 3007, 7, 0, 4.12E-04

CONM2, 3008, 8, 0, 4.12E-04

CONM2, 3009, 9, 0, 4.12E-04

CONM2, 3010, 10, 0, 4.12E-04

CONM2, 3011, 11, 0, 4.12E-04

CONM2, 3012, 12, 0, 4.12E-04

CONM2, 3013, 13, 0, 4.12E-04

CONM2, 3014, 14, 0, 4.12E-04

CONM2, 3015, 15, 0, 4.12E-04

CONM2, 3016, 16, 0, 4.12E-04

CONM2, 3017, 17, 0, 4.12E-04

CONM2, 3018, 18, 0, 4.12E-04

CONM2, 3019, 19, 0, 4.12E-04

CONM2, 3020, 20, 0, 4.12E-04

CONM2, 3021, 21, 0, 4.12E-04

CONM2, 3022, 22, 0, 4.12E-04

CONM2, 3023, 23, 0, 4.12E-04

CONM2, 3024, 24, 0, 4.12E-04

CONM2, 3025, 25, 0, 4.12E-04

CONM2, 3026, 26, 0, 4.12E-04

CONM2, 3027, 27, 0, 4.12E-04

CONM2, 3028, 28, 0, 4.12E-04

CONM2, 3029, 29, 0, 4.12E-04

CONM2, 3030, 30, 0, 4.12E-04

CONM2, 3031, 31, 0, 4.12E-04

CONM2, 3032, 32, 0, 4.12E-04

CONM2, 3033, 33, 0, 4.12E-04

CONM2, 3034, 34, 0, 4.12E-04

CONM2, 3035, 35, 0, 4.12E-04

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CONM2, 3451, 455, 0,4.12E-04
CONM2, 3452, 456, 0,4.12E-04
$ end joint mass
$ start suspension cable mass
CONM2, 3453, 514, 0,2.59E-04
CONM2, 3454, 515, 0,2.59E-04
CONM2, 3455, 516, 0,2.59E-04
CONM2, 3456, 524, 0,2.59E-04
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CONM2, 3461, 536, 0,2.59E-04
CONM2, 3462, 544, 0,2.59E-04
CONM2, 3463, 545, 0,2.59E-04
CONM2, 3464, 546, 0,2.59E-04
$ GIMBAL ENCODER, DECODER MASS
CONM2, 3465, 598, 0,03148
CONM2, 3466, 599, 0,02643
CONM2, 3467, 600, 0,02267
CONM2, 3468, 601, 0,01943
CONM2, 3469, 698, 0,03148
CONM2, 3470, 699, 0,02643
CONM2, 3471, 700, 0,02267
CONM2, 3472, 701, 0,01943
CONM2, 3473, 798, 0,03148
CONM2, 3474, 799, 0,02643
CONM2, 3475, 800, 0,02267
CONM2, 3476, 801, 0,01943
$.082902 GIMBAL LASER MASS (32 lbm)
CONM2, 3477, 602, 0,8.290E-2, 0, 0, 0,
,05, ,1, ,0,
CONM2, 3478, 702, 0,8.290E-2, 0, 0, 0,
,05, ,1, ,0,
CONM2, 3479, 802, 0,8.290E-2, 0, 0, 0,
,05, ,1, ,0,
$.000206 HALF A NODE BALL AT ENDS OF
GIMBAL SUPPORT
CONM2, 3481, 550, 0,2.06E-4
CONM2, 3482, 554, 0,2.06E-4
CONM2, 3483, 558, 0,2.06E-4
CONM2, 3484, 562, 0,2.06E-4
CONM2, 3485, 650, 0,2.06E-4
CONM2, 3486, 654, 0,2.06E-4
CONM2, 3487, 658, 0,2.06E-4
CONM2, 3488, 662, 0,2.06E-4
CONM2, 3489, 750, 0,2.06E-4
CONM2, 3490, 754, 0,2.06E-4
CONM2, 3491, 758, 0,2.06E-4
CONM2, 3492, 762, 0,2.06E-4
$ INSTRUMENTATION MASS
$ SERVO BLOCK      - .000979
$ STRUTCELL BLOCK  - .000135
$ STRUTCELL BLOCK + 3 STRUTCELL ACC
CONM2, 3501, 59, 0,0.000201
CONM2, 3502, 60, 0,0.000201
CONM2, 3503, 79, 0,0.000201
CONM2, 3504, 80, 0,0.000201
CONM2, 3505, 91, 0,0.000201
CONM2, 3506, 92, 0,0.000201
CONM2, 3507, 115, 0,0.000201
CONM2, 3508, 116, 0,0.000201
CONM2, 3509, 127, 0,0.000201
CONM2, 3510, 128, 0,0.000201
CONM2, 3511, 147, 0,0.000201
CONM2, 3512, 148, 0,0.000201
CONM2, 3513, 159, 0,0.000201
CONM2, 3514, 160, 0,0.000201
CONM2, 3515, 171, 0,0.000201
CONM2, 3516, 172, 0,0.000201
CONM2, 3517, 195, 0,0.000201
CONM2, 3518, 196, 0,0.000201
CONM2, 3519, 207, 0,0.000201
CONM2, 3520, 208, 0,0.000201
CONM2, 3521, 219, 0,0.000201
CONM2, 3522, 220, 0,0.000201
CONM2, 3523, 239, 0,0.000201
CONM2, 3524, 240, 0,0.000201
CONM2, 3525, 255, 0,0.000201
CONM2, 3526, 256, 0,0.000201
CONM2, 3527, 264, 0,0.000201
CONM2, 3528, 287, 0,0.000201
CONM2, 3529, 288, 0,0.000201
CONM2, 3530, 299, 0,0.000201
CONM2, 3531, 300, 0,0.000201
CONM2, 3532, 312, 0,0.000201
$ SERVO BLOCK + 3 SERVO ACCELEROMETERS
CONM2, 3533, 4, 0,0.002176
CONM2, 3534, 311, 0,0.002176
CONM2, 3535, 352, 0,0.002176
CONM2, 3536, 348, 0,0.002176
CONM2, 3537, 251, 0,0.002176
CONM2, 3538, 263, 0,0.002176
CONM2, 3539, 431, 0,0.002176
CONM2, 3540, 435, 0,0.002176
$ SERVO BLOCK + 2 SERVO ACC + 1 STRUTCELL
ACC
CONM2, 3541, 28, 0,0.001799
CONM2, 3542, 52, 0,0.001799
CONM2, 3543, 68, 0,0.001799
CONM2, 3546, 104, 0,0.001799
CONM2, 3547, 136, 0,0.001799
CONM2, 3548, 184, 0,0.001799
CONM2, 3549, 228, 0,0.001799
$ SERVO BLOCK + 1 SERVO ACC + 2 STRUTCELL
ACC
CONM2, 3550, 3, 0,0.001422
CONM2, 3551, 27, 0,0.001422
CONM2, 3552, 51, 0,0.001422
CONM2, 3553, 67, 0,0.001422
CONM2, 3554, 103, 0,0.001422
CONM2, 3555, 135, 0,0.001422
CONM2, 3556, 183, 0,0.001422
CONM2, 3557, 227, 0,0.001422
CONM2, 3558, 252, 0,0.001422
CONM2, 3559, 370, 0,0.001422
CONM2, 3560, 372, 0,0.001422
CONM2, 3561, 454, 0,0.001422
CONM2, 3562, 456, 0,0.001422
$.0021660 THRUSTER AIR HOSE MASS (379.24 gms)
CONM2, 3563, 8, 0,0.0021660
CONM2, 3564, 12, 0,0.0021660
CONM2, 3565, 136, 0,0.0021660

```

CONM2, 3566, 140, 0, .0021660
 CONM2, 3567, 257, 0, .0021660
 CONM2, 3568, 260, 0, .0021660
 CONM2, 3569, 297, 0, .0021660
 CONM2, 4770, 300, 0, .0021660
 \$.0038050 mass for thruster controller
 CONM2, 3570, 167, 0, .0038050
 CONM2, 3571, 168, 0, .0038050
 CONM2, 3572, 165, 0, .0038050
 CONM2, 3573, 166, 0, .0038050
 \$.0038860 mass for thruster controller
 CONM2, 3574, 101, 0, .0038860
 CONM2, 3575, 104, 0, .0038860
 CONM2, 3576, 103, 0, .0038860
 CONM2, 3577, 102, 0, .0038860
 \$.0066800 air supply bracket and tubing mass
 CONM2, 3578, 8, 0, .0066800
 CONM2, 3579, 12, 0, .0066800
 CONM2, 3580, 136, 0, .0066800
 CONM2, 3581, 140, 0, .0066800
 CONM2, 3582, 257, 0, .0066800
 CONM2, 3583, 257, 0, .0066800
 CONM2, 3584, 260, 0, .0066800
 CONM2, 3585, 260, 0, .0066800
 CONM2, 3586, 297, 0, .0066800
 CONM2, 3587, 297, 0, .0066800
 CONM2, 3588, 300, 0, .0066800
 CONM2, 3589, 300, 0, .0066800
 \$.0096030 THRUSTER MASS (1681.3 gms)
 CONM2, 3590, 489, 0, .0096030
 CONM2, 3591, 496, 0, .0096030
 CONM2, 3592, 499, 0, .0096030
 CONM2, 3593, 491, 0, .0096030
 CONM2, 3594, 495, 0, .0096030
 CONM2, 3595, 492, 0, .0096030
 CONM2, 3596, 493, 0, .0096030
 CONM2, 3597, 494, 0, .0096030
 CONM2, 3598, 490, 0, .0096030
 CONM2, 3599, 498, 0, .0096030
 CONM2, 3600, 503, 0, .0096030
 CONM2, 3601, 501, 0, .0096030
 CONM2, 3602, 502, 0, .0096030
 CONM2, 3603, 505, 0, .0096030
 CONM2, 3604, 504, 0, .0096030
 CONM2, 3605, 500, 0, .0096030
 \$.0133650 LASER MASS (2340 gms)
 CONM2, 3606, 497, 0, .0133650
 \$.000858 & .000429 THRUSTER CONTROLLER
 BOARD SIGNAL CABLE MASS
 CONM2, 3610, 97, 0, .000858
 CONM2, 3611, 98, 0, .000858
 CONM2, 3612, 161, 0, .000429
 CONM2, 3613, 162, 0, .000429
 CONM2, 3614, 166, 0, .000429
 CONM2, 3615, 169, 0, .000429
 \$.007772 GIMBAL CONTROLLER BOARD (3# AT
 EACH CORNER)
 CONM2, 3621, 57, 0, .007772
 CONM2, 3622, 58, 0, .007772
 CONM2, 3623, 59, 0, .007772
 CONM2, 3624, 60, 0, .007772
 CONM2, 3625, 81, 0, .007772
 CONM2, 3626, 82, 0, .007772
 CONM2, 3627, 83, 0, .007772
 CONM2, 3628, 84, 0, .007772
 CONM2, 3629, 225, 0, .007772
 CONM2, 3630, 226, 0, .007772
 CONM2, 3631, 227, 0, .007772
 CONM2, 3632, 228, 0, .007772
 \$ IMU AT CONTROLLER BOARD 1735 gms.
 CONM2, 3633, 605, 0, .009912
 CONM2, 3634, 705, 0, .009912
 CONM2, 3635, 805, 0, .009912
 \$ MASS AT SUSPENSION SPRING 6 lbm
 CONM2, 3636, 509, 0, .015544
 CONM2, 3637, 519, 0, .015544
 CONM2, 3638, 529, 0, .015544
 CONM2, 3639, 539, 0, .015544
 \$ GIMBAL PLATE
 MAT1, 1, 1.E+07, .,333, .000380
 \$ GIMBAL RING
 MAT1, 4, 1.E+07, .,333, .000262
 \$ GIMBAL POSTS, WEIGHLESS
 MAT1, 5, 1.E+07, .,333, .000000
 \$ GIMBAL LASER SUPPORT - WEIGHLESS
 MAT1, 11, .30E+08, .11538+8, 0.
 \$ SUSPENSION CABLE STANDOFF
 MAT1, 12, .30E+08, .11538+8, .0007332
 \$ 7X19 1/8" STAINLESS STEEL CABLE
 MAT1, 13, .30E+08, .11538+8, .0007332
 \$ SUSPENSION KEVLAR CABLE
 MAT1, 14, 5.E+06, .,333, .000101, 0.
 \$ THRUSTER PLATES
 MAT1, 15, 1.E+07, .,333, 0.
 \$ REFLECTOR SPACER PLATE SUPPORT BEAMS -
 WEIGHLESS
 MAT1, 17, .10E+08, .,333, 0.
 \$ REFLECTOR SPACER PLATE
 MAT1, 25, .30E+08, .11538+8, .0007332
 \$ 3/4" DIAMETER ROD - REFLECTOR SUPPORT
 MAT1, 27, .10E+08, .37509+7, .0002539
 \$ ALUMINUM ANGLE - REFLECTOR SUPPORT
 MAT1, 28, .10E+08, .37509+7, .0002539
 \$ ALUMINUM ANGLE - REFLECTOR SUPPORT
 MAT1, 29, .10E+08, .37509+7, .0002539
 \$ BOLTS FOR REFLECTOR FIX
 MAT1, 30, .30E+08, .11538+8, .0007332
 \$ STEEL PLATE
 MAT1, 40, .30E+08, .11538+8, .0007332
 \$ TRUSS MAT1 CARDS, updated densities 92/7/28
 \$ SECTION#1 LONGERONS,BATTENS AND
 DIAGONALS
 MAT1, 101, 1.E+07, .,333333, 3.6358-4, 0.
 MAT1, 102, 1.E+07, .,333333, 5.8464-4, 0.
 MAT1, 103, 1.E+07, .,333333, 5.3917-4, 0.
 \$ SECTION#2 LONGERONS,BATTENS AND
 DIAGONALS
 MAT1, 201, 1.E+07, .,333333, 5.8206-4, 0.
 MAT1, 202, 1.E+07, .,333333, 5.8464-4, 0.
 MAT1, 203, 1.E+07, .,333333, 5.3917-4, 0.
 \$ SECTION#3 LONGERONS,BATTENS AND
 DIAGONALS
 MAT1, 301, 1.E+07, .,333333, 4.0156-4, 0.
 MAT1, 302, 1.E+07, .,333333, 5.8464-4, 0.
 MAT1, 303, 1.E+07, .,333333, 5.3917-4, 0.
 \$ SECTION#4 LONGERONS,BATTENS AND
 DIAGONALS
 MAT1, 401, 1.E+07, .,333333, 3.4581-4, 0.

```

MAT1,402, 1.E+07, .333333,5.8464-4, 0.
MAT1,403, 1.E+07, .333333,5.3917-4, 0.
$ GIMBAL SUPPORT BEAMS
MAT1,502, 1.E+07, .333333,5.8464-4, 0.
$ GIMBAL PLATE
PSHELL, 1, 1, .50, 1
$ GIMBAL 1/2"X1" RING
PBCOMP, 4, 4, .50,.0416667,.0104167, 0.,.0286098, 0.
,0.,0.
$ GIMBAL 3"X3" POST
PBCOMP, 5, 5, 9.0, 6.750, 6.750, 0., 11.407, 0.
,0.,0.
$ GIMBAL LASER SUPPORT
PBCOMP,11,11, 1., .083333, .083333, 0., .166667, 0.
,0.,0.
$ SUSPENSION CABLE STANDOFFS
PBCOMP,12,12, 1., .083333, .083333, 0., .166667, 0.
,0.,0.
$ 7X19 1/8" STAINLESS STEEL CABLE
PROD,13, 13, .012272
$ .170" KELVAR CABLE
PROD,14, 14, .022698
$ THRUSTER & LASER PLATE
PSHELL,15, 15, .3024, 15
$ WEIGHTLESS BEAM BACKING UP REFLECTOR
SPACER PLATE
PBCOMP,17,17, .001, .0001, .0001, 0., .0002, 0.
,0.,0.
$ SPACER PLATE
PSHELL,25,25,1.622,25
$ 3/4" DIAM ROD - REFLECTOR SUPPORT
PBCOMP,27,27, .4418, 1.55E-02, 1.55E-02, 0., 3.1E-02,
0.
,0.,0.
$ 1 X 1 X 5/16" AL ANGLE CROSS MEMBERS
PBCOMP,28,28, 0.339, 3.E-02, 3.E-02, 0., .00439, 0.
,0.,0.
$ 1 X 1 1/4 X 1/4" AL ANGLE THAT SUPPORTS
BASE PLATE
PBCOMP,29,29, .5, 3.97E-02, 7.10E-02, 0., .1107, 0.
,0.,0.
$ PBAR 30 IS A 3/8" DIAM. STEEL MEMBER FOR
REFLECTOR FIX
PBCOMP,30,30, .06627, .000971, .000971, 0., .001942,
0.0
,0.,0.
$ STEEL PLATE, UPDATED 90/10/02
PSHELL,40,40, .512367,40

$ truss pid cards, updated 92/7/28
$ SECTION#1
PBCOMP,101,101,.333000,.027803,.027803,0.,.055607,
0.
,0.,0.
PBCOMP,102,102,.097400,.002335,.002335,0.,.004670,
0.
,0.,0.
PBCOMP,103,103,.083100,.002449,.002449,0.,.004897,
0.
,0.,0.
$ SECTION#2
PBCOMP,201,201,.099100,.002760,.002760,0.,.005520,
0.
,0.,0.
PBCOMP,202,202,.097400,.002335,.002335,0.,.004670,
0.
,0.,0.
PBCOMP,203,203,.083100,.002449,.002449,0.,.004897,
0.
,0.,0.
$ SECTION#3
PBCOMP,301,301,.175000,.006303,.006303,0.,.012605,
0.
,0.,0.
PBCOMP,302,302,.097400,.002335,.002335,0.,.004670,
0.
,0.,0.
PBCOMP,303,303,.083100,.002449,.002449,0.,.004897,
0.
,0.,0.
$ SECTION#4
PBCOMP,401,401,.264000,.015763,.015763,0.,.031525,
0.
,0.,0.
PBCOMP,402,402,.097400,.002335,.002335,0.,.004670,
0.
,0.,0.
PBCOMP,403,403,.083100,.002449,.002449,0.,.004897,
0.
,0.,0.
$ GIMBAL SUPPORT BEAMS
PBCOMP,502,502,.097400,.002335,.002335,0.,.004670,
0.
,0.,0.
$
ENDDATA

```

The following NASTRAN runstream uses the mass and stiffness matrices stored in the data base DBALL to calculate eigenvalues and eigenvectors. Note the constraints are changed to reflect the true boundary conditions. This runstream runs under MSC version 66, rigid format 63.

```

NASTRAN REAL=0, HICORE=1000000
RESTART VERSION=1 KEEP
ID PHASE-TWO SUSPENDED FROM KELVAR CABLES
APP DISPLACEMENT
SOL 63
TIME 200
DIAG 16
COMPILE SOL63 SOUIN=MSCSOU NOLIST NOREF $

```

```

$ALTER TO PUT DYNAMIC OUTPUT ON OUTPUT2 TAPE FOR IDEAS
RFALTER RF63D66
$ALTER FOR RECOVERING kG FROM SOL66
RFALTER RF63D89
ENDALTER
CEND
LINE=36
METHOD=33
SEALL=ALL
SPC=101
MPC=1
DISPLACEMENT=ALL
OUTPUT(PLOT)
CSCALE=1.8
SET 1 = ALL
SET 2 = 550 THRU 602, 650 THRU 702, 750 THRU 802
SET 30 = 1 THRU 500, 812 THRU 899, 955 THRU 986,
        1007 THRU 1146, 1267 THRU 1421, 1531 THRU 1589,
        1601 THRU 1893, 2051 THRU 2058
PLOTTER NAST
AXES X,Y,Z
VIEW = 180.,0.,0.
PTITLE = FRONT VIEW
FIND SCALE, ORIGIN 1, SET 30
PLOT MODAL DEFORMATION,SET 30,ORIGIN 1,SHAPE
AXES Y,X,Z
VIEW = 180.,0.,0.
PTITLE = SIDE VIEW
FIND ORIGIN 1
PLOT MODAL DEFORMATION,SET 30,ORIGIN 1,SHAPE
AXES Z,X,Y
VIEW = 0.,0.,180.
PTITLE = TOP VIEW
FIND ORIGIN 1
PLOT MODAL DEFORMATION,SET 30,ORIGIN 1,SHAPE
$
BEGIN BULK
$2345678$2345678$2345678$2345678$2345678$
SPC1 101 123456 508 518 528 538
SPC1 101 12456 509 519 529 539
PARAM,LGDISP,1
PARAM,LOOPID,4
PARAM,POST,-2
PARAM,OUNIT2,13
PARAM,OQG,NO
PARAM,OUG,YES
PARAM,OEF,NO
PARAM,OES,NO
PARAM,OEE,NO
PARAM,OGPS,NO
PARAM,OCMP,NO
PARAM,OESE,NO
PARAM,OMU,NO
PARAM,OGPF,NO
EIGRL, 33, 0., 30.
ENDDATA

```

Appendix B

The following is a MATLAB routine to evaluate effective independence based on maximum modal amplitude .

```
function [limit,trac,deter,cond,fdof,efi,order,fphi]=itindep(x,cdof)
%
%ITINDEP [limit,trac,deter,cond,fdof,efi,order,fphi]=itindep(x,cdof)
%
% Iteratively computes effective independence and rank
% degrees of freedom
%
% x = Input mode shape partitions in numerical order
% cdof = Input containing dof ID numbers in numerical order
% ie. 8000-1 = 8000.1 etc
%
% limit = EFI value for highest ranked dof to be truncated
% during each iteration
% trac = Trace of Ao = PHI'*PHI
% deter = Determinant of Ao
% cond = Condition number of Ao
% fdof = Final list of sensor dof ID numbers
% efi = Final effective independence ranking
% order = Final EFI sorted by descending magnitude
% fphi = Final partioned mode set
%
% Input Number of Sensors
%
sen = input(' Enter Number of Sensors: ');
%
% Set Number of dof to be Truncated Per Iteration
ntk = 1;
%
% Set Number of Iterations
%
nit = fix(max(size(cdof))-sen/ntk);
%
disp(' ');
disp(' EFFECTIVE INDEPENDENCE');
disp(' ');
disp([' Number of Sensors : ',num2str(sen)]);
disp([' Number of DOF Truncated/Iteration : ',num2str(ntk)]);
disp([' Number of Iterations : ',num2str(nit)]);
disp(' ');
junk = input(' RETURN to Continue');
disp(' ');
disp(' Iterating . . . Please Wait');
%
% Calculate Initial Matrix Measures and Ranking
%
% -----
%
t1 = clock;
a = x'*x;
fphi = x;
```



```

fdof = cdof;
trac(1) = trace(a);
deter(1) = det(a);
cond(1) = rcond(a);
[p,l] = eig(a);
e = fphi*p;
e2 = e.^2;
efd = e2*(inv(l));
[m,n] = size(fphi);
add = ones(n,1);
efi = efd*add;
[y,I] = sort(-efi);
order = -y;
%
% Loop Over Iterations
% -----
%
for i = 1:nit,
    j = i+1;
    [m,n] = size(fphi);
    format short e
    limit(i) = order(m-ntk+1);
    one = ones(m-ntk,1);
    i1 = cumsum(one);
    id = I(i1);
    iext = sort(id);
    fphi = fphi(iext,:);
    fdof = fdof(iext);
    a = fphi'*fphi;
%
    trac(j) = trace(a);
    deter(j) = det(a);
    cond(j) = rcond(a);
    [p,l] = eig(a);
    e = fphi*p;
    e2 = e.^2;
    efd = e2*inv(l);
    add = ones(n,1);
    efi = efd*add;
    [y,I] = sort(-efi);
    order = -y;
%
end;
%
t2 = clock;
Etime=etime(t2,t1);
trac=trac';
deter=deter';
cond=cond';
[yy,II] = sort(I);
end;
disp(' ');
disp([' Elapsed Wall Clock Time (Sec): ',num2str(Etime)]);
format short;

```

REPORT DOCUMENTATION PAGE			Form Approved OMB No. 0704-0188	
Public reporting burden for this collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington, VA 22202-4302, and to the Office of Management and Budget, Paperwork Reduction Project (0704-0188), Washington, DC 20503.				
1. AGENCY USE ONLY (Leave blank)		2. REPORT DATE October 1995		3. REPORT TYPE AND DATES COVERED Technical Memorandum
4. TITLE AND SUBTITLE Langley's CSI Evolutionary Model: Phase II			5. FUNDING NUMBERS WU 233-01-01-03	
6. AUTHOR(S) Lucas G. Horta, Mercedes C. Reaves, Kenny B. Elliott, W. Keith Belvin, John E. Teter				
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) NASA Langley Research Center Hampton, VA 23681-0001			8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING / MONITORING AGENCY NAME(S) AND ADDRESS(ES) National Aeronautics and Space Administration Washington, DC 20546-0001			10. SPONSORING / MONITORING AGENCY REPORT NUMBER NASA TM-109059	
11. SUPPLEMENTARY NOTES				
12a. DISTRIBUTION / AVAILABILITY STATEMENT Unclassified - Unlimited Subject Category - 18 Availability: NASA CASI, (301) 621-0390			12b. DISTRIBUTION CODE	
13. ABSTRACT (Maximum 200 words) Phase II testbed is part of a sequence of laboratory models, developed at NASA Langley Research Center, to enhance our understanding on how to model, control, and design structures for space applications. A key problem with structures that must perform in space is the appearance of unwanted vibrations during operations. Instruments, design independently by different scientists, must share the same vehicle causing them to interact with each other. Once in space, these problems are difficult to correct and therefore, prediction via analysis design, and experiments is very important. Phase II laboratory model and its predecessors are designed to fill a gap between theory and practice and to aid in understanding important aspects in modeling, sensor and actuator technology, ground testing techniques, and control design issues. This document provides detailed information on the truss structure and its main components, control computer architecture, and structural models generated along with corresponding experimental results.				
14. SUBJECT TERMS modal testing, vibration, finite elements, test methods			15. NUMBER OF PAGES 104	
			16. PRICE CODE A06	
17. SECURITY CLASSIFICATION OF REPORT Unclassified	18. SECURITY CLASSIFICATION OF THIS PAGE Unclassified	19. SECURITY CLASSIFICATION OF ABSTRACT	20. LIMITATION OF ABSTRACT	